

3DF ZEPHYR 9.0

USER MANUAL



Table of contents

Introduction	4
System Requirements	4
Versions	5
Activation	5
Documentation	6
A Quick Overview	6
Photography Guide	8
The Main Window	11
Starting a new project	12
Setup multi-camera groups	17
Import Constraints	21
Cameras orientation	27
The bounding box	32
3D Model Generation	33
Texture generation	37
Extracting a dense point cloud	41
Raw and refined dense point clouds	43
Extracting a mesh	44
Mesh enhancement and densification	46
Gaussian Splatting	47
Starting a project from a video	48
Project Panel	49
Animator panel	52
Control Points panel	55
Measures panel	68
Editing panel	70
Registration panel	77
Bundle adjustment	79
Layers and multispectral images	80
The "File" menu	81
Open, Save and Load a project	82
The "Workflow" menu	83
The "Advanced" menu	85
Automatic register images to scans	86
Generate and exports normal maps function	87
Generate and Export planar texture maps	88
ArtEngine Seam Removal	89
Orthophoto generation	90
Generating orthophoto via new project wizard	96
Multispectral orthophoto composition	99
Orthophoto Editor	100
The "Import" menu	105
Import a model (point cloud or mesh)	106
Import a mesh with UV map	107
Merge projects	107
Import drawing elements	108
The "Export" menu	109

The "Edit" menu	112
The "Scene" menu	112
Maps within the scene	113
The "Tools" Menu	113
Tools - Workspace	114
Tools - Selection	117
Tools - Point Cloud Filters	119
Tools - Mesh Filters	120
Classification	125
Tools - Control points and Distances	128
Print Markers and markers use	129
Tools - Distances and Measurements	132
Tools - Registration	133
Tools - Sections and Contour Lines	142
Tools - Lines Extraction	144
Drawing Elements & Layers	149
Guided BreakLines	158
Tools - Surfaces Extraction	160
Tools - Scripting Console	162
Tools - Options	163
The "Utilities" menu	165
3DF Masquerade	165
Automatic Masking	171
Manual masking tools	175
GEOBIM (Revit plugin)	177
Batch processing	178
Run benchmark	179
Camera Calibration Manager	180
Preset Manager	181
Images	182
Image quality index	182
Extract MPO files	183
Image conversion	183
Decompose equirectangular panoramas	184
DEM viewer and elevation profile	186
Launch camera calibration	190
Bubble view extraction	190
Multispectral	190
Launch Radiometric Calibration	190
Multispectral Viewer	193
Other	194
System Info	194
DSLR Remote Shooting	194
Handle laser scanner point clouds	195
Custom shaders	196
Troubleshooting	196
FAQs	197
Performance tweaking	199
Running Zephyr via remote desktop	199

Introduction

Welcome to 3DF Zephyr

3DF Zephyr allows you to reconstruct 3D models from photos automatically. The process is entirely automatic, and no coded targets, manual editing or special equipment are needed. 3DF Zephyr is built on top of our proprietary, cutting-edge, reconstruction technology. 3DF Zephyr comes with a user-friendly interface, and the possibility to export in many common 3D formats or even to generate lossless video without the need for external tools. Furthermore, 3DF Zephyr has a lot of advanced functionalities, and you can, for example, edit your models, create true orthophotos, digital elevation models (DTM), manage laser scan data and calculate areas, volumes, angles, contour lines, and much more.

Here in 3Dflow, we worked hard to build up both the core technologies and the user interface. The obtained solution is in all probability the most accurate, completely automatic, best engineered multiview-stereo algorithm available on the market.

If you need further help, if you would like to request features or if you want to discuss the product and the technology behind it, please remember that our forum (<http://forum.3dflow.net>) is always willing to receive new users.

Before starting, you might want to read some hints and tips on how to take the 'correct' photos and an overview of the reconstruction process.

If you prefer you can also jumpstart and directly Start a new Project.

Moreover, please note that there are also free online tutorials available, featuring demo datasets you can download and more in-depth tips and tricks: our tutorials are available at the URL <http://www.3dflow.net/it/technology/documents/3df-zephyr-tutorials/>

At the URL www.3dflow.net/account there's the opportunity to create your own 3Dflow Account: with these credentials you can access both to your private area and our forum. In the private area you can open support tickets, submit a bug report, request a beta key and manage the licenses tied to your specific email. From this area, if necessary, you can also deactivate autonomously your license: all you will need to do is to reset the license remotely and activate it on another computer.

System Requirements

3DF Zephyr is a computationally demanding application. It takes advantage of all available CPU cores, and it makes use of the Nvidia CUDA technology where available. Please note that computation via a dedicated GPU can drastically improve performances (multi GPU configurations are supported as well in Lite and Full versions). We also suggest exiting all running applications when performing a reconstruction with 3DF Zephyr.

Minimum System Requirements:

OS: Windows 11/10

Processor: Dual Core 2.0GHz or equivalent processor

Memory: 16GB System RAM

Hard Disk Space: 20GB free HDD Space

Video Card: Direct X 9.0c compliant NVIDIA or OpenCL video card with at least 1GB of RAM

Recommended System Requirements:

OS: Windows 11/10

Processor: Quad-core Intel or AMD CPU

Memory: 32GB System RAM

Hard Disk: 40GB free HDD Space - SSD drive

Video Card: Direct X 9.0c compliant NVIDIA video card with at least 4GB of RAM and CUDA capabilities ≥ 3.5 or OpenCL ≥ 1.2

Versions

3DF Zephyr is the complete photogrammetry software solution.

Since version 5.0, the old "3DF Zephyr Pro" and "3DF Zephyr Aerial" versions have been merged into one single version, called "3DF Zephyr". Please contact support@3dflow.net for any question you may have!

Our two additional flavors, "3DF Zephyr Lite" and "3DF Zephyr Free" remains the same.

3DF Zephyr is the complete photogrammetry software solution dedicated and designed for topography, urban monitoring, natural hazard, mining, UAV, precision agriculture applications, architecture, archaeology, medicine & dentistry, body scanning, vfx and much more.

3DF Zephyr Lite/3DF Zephyr Lite Steam Edition is a commercial solution aimed at small businesses, artists or in general to those users who just want to obtain a 3D mesh and/or those who don't need all the tools available in the complete edition.

3DF Zephyr Free is a completely free edition, excellent for sharing your project files with customers, friends and colleagues. Although it has serious computation limitations (for example, a maximum of 50 pictures can be used) it is still a great viewer and the perfect way to learn the ropes of photogrammetry.

3DF Zephyr and 3DF Zephyr Lite require online activation. 3DF Zephyr Lite Steam Edition must be run through the Steam application.

3DF Zephyr also comes in an education version, with the same functions and features but without a commercial licensing. 3DF Zephyr Education is dedicated to students, teachers and schools.

For an updated feature comparisons list, you can refer to the following page:
<https://www.3dflow.net/3df-zephyr-feature-comparison/>

Activation

3DF Zephyr, 3DF Zephyr Education and 3DF Zephyr Lite editions require online activation (3DF Zephyr Lite Steam Edition will work through the Steam Application by Valve and does not require a product key).

The product keys are supplied by email at the moment of purchase. If you lost your product key, please get in touch with our technical support so that we can resolve your issue.

You can activate your software license on the first run.

The activation process will bind the product key to the computer. The activation is per-machine, and not per-user.

You can activate your key on as many computer as you need, as the license is floating: upon startup and shutdown, Zephyr will obtain and release a lease so you can safely install and use Zephyr on multiple machines within your organizations. An internet connection is required.

If you have problems regarding online activation or deactivation, please email support@3dflow.net - a manual offline activation process can also be issued in special cases.

Documentation



3Dflow put a lot of effort into making make Zephyr's interface as user-friendly as possible.

However, if you want to get the best results, please spend a few minutes reading the hints and tips you will find in this documentation.

This guide is intended for all the different versions of 3DF Zephyr unless stated otherwise.

In the [next section](#), we will quickly review the reconstruction process. It is not essential to fully understand the "magic" behind Zephyr, but a quick review of the main concepts can be useful.

A Quick Overview

Here in 3Dflow we are, first and foremost, Computer Vision researchers. Computer Vision is, generally speaking, the science that studies how to extract (any kind of useful) information starting from images. This is a very rough definition and many subproblems

can be delineated and many different meanings for the concept of "information" can be given. Extracting three-dimensional models from a number of images (extracting 3D information from a 2D input) is a well-studied problem in Computer Vision. 3DF Zephyr represents a highly refined and well-engineered solution for this problem.

There are three main phases in Zephyr:

- [Starting a new project and defining the camera pose](#) - this is also referred as 'Structure from Motion'
- [Generating 3D model](#)
 - o [Extracting a Dense Point Cloud](#) - this is also referred as 'Multi-View Stereo'
 - o [Extracting a Surface](#)
- [Extracting a Textured Mesh](#)

When [starting a new project](#) the software will extract the camera external parameters (positions and orientations) and their internal parameters (i.e. the focal length and other camera properties). All the magic of this phase is done by [Samantha](#), our leading Structure from Motion Technology. If you want to input the internal camera parameters manually instead of letting Samantha estimate them, [you can](#).

After the cameras have been oriented, you can proceed and generate the 3d model. This step goes through two phases :

- Extract a [dense reconstruction](#). The process requires the input cameras to be correct. If you believe a camera is not correctly oriented, you can remove it from the workspace. Before proceeding you can also [restrict or expand the volume of reconstruction](#). The densification stage is managed by [Stasia](#), our Multi-View Stereo technology, powers the reconstruction process. You can create different dense reconstructions (with varying parameters) and save them into the workspace.

- [Create a triangular mesh](#), starting from a dense reconstruction. Based on what you are going to reconstruct you can choose from either the generation of a smoothed surface (when dealing with human body or terrains for instance) or the generation of a sharp surface that more benefits scenes such as buildings or mechanical parts. The latter kind of surfaces are handled by [Sasha](#), the meshing algorithm developed by 3Dflow.

Every mesh polygon gets textured using the most appropriate pictures according to their visibility and quality. Within the texture generation phase there is a color balance algorithm as well, that allows the user to select and set-up the best color for each pixel automatically by checking the different lighting changes on the photos.

In the [next section](#) we will give some hints and tips on how to take the right photos.

Photography Guide



In this section we will list some tips to obtain good reconstructions. 3DF Zephyr is completely automatic but does require some forethought to produce the best results.

Camera sensors.

Please bear in mind when picking your gear:

- camera performance is not determined by its megapixel resolution;
- high-end cameras do not always lead to better results;

A good camera must allow full light management in order to control each exposure value. That is why DSLR cameras (colloquially also referred as "reflex") are usually recommended even though also mirrorless cameras and bridge cameras can fulfill that need.

The camera sensor is the crucial factor and the following hints may be helpful:

- **Pixel size must be higher than 2 μm** ; therefore it is strongly recommended to use a camera with a sensor bigger than 1/2.3" even though smaller sensors may be used depending on the accuracy you want to reach;
- Pay attention to pixel size rather than pixels count for each picture. For instance, if a 36 megapixel full-frame reflex (35.9 x 24 mm) is being used it is advisable to shoot at a lower resolution than the maximum provided. It is better to get bigger pixels in the images even though fewer;

Lenses.

Every survey has its own features and conditions so choosing the most suitable lens depends on both environmental conditions (light, obstacles on field, user movement capability) and features of the survey subject/scene. The following tips are provided to pick the proper photographic gear:

- Full-frame cameras: use lenses with a focal length between 25 and 50 mm;
- Cameras equipped with an APS-C sensor or with a lower sensor size: use lenses with focal length values between 18 and 35 mm, considering a crop factor value between 1.5 and 1.6;

It is strongly recommended to keep shooting the same focal length for all the pictures you take. Even if Zephyr can handle several kind of cameras and lenses at the same time and in the same project, you can get better and faster results if working with a consistent set-up;

Shooting techniques.

The techniques for capturing images need to be adapted depending on the subject matter and situation. Below are some suggestions for common situations.

Parallel axis capture



Use this technique with planar or regular surfaces in application fields such as architecture and aerial photogrammetry. White triangles indicate the camera positions and their field of view.

Convergent axis capture



Use this technique when it is possible to move around the subject/scene

Interiors capture



Use this technique when capturing interiors.

If a small or medium size object is to be fully reconstructed it is possible to keep the camera in a fixed position (on a tripod for instance) and to put the object on a turntable. Then [3DF Masquerade](#) will enable the background in the pictures to be hidden.

General rules.

- Keep the subject in the center of the frame;
- Avoid direct light sources that may cast shadows and hide surface areas;
- Avoid high ISO values since the noise may adversely affect the Structure from Motion phase in Zephyr;
- Keep high aperture values (f/8 - F/16) when possible, as it helps get a wide depth of field on pictures;
- Avoid blurry photos. Using good quality cameras as well as having good lighting setup can help. Consider also using a tripod if necessary.
- Have lots of overlap between each photo (70-80%). This is probably the most important tip. Shoot as many photos you can. Each part of the scene you're shooting should appear in at least three separate views taken from different locations. This is a minimum requirement, taking more photos will probably improve the final results.
- Limit the angles between photos. When moving around objects, try to keep the angle between each photo very low.
- Shoot scenes with lots of detail and texture. The visual texture in the photos is what ties them together. 3DF Zephyr does not work well with uniform or highly repetitive texture and does not work at all with specular or transparent objects. You can, however, mask out certain areas using 3DF Masquerade (bundled with 3DF Zephyr).
- Don't try to adjust lens distortion as that error is quite essential during the first phase

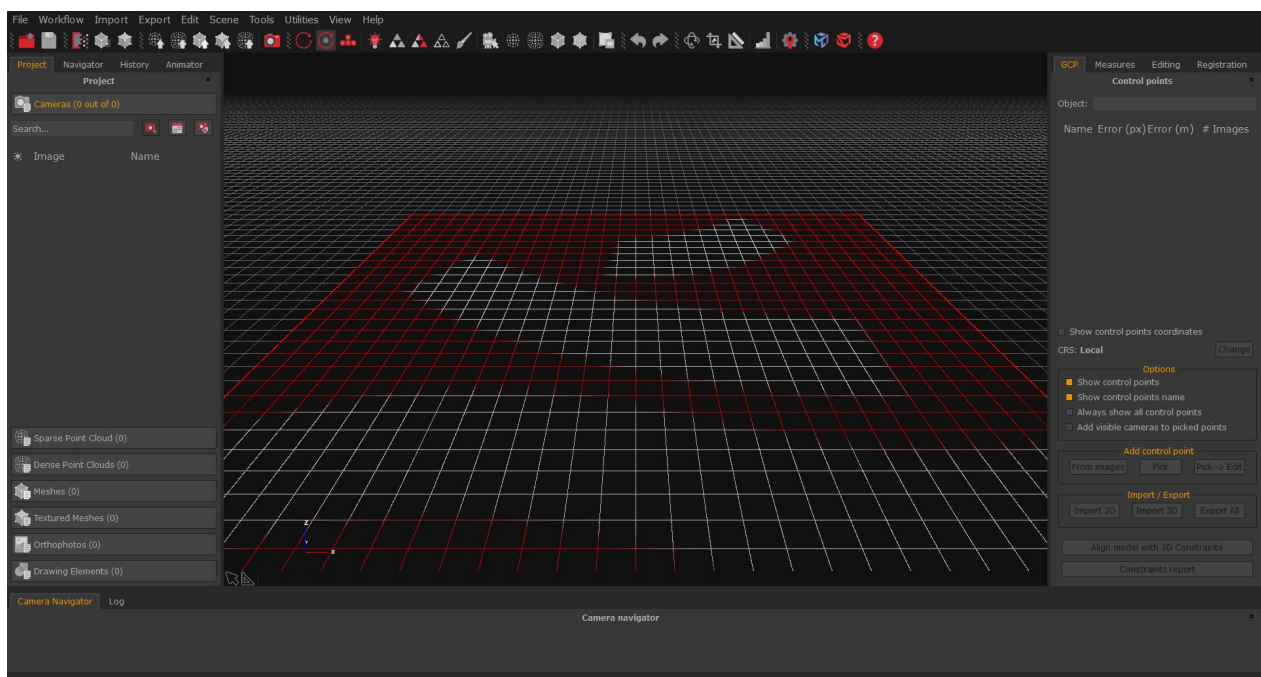
of Structure from Motion;

- Even if 3DF Zephyr can deal with different cameras or lenses within the same dataset, you will obtain better results by using the same camera with the same focal length.
- The more photos you take, the better results you will get: having redundant information will help Zephyr.

Remember that you can use the [Image Quality Index](#) inside Zephyr to check the status of the pictures you are working on.

The Main Window

When opening Zephyr, the interface layout will look like this:



On the upper side, the menu bar and the toolbar give you access to all the basic actions and functionality of Zephyr.

The Render window at the center lets you [navigate through the 3D scene](#). You can also right click on it to open a contextual menu to perform specific actions.

The other windows are completely "dockable"; this means you can move and dock them in any part of the main window. To hide or show a specific dock use the **View** menu.

An optional toolbar can also be shown at the top or bottom of the 3D scene. This toolbar can give quick access to picking and measurement tools (not available in 3DF Zephyr Lite and 3DF Zephyr Free).

3DF Zephyr always saves and loads the interface layout of your last run. From **Tools** >

Options > Application > Restore Settings you can restore the factory default settings (including the interface layout).

On the left side, in the **Project** tab you can review all the objects currently loaded in the workspace. The Objects are divided into 4 categories: cameras, sparse point cloud, dense point clouds and meshes. You can remove, rename and edit every object by right clicking on them and selecting the specific action.

The **Navigator** tab helps you navigate through workspaces.

On the left side you can find the **Animation** tab, where you are able to create and export video animation of your 3D models.

On the right side there are the **Control Points** tab, the **Measures** tab, the Registration tab, and the **Editing** tab as well.

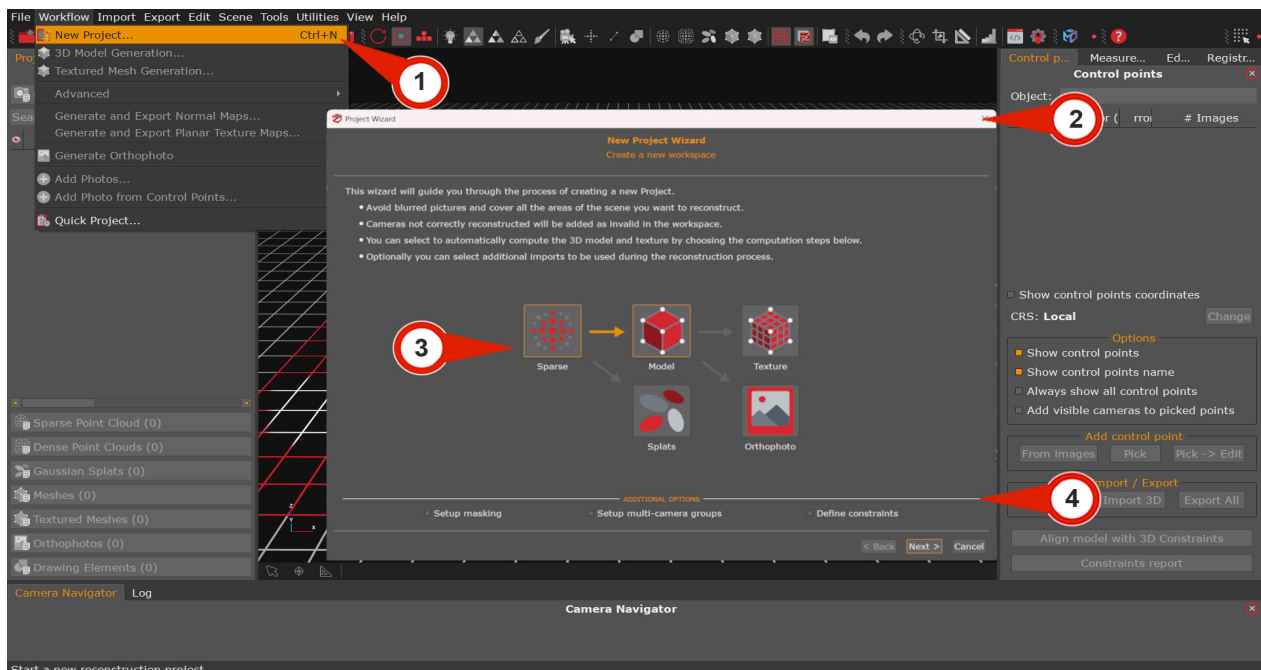
On the same tab, the **History** tab lets you review, undo and redo the performed actions.

The **Navigation** bar is located at the bottom alongside the thumbnails of the photos loaded in Zephyr and the **Log** panel.

Starting a new project

Got the photos? Then you are ready to begin the reconstruction process!

To create a new project, just click on **Workflow > New Project (1)**. The **Project Wizard (2)** will guide you through the picture import and the camera orientation phase setup.



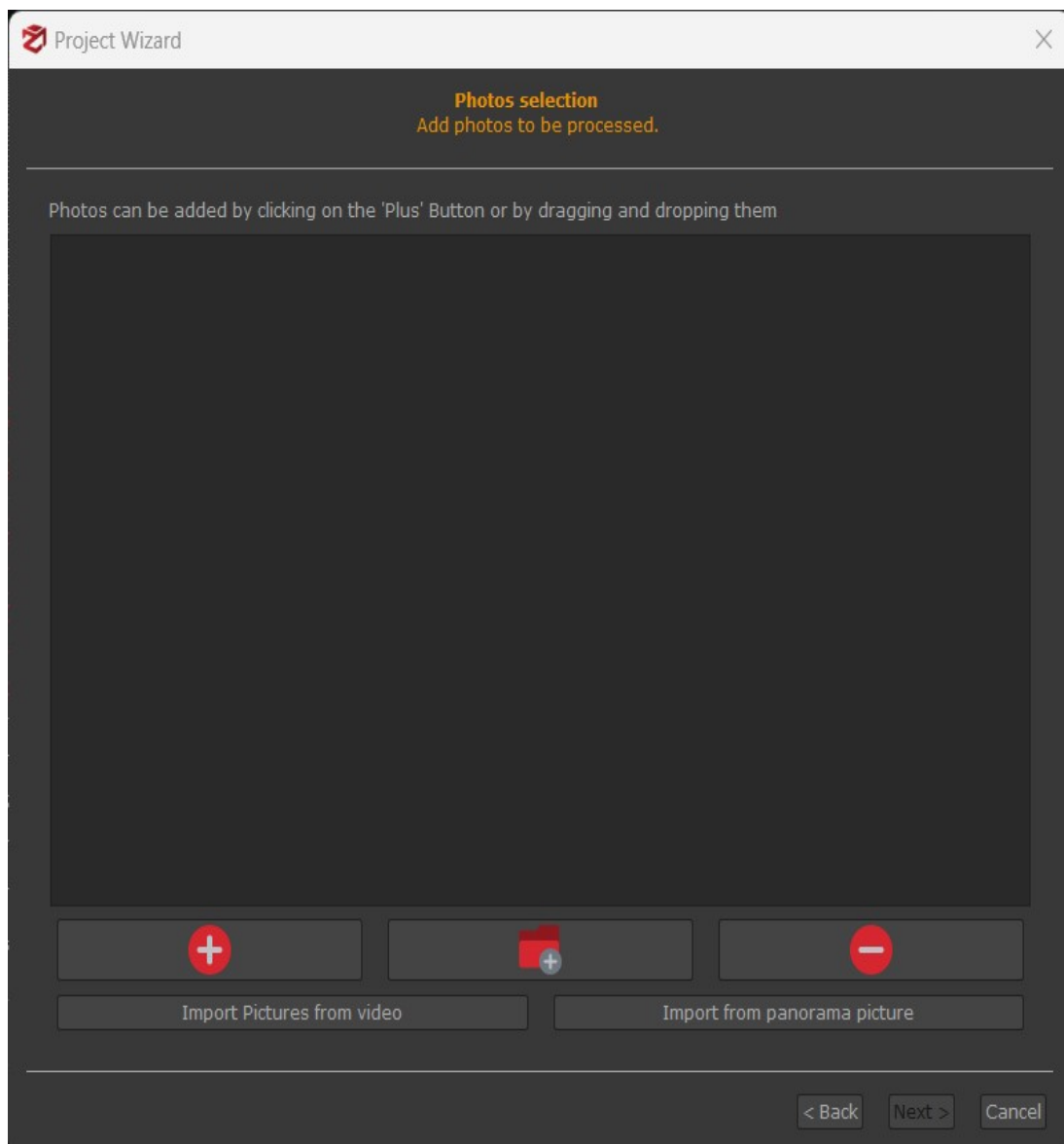
In the **Computation Steps (3)** section, you can select which 3D reconstruction phases to run in addition to the camera orientation phase by clicking the corresponding icons. For

example, enabling the **Model** icon will instruct the software to automatically process the sparse point cloud, dense cloud, and mesh generation in sequence, pausing afterwards to let you review the result before proceeding with textured mesh generation.

If you don't need to import control points, camera coordinates or image masks, simply click the **"Next"** button to go through the wizard.

The **"Additional Options" (4)** section allows for importing and dealing with image masks, control points (2D and 3D coordinates), camera coordinates, and setup camera groups.

The **"Photos selection"** page will follow: it is possible to drag 'n' drop the files - or related folder(s) - into the window or click the **"+" button** to select the desired path. You can also add a specific directory including the pictures. You will likely use JPG or PNG files, but you may also use raw file formats such as NEF, CR2, ARW2, etc. Please, remember that raw files are generally slower to load.

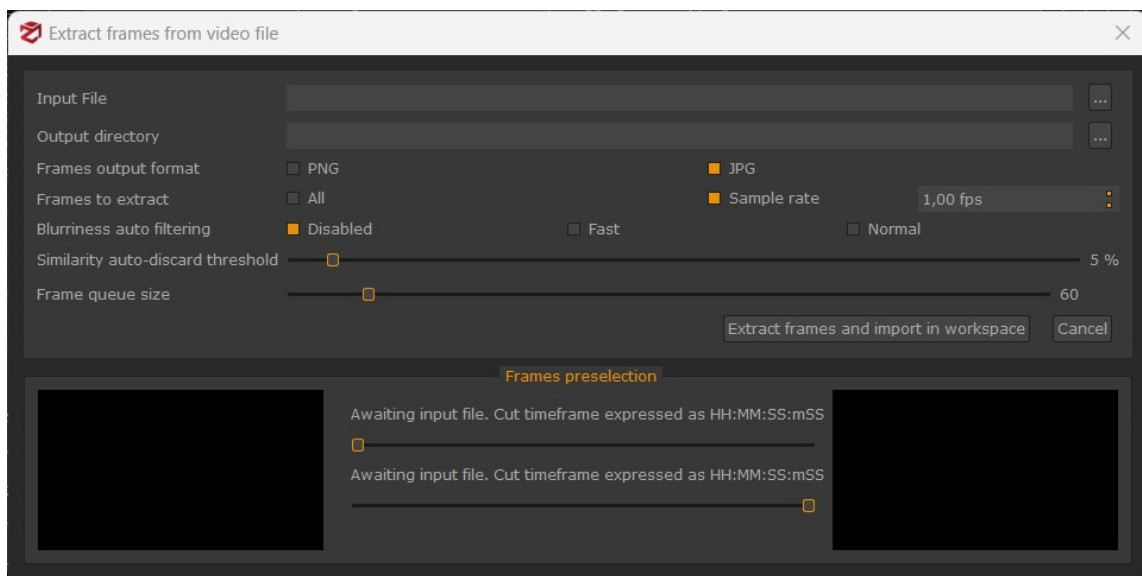


The **"Import pictures from video"** tool will extract a number of frames from the video file you have selected. These frames will go through the same process as the one for standard images.

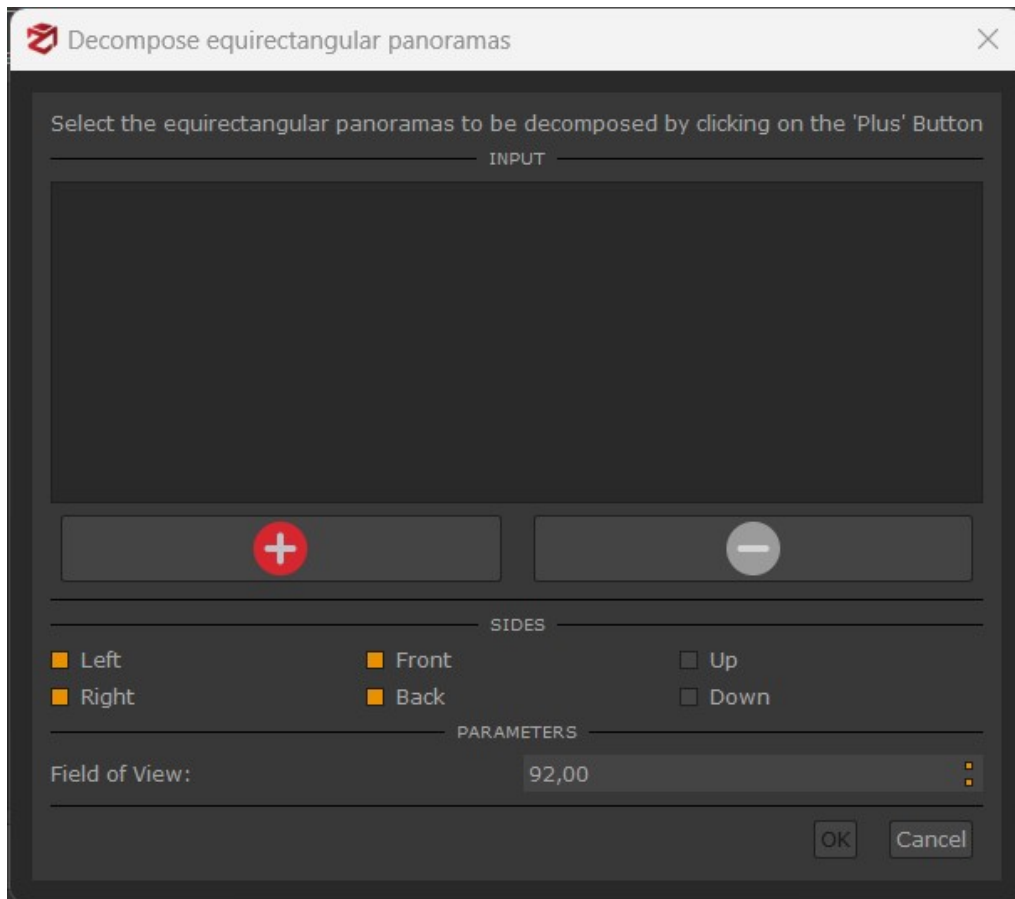
This tool allows for setting:

- the frames output format (.png, .jpg);
- the frame rate (fps) to be extracted;
- the blurriness filter to discard low-quality frames;
- the similarity threshold to discard too akin frames;

Also, it's possible to cut those video parts you don't want to consider during the frame extraction.



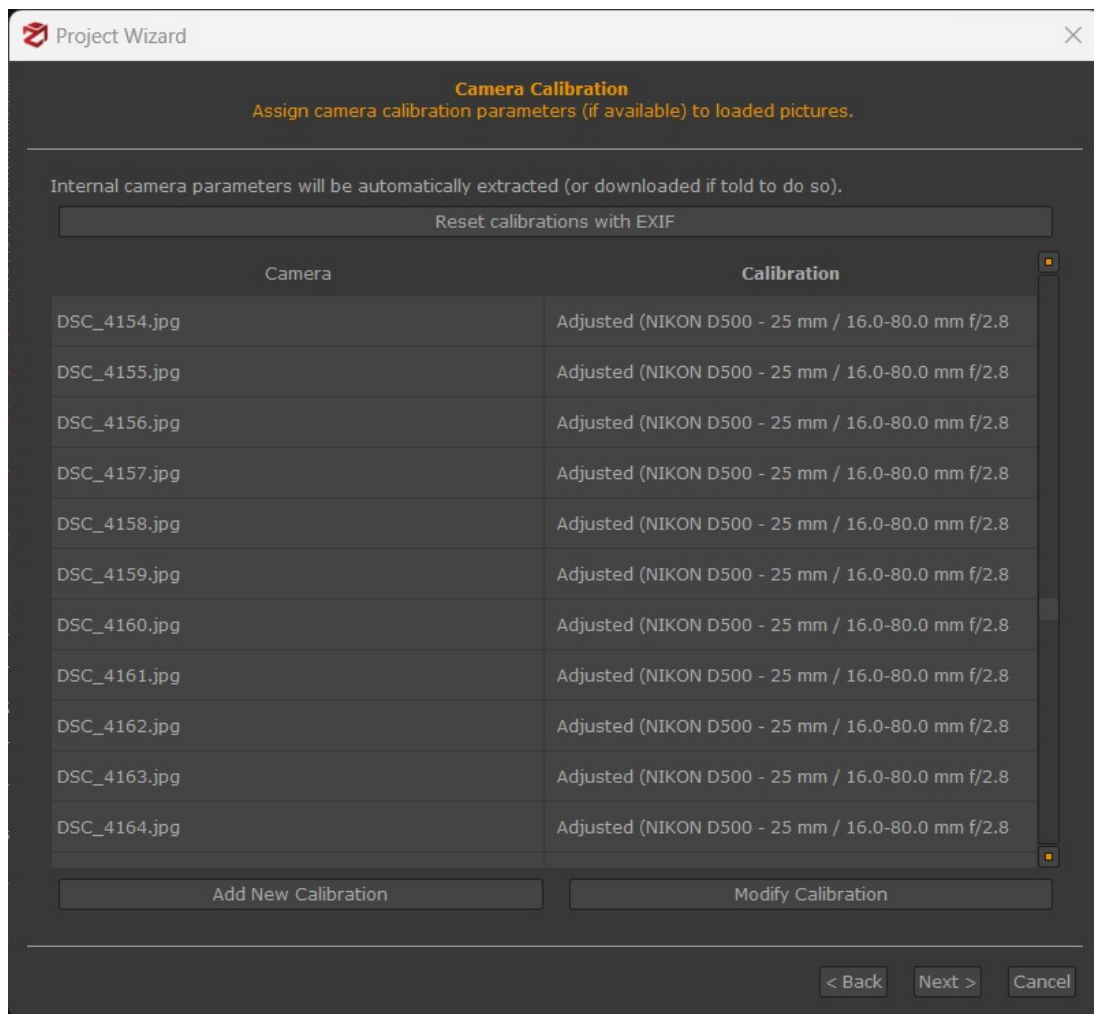
The **"Import from panorama picture"** tool will split each imported 360° picture in six equirectangular images. Once the pictures have been imported, users can pick the sides of the pano pictures to extract by clicking the **"plus"** button. They can also set the field of view of the equirectangular pictures.



Once you have selected the data you want to process, click the **Next** button to get to the **Camera calibration page**. You will notice a list of the pictures you have imported and their calibration recap that 3DF Zephyr - and its Structure from Motion algorithm specifically - will leverage.

You can select/deselect the pictures by clicking on their name or right-clicking the window and picking the desired option from the menu.

From this page, you can [Add a New Calibration](#) or eventually **modify the Calibration** that 3DF Zephyr has automatically selected.



Zephyr is 100% auto-calibrated, so in most cases you don't have to do anything at this point. However, you can click the **"Modify Calibration"** button if you have previously calibrated your camera equipment.

In the **Modify Calibration** page, you can select what camera setup will be edited (if the loaded pictures have been taken with different cameras/lenses), and define the camera's internal parameters.

Modify calibration

Current calibration: Adjusted (NIKON D500 - 25 mm / 16.0-80.0 mm f/2.8-4.0 3712 x 5568 px)

- ☐ Autocalibrated
- ☒ Adjust Focal Length
- ☒ Adjust Principal Point
- ☒ Use Precalibration step
- ☒ Adjust Radial Distortion Parameters
- ☒ Adjust Tangential Distortion Parameters

Focal Length

fx (pixels) 5791.59461682

fy (pixels) 5791.59461682

Radial Distortion

k1 0.009917856

k2 0.163216225

k3 0.00429978

Tangential Distortion

p1 0

p2 0

Optical Center

cx 1870.48131268

cy 2777.90688648

Skew

Skew 0

Import parameters from calibration manager

Import parameters from file

OK Cancel Apply

You can load calibration files (.txt, .xml) created with an external application or the 3DF Zephyr calibration tool (Utilities > Images > Camera calibration), by clicking the **Import parameters from file** button.

By clicking the **"Import parameters from calibration manager"** button, you can import the camera parameters you have previously loaded in the **Camera Calibration Manager** tool (**Utilities** menu).

TIP: If you have imported wide-angle or fish-eye pictures and have issues with the camera orientation phase, enabling the **"Adjust tangential distortion parameters"** option is recommended.

Once the calibration step has been completed you simply need to set up and run the camera calibration phase.

Setup multi-camera groups

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Stereo Cameras group/rig relationship parameters (translation/baseline and rotation) can be specified during the new project creation. Zephyr will organize the images in linked groups with the possibility to change the groups or insert custom parameters.

To start this workflow the "**Setup multi-camera groups**" check-box should be activated on the first page of the **New Project Wizard**.

Note: Zephyr can recognize automatically the camera relationship from Leica Blk3d devices.

On the Photo Selection page, click the "**Add Directory**" button to include multi-camera folders. Then, proceed by clicking the "Next" button. Zephyr can automatically identify the dataset folder structure and it will prompt the following message: "It appears that images are grouped in folders. Would you like to link them?" press
Pressing the following buttons:

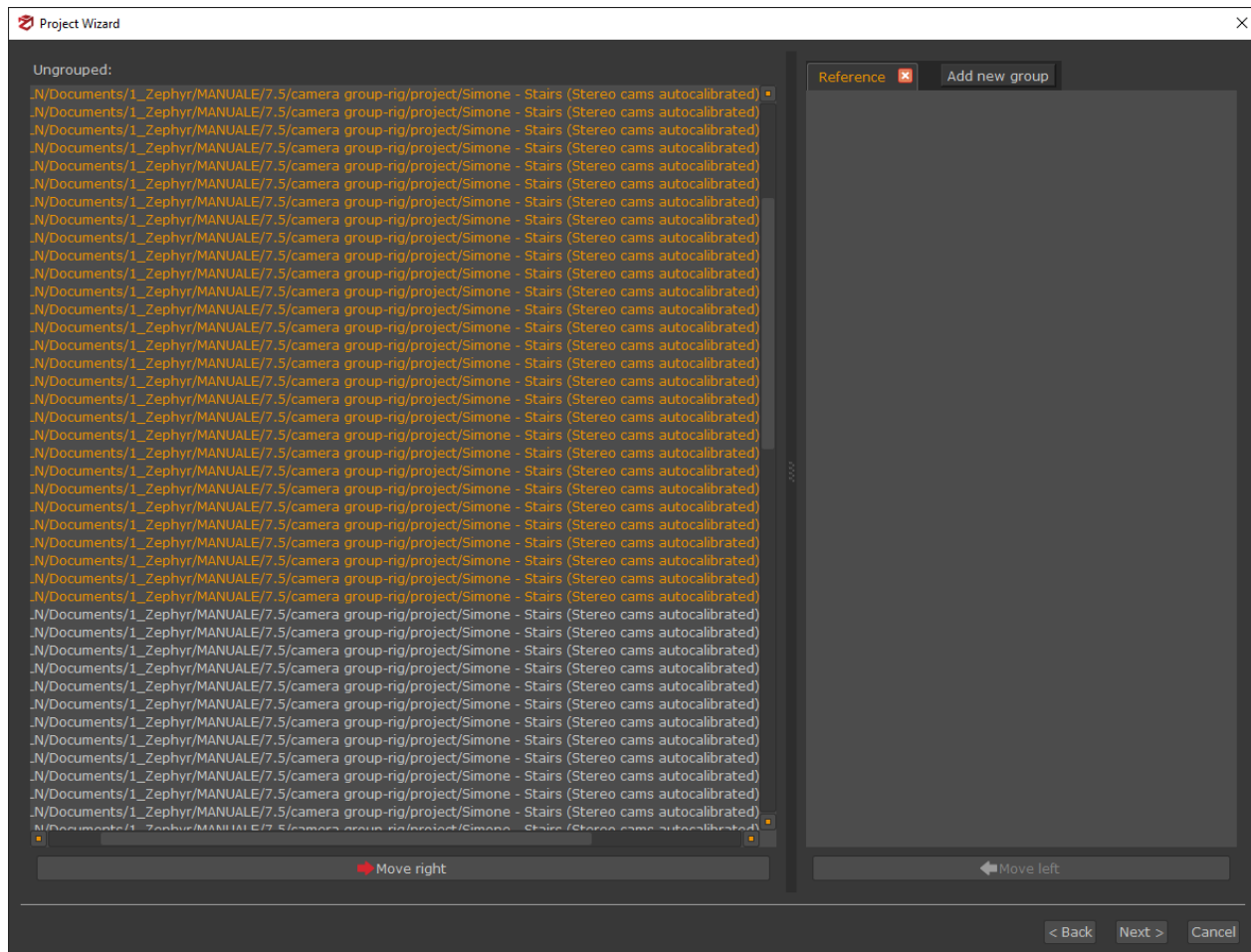
YES: will create automatically groups on the base of the directory structure.

NO: will allow to create the groups manually in the next page.

Setup multi-camera groups manually

In the case that the pictures are all in the same folder or you pressing NO button in the previous prompt windows will be possible to create the reference and camera groups manually.

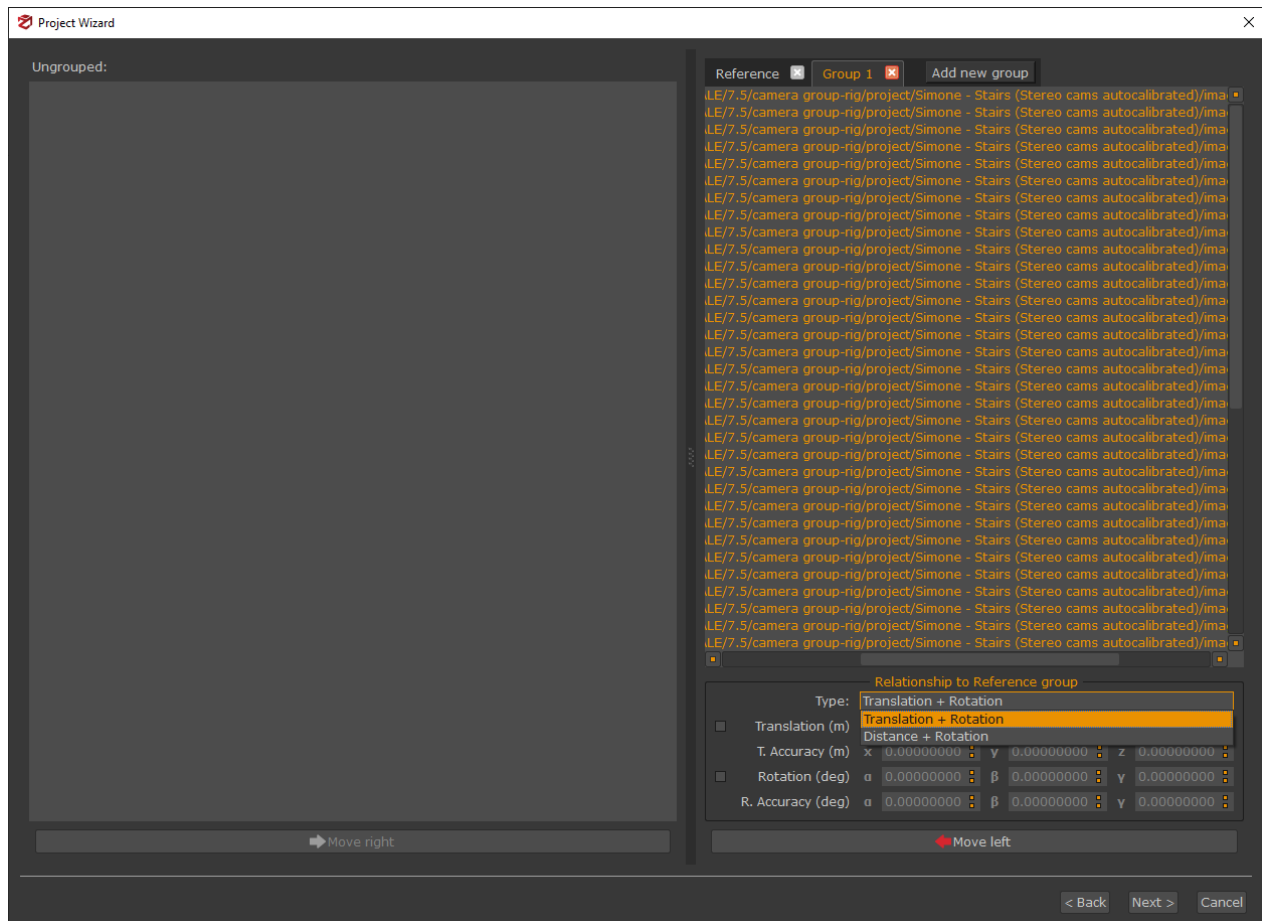
In the **Ungrouped** window, it's possible to select the image's amount taken by the first camera and click the "**Move right**" button" for creating the **Reference group**.



Selecting the **"Add New Group"** tab will generate additional camera groups for adding the remaining images captured by other cameras. It's important that each image folder must contain the same number of images to establish these groups.

Within each group, you'll have the option to configure relationship parameters associated with the Reference group.

Setup multi-camera groups wizard



Reference group and other groups of cameras can be set with two different type of relations:

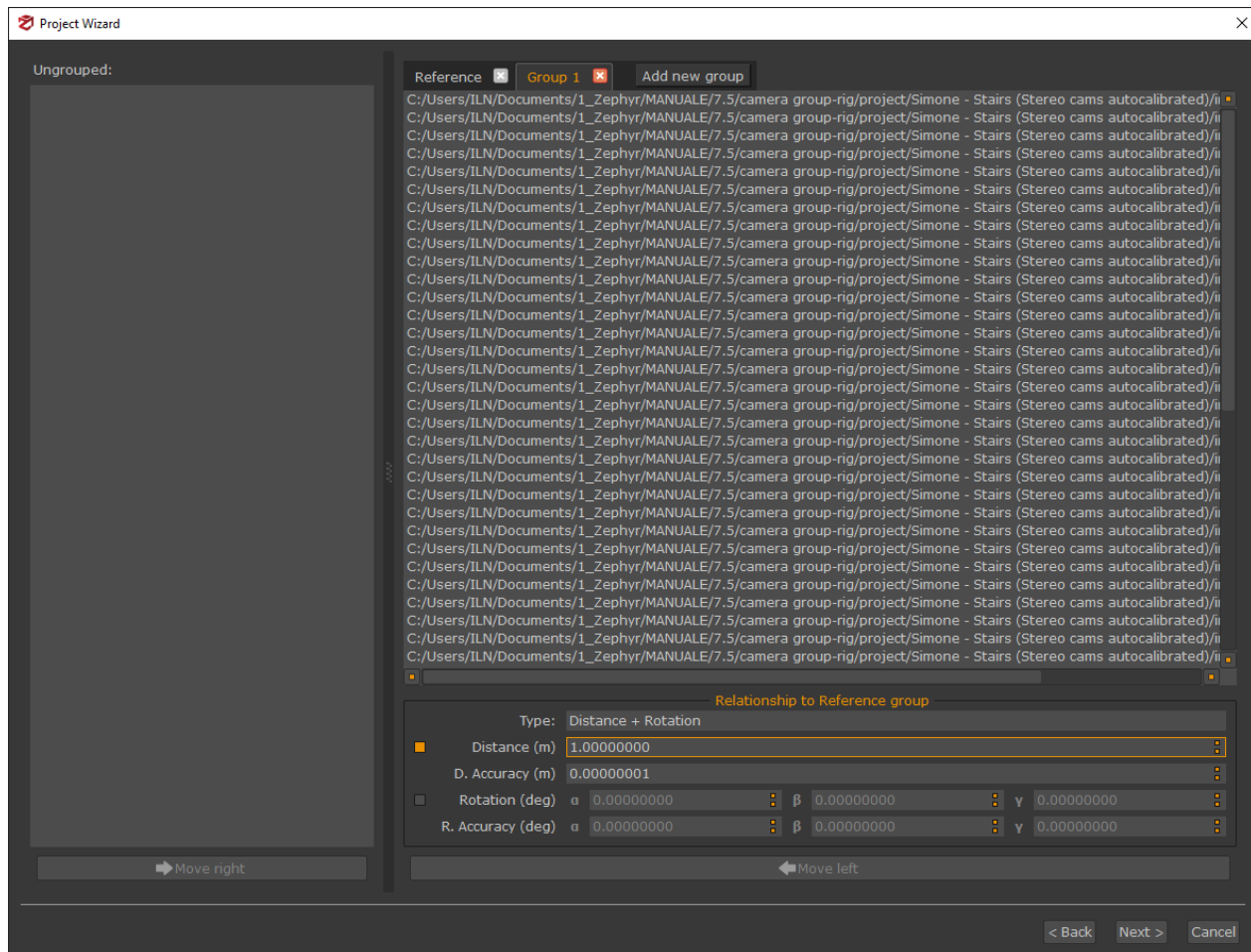
1) Translation + Rotation

2) Distance + Rotation

In both types of options, you can enable the flag and adjust parameters such as XYZ axis, distances, and accuracy. Enabling the **Rotation** flag will allow to modify rotation angles if necessary.

Using distance constraints between camera groups

Configuring the relationship with the reference group using both Distance+Rotation enables you to utilize the distance between camera groups to scale the project.



In the "Distance (m)" field, you can specify the distance between the cameras, for example, 1 meter, and set the desired accuracy. Afterward, click the "Next" button to generate a sparse point cloud.

Using translation constraints between camera groups

In the "Translation (m)" field, you can specify the the x-y-z translation that bring the selected group to the reference camera. The accuracy for each axis can be also specified.

Using rotation constraints between camera groups

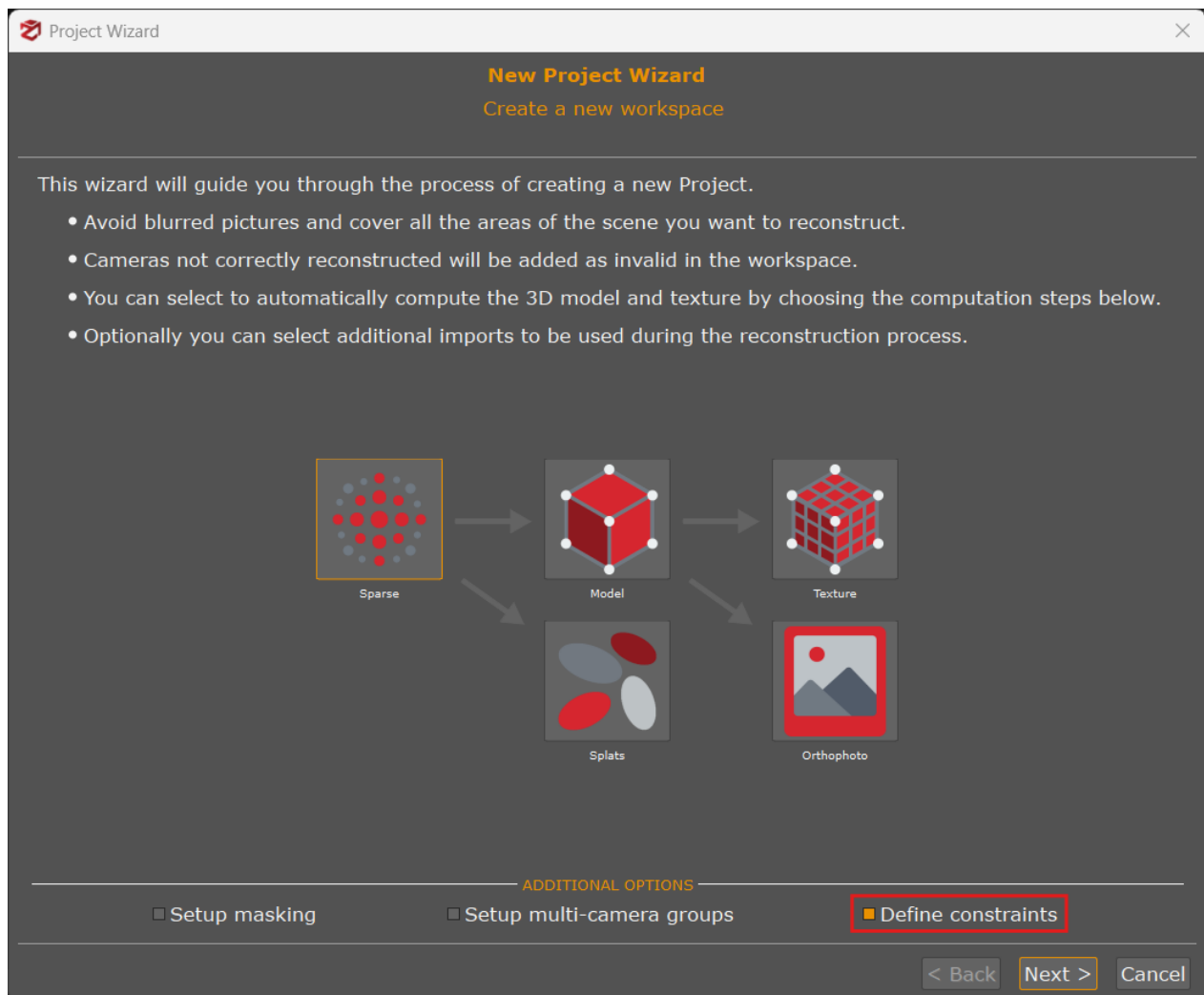
In the "Rotation (deg)" field, you can specify the the rotation (in degrees) along the axis X-Y-Z that bring the selected group to the reference camera. The accuracy for each angle can be also specified.

Import Constraints

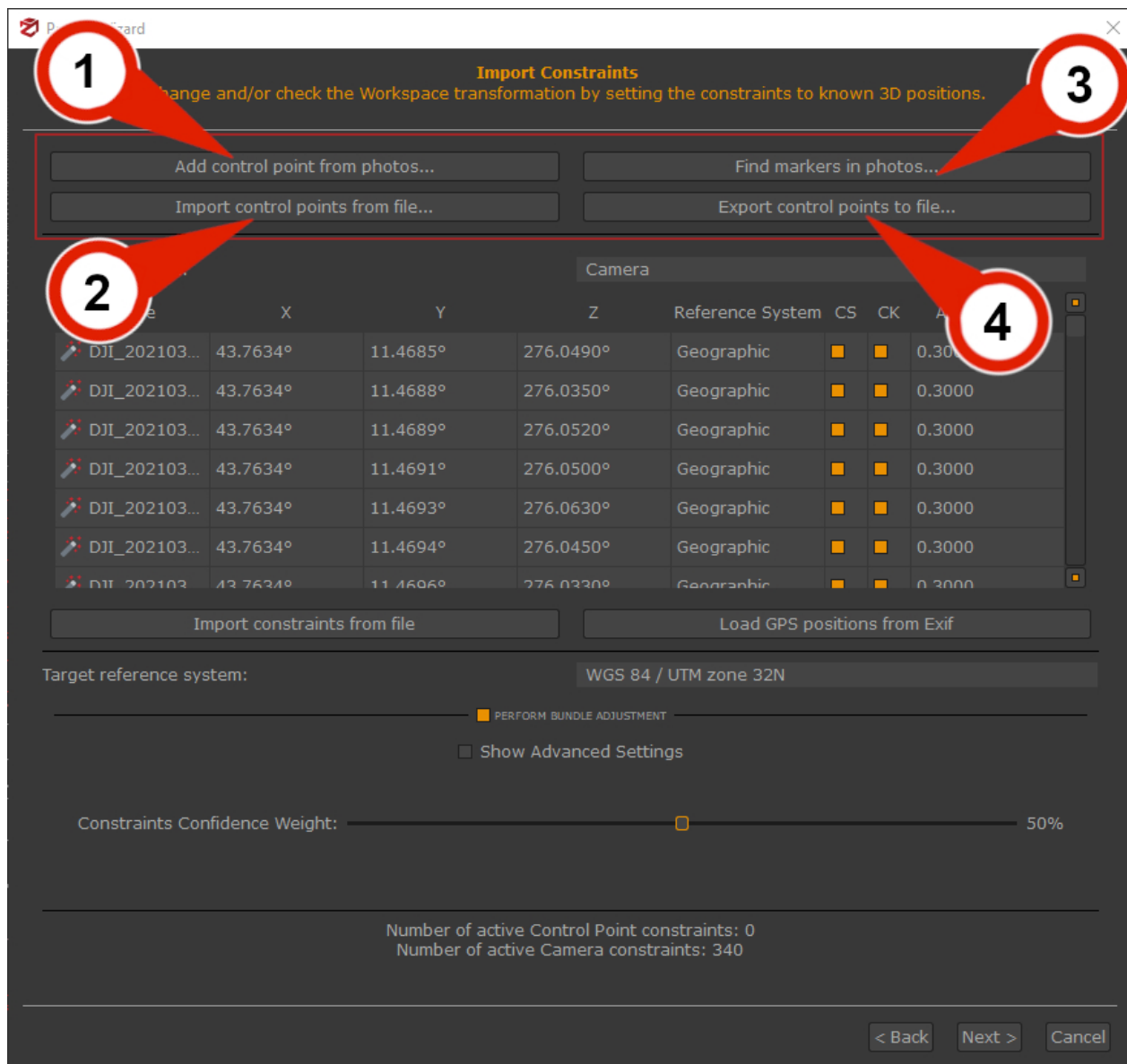
These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

As part of the workflow for creating a new project, constraints can be set by importing known 3D positions from external control points and geographic positions from images. To do this, the **"Define constraints"** check-box should be activated on the first page of the **New Project Wizard**.

Note: camera position constraints with RTK coordinates will be recognized automatically.



The **Import Constraints** page will follow the **Camera calibration** page. In the page's upper section, it's possible to open different tools for control point management.



Add control points from photo (1):

This tool allows the placement editing of 2D image coordinates, picking control points directly from the photos.

For the scaling process, you must place each control point on at least three pictures. It is also advisable to pick the control point on as many pictures as possible if you plan to leverage control points to adjust the camera positions using the Bundle Adjustment optimization.

The use of this feature is suitable for dealing with small/medium number images and in special cases where you want to improve image orientation by providing more data to the 3DF Zephyr SFM algorithm.

Import control points from file (2):

It opens the import control point tool for importing 2D image coordinates from text or csv

files.

This feature is advisable when you have already created project 1 with oriented images associated with spatial coordinates and want to use them in project 2 to improve the orientation of cameras in special cases. If you are also dealing with huge datasets and/or large numbers of control points, then you can import GCPs at once rather than scrolling the whole set of images again; it may be way more time-saving.

Find markers in photos (3):

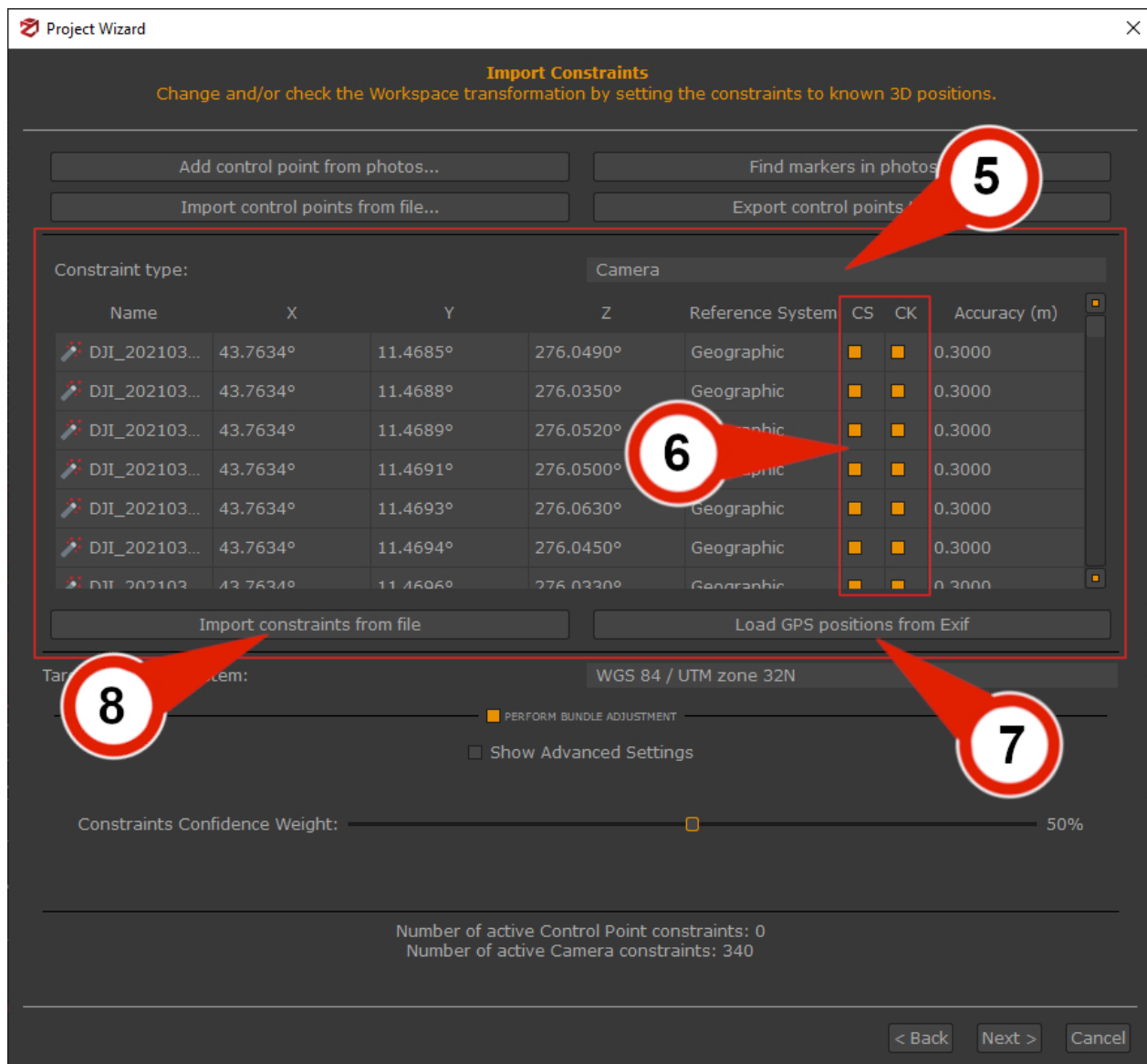
It opens the Detect marker tool for finding automatically markers placed in the scene.

Export control points to file (4):

This function allows to export 2D image coordinates associated with Ground Control Points (GCP) to a text or CSV file, creating a *ControlPoints2D.txt file. Each line defines a GCP as a 2D image coordinate:

"GCP1"	"IMG_3319.jpg"	4.33473658e+03	2.24061730e+03
"GCP1"	"IMG_3320.jpg"	3.30352087e+03	2.42468881e+03
"GCP2"	"IMG_3319.jpg"	3.01642756e+03	3.16114630e+03
"GCP2"	"IMG_3320.jpg"	1.68567672e+03	2.14786953e+03

The middle section it features the **constraint tab**.



The **Constraint type filter (5)** allows to change the view to

- Camera: this option allows viewing the GPS coordinates of each image.
- Control point: this option will allow the display of the imported constraints from an external source.

Pressing "CTRL+A" will allow selecting all the tab rows, and "Right-click" with the cursor will allow you to change *Reference system* and *Accuracy* for each camera or control point.

Constraints and Check Points column (6)

Each control point can be set as Checkpoint (to measure the residuals), Constraint (used in the bundle adjustment), or both by using the check-boxes on the left of each point. It's always a good idea to include some checkpoints that are not set as constraints.

- **Constraints (CS)** are those points you are most confident of in terms of accuracy level, and 3DF Zephyr relies on them to drive the scaling process.

- **Checkpoints (CK)** are references that the software only considers while scaling to monitor the error value.

Load GPS position from Exif (7)

This button import camera positions by loading them from Exif information and using them as constraints.

A common scenario is when loading information from images taken by drones or UAV systems that record the GPS coordinates of the shots in Exif data.

Import constraints from a file (8)

this function allows directly set constraints from a text or .csv file via the "Import constraints from file" button; the imported coordinates and the GCPs you have added to the project must have the same name/label.

Coordinates should be defined using the following syntax:

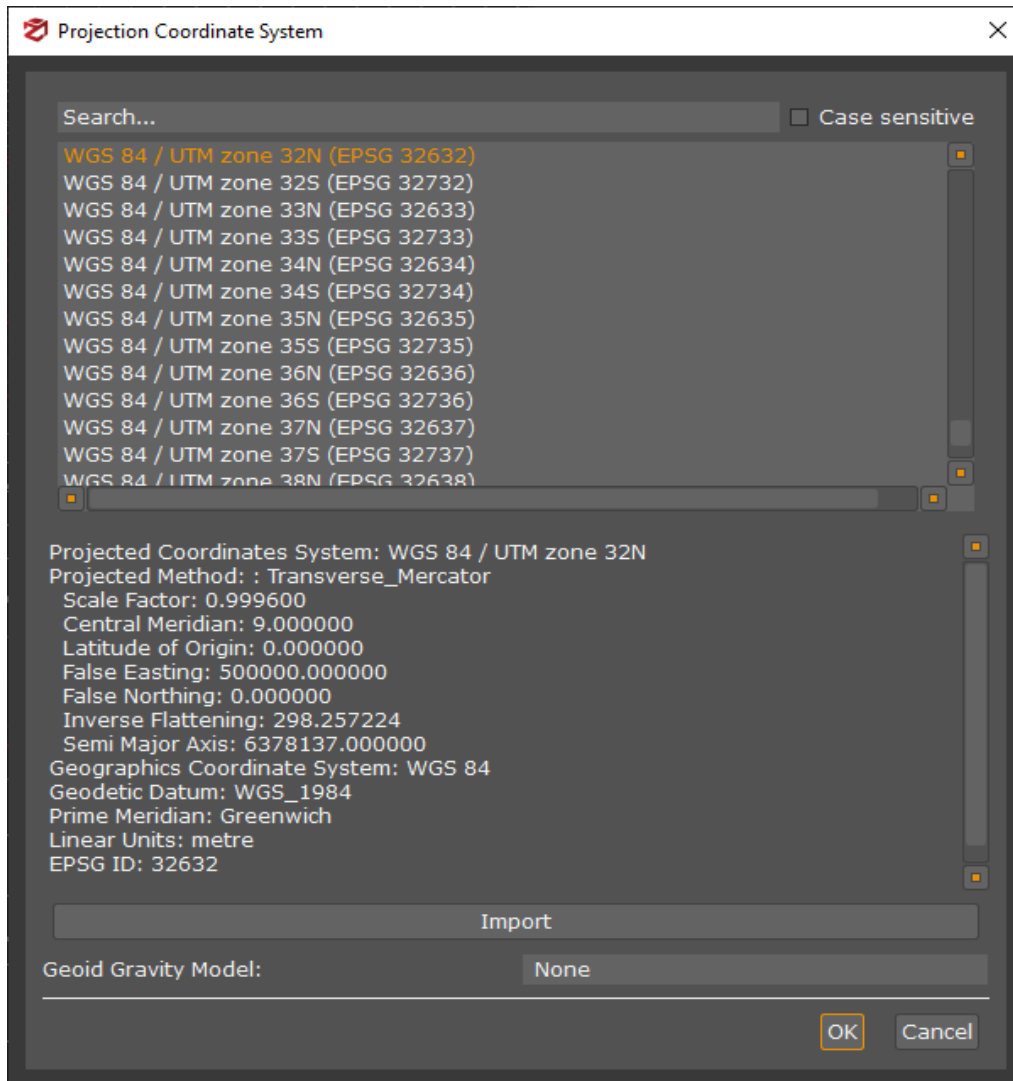
```
"Control_Point_1" 8.18880729e-01 -5.14516149e-01 4.54143586e-01
"Control_Point_2" -5.64690812e-01 -5.65085273e-01 1.09244112e+00
```

Note: control points coordinates can be selected and imported after creating a sparse point cloud from the "**Align model with 3D constraints**" menu.

The lower wizard's section displays the **Target reference system** and the **Bundle Adjustment** check-box.

The **Reference System** can be changed by clicking on it and choosing the **Select reference system** option from the drop-down menu.

The **Projection Coordinates System** window will be open:



It's possible to select the new coordinate reference system from the 3DF Zephyr database, or import a new one from an external source by clicking the **'Import'** button and clicking **"OK"**.

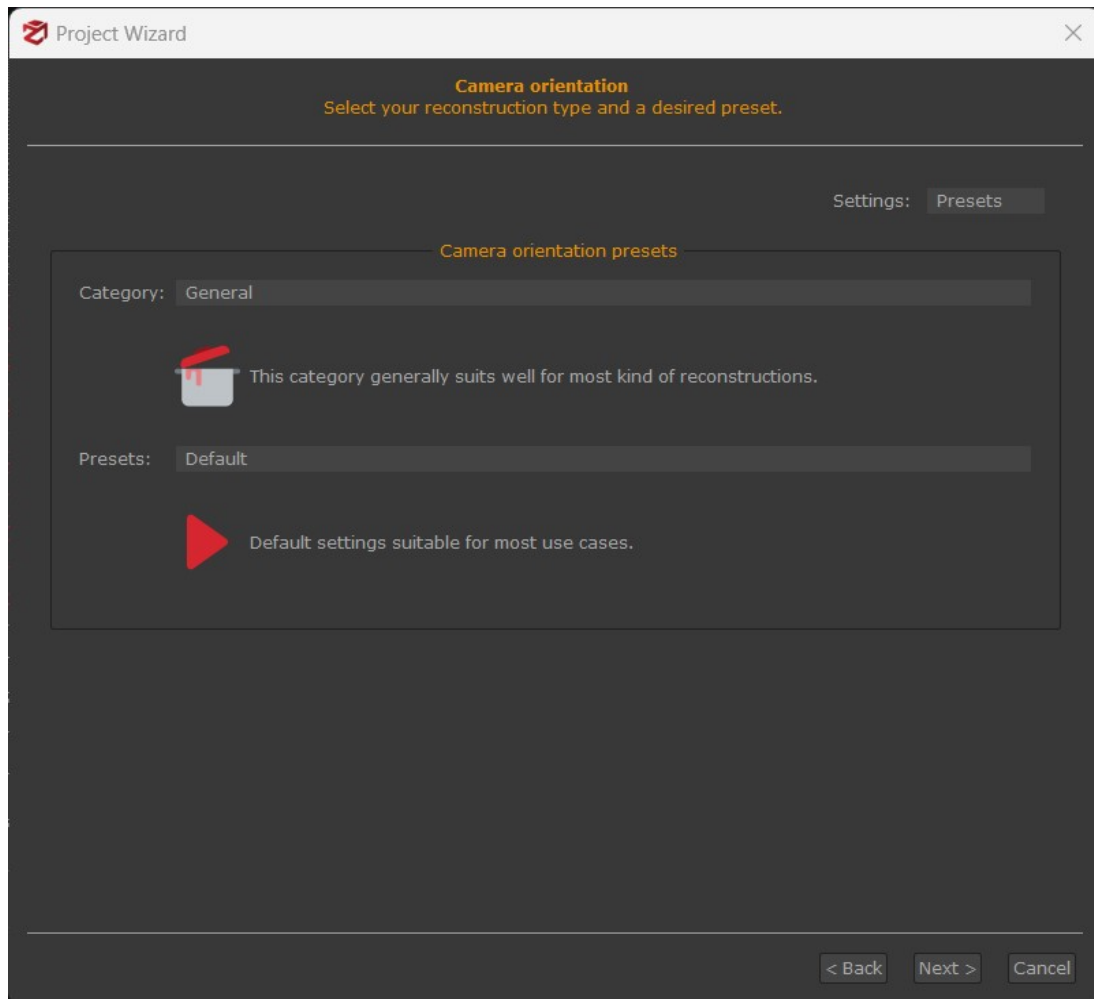
Optionally, a **Geoid Gravity Model** can also be loaded in relation to the Coordinate Reference System.

Bundle Adjustment check-box

It's possible to enable/disable the **"Perform Bundle Adjustment"** option to optimize the camera positions, and minimizing the reprojection error of the control points you have added to the project. The slider will allow setting the global confidence weight for the control points used as constraints.

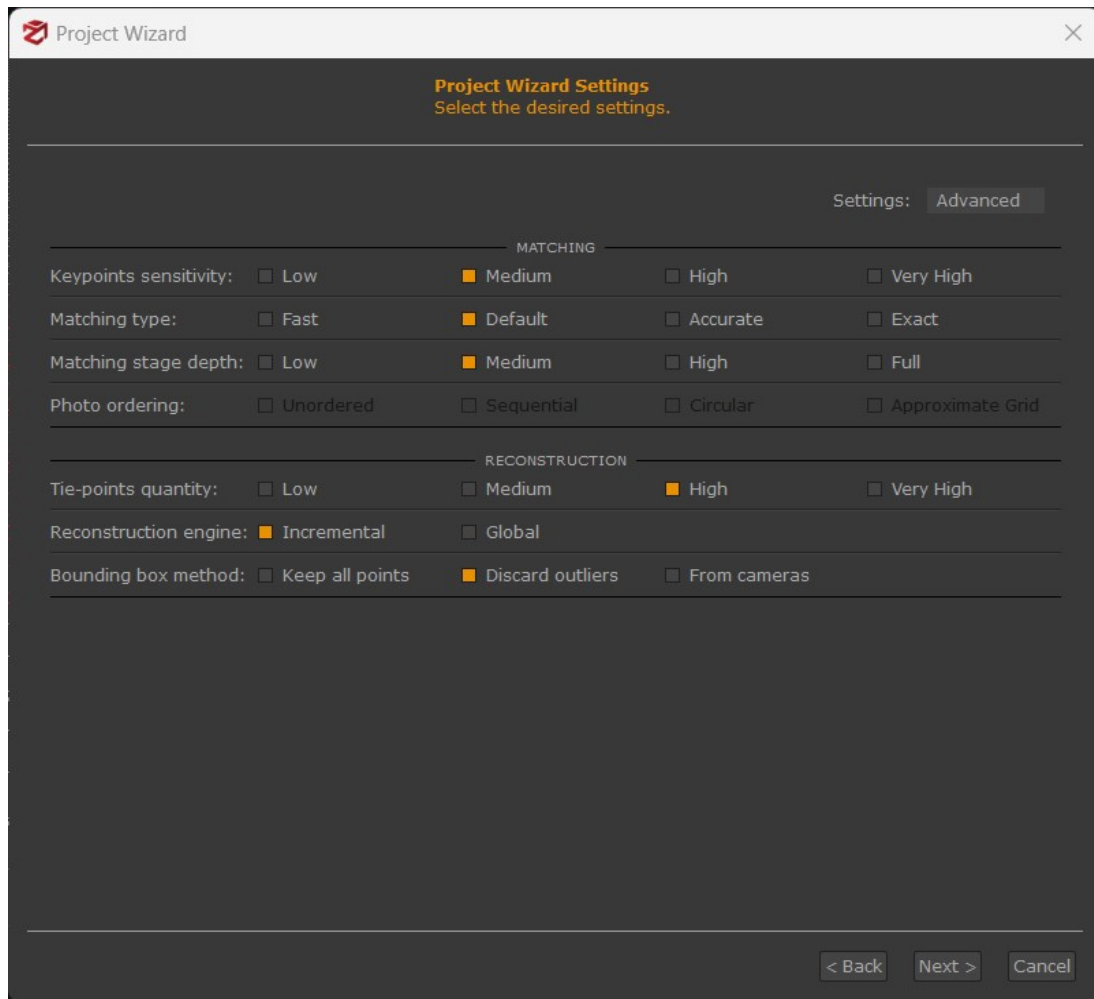
Cameras orientation

The first phase of 3D reconstruction is called Structure from Motion and computes the position and orientation of each photo loaded in Zephyr. This step results in a sparse point cloud.



Users must define the **Category** depending on the scenario/subject they have captured, and select the **Preset** according to the accuracy and quality level they want to achieve on the 3D model(s).

You can switch to the **Advanced settings** by clicking the drop-down menu in the upper right corner of the window.



The advanced settings are explained in detail below:

Keypoints Sensitivity: "keypoints" refers to the matched pixels in the pictures. This parameter determines the maximum number of keypoints that are to be extracted for each image. Please note that **a substantial number of keypoints does not lead to a better result** since the more elements involved, the higher the ambiguity during the matching phase.

Low:	extracts up to 5,000 keypoints per image
Medium:	extracts up to 7,500 keypoints per image
High:	extracts up to 10,000 keypoints per image
Very High:	extracts up to 15,000 keypoints per image

It is recommended to decrease keypoints density when:

- the outcome is required quickly;
- the distance between the cameras and the subject/scene does not vary;
- pictures have enough (at least 60%) and high (70% - 80%) overlap;

It is recommended to increase keypoints density when:

- cameras are not oriented properly;
- pictures are too close to or too far from the subject/scene;
- pictures have low overlap;
- the subject/scene has a uniform or textureless surface (e.g., a white wall);

Matching Type: controls which optimizations (if any) should be used when computing matches between images. The "accurate" option will take longer to complete camera orientation;

Matching Stage Depth: controls how many keypoint matches are performed on the images. Usually, the more is the better, however, this comes at a computational cost.

It is recommended to decrease this parameter when:

- the outcome is required quickly;
- cameras are close to the subject/scene;
- pictures come with good texturing and high overlap (70% - 80%);

It is recommended to increase this parameter when:

- cameras are not oriented properly;
- pictures are too close to or too far from the subject/scene;
- pictures have low overlap;
- the subject/scene has uniform or texture-less surfaces (e.g., a white wall);

Photo Ordering: this parameter tells 3DF Zephyr which capture sequence has been leveraged onsite, thus speeding up the near-image detection. By using the "**sequential**" option, you are telling 3DF Zephyr the pictures have been taken sequentially (photo 1 - photo 2 - photo 2 - photo 3 - etc.), while the "**circular**" option hints at a closed loop sequence.

If you don't know the photo order, pick the "**unordered**" option. The last "**approximate grid**" option is designed for nadiral aerial datasets.

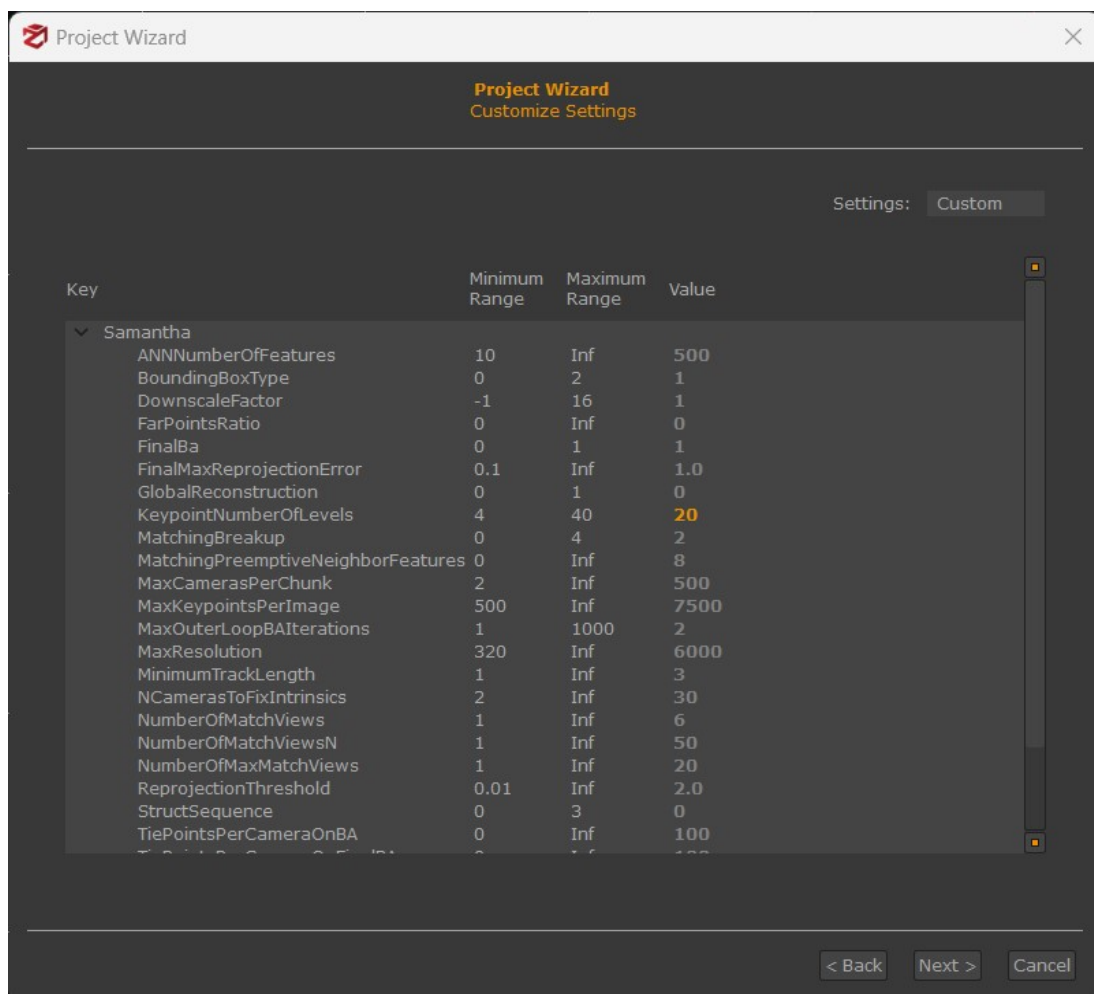
Tie-points quantity: this value affects the number of points to be considered during the Bundle Adjustment optimization. A higher value can lead to better results and a higher computational cost.

Reconstruction Engine: 3DF Samantha supports both incremental and global reconstruction pipelines. The global pipeline tries to solve the orientation problem globally, which means that it's usually faster than the incremental one and potentially less prone to drifting error. The incremental engine on the other hand, albeit slower, tends to include more cameras in the final solution. In a nutshell, you are supposed to use the global pipeline if you are processing a huge dataset (more than 1000 pictures).

Bounding box method: it defines the computation method of the bounding box. It's recommended to keep the default option "discard outliers", namely the far points that are not relevant to the 3D reconstruction.

A further description of those parameters is available here: <http://www.3dflow.net/3df-zephyr-parameters-tuning-guide/>

From the "**Settings**" drop-down menu, you may also select the "**Custom**" mode. This mode allows you to fine-tune in detail every single reconstruction parameter. Remember that you can load an XML file or reset the values to default settings by right-clicking and selecting the desired option. Please note that a hint related to the selected parameter is shown at the bottom of the window.



Once the camera orientation phase has been completed, the sparse point cloud will appear in the workspace as well as the oriented cameras identified by blue pyramids whose size and color are editable from the **Options** menu.

ACCURACY EVALUATION OF CAMERAS ORIENTATION PHASE

Once you are done with the first 3D reconstruction step, it is advisable to check its accuracy in order to figure out which pictures should be discarded to decrease the error even on further phases.

By clicking on **Tools > Workspace > Camera Stats** the following chart will appear:

Camera stats

Projection method: WGS 84 / UTM zone 35N

Name	Latitude (deg)	Longitude (deg)	Altitude (deg)	X (m)	Y (m)	Z (m)	Yaw (deg)	Pitch (deg)	Roll (deg)	Mean Reproj. Error	Points
 39,6821	28,0011	343,928	585851	4,39295E+06	343,928	150,556	0,579771	134,877	0,818597	3179	
 39,682	28,0013	343,872	585869	4,39294E+06	343,872	150,389	0,587518	128,893	0,749849	4155	
 39,6819	28,0014	343,913	585877	4,39293E+06	343,913	150,334	0,623336	129,548	0,70201	5076	
 39,6818	28,0015	343,904	585885	4,39292E+06	343,904	150,271	0,611056	130,051	0,700622	5311	
 39,6818	28,0016	343,861	585893	4,39292E+06	343,861	150,248	0,64757	130,302	0,707211	5405	
 39,6817	28,0017	343,888	585901	4,39291E+06	343,888	150,179	0,6981	130,894	0,683726	5568	
 39,6816	28,0018	343,871	585909	4,3929E+06	343,871	150,137	0,692088	130,26	0,640125	6036	
 39,6816	28,0018	343,851	585913	4,3929E+06	343,851	150,12	0,673259	129,072	0,659479	5893	
 39,6816	28,002	343,856	585923	4,3929E+06	343,856	150,019	0,806771	93,1973	0,70148	5112	
 39,6816	28,0021	343,901	585934	4,3929E+06	343,901	149,936	0,862499	90,9439	0,683728	5295	
 39,6816	28,0021	343,91	585936	4,3929E+06	343,91	150,95	1,8867	64,826	0,74561	4387	
 39,6817	28,002	343,858	585927	4,39291E+06	343,858	150,565	1,18359	-44,4861	0,733452	4833	
 39,6817	28,0019	343,922	585919	4,39291E+06	343,922	150,409	1,15539	-47,3238	0,703474	4997	
 39,6818	28,0018	343,944	585911	4,39292E+06	343,944	150,324	1,13366	-48,4422	0,750079	4589	
 39,6823	28,0011	343,849	585853	4,39297E+06	343,849	149,829	0,866529	-42,7411	0,747575	4495	

The two columns on the right show the **Mean reprojection error** for each picture and the **Points**, namely the number of keypoints (the points for which the software retrieved the position) detected in each photo. By clicking on the entries "Mean Reproj. Error" and "Points", users can sort the values in decreasing or ascending order.

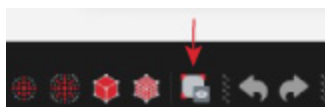
Overall, a well-oriented picture with a good accuracy degree results in a low reprojection error and a number of keypoints. Keypoints represent the equations amount exploited during the reconstruction phase, so their high value is related to the higher reliability of the final result. It's worth noting that the reprojection error gives a rough idea of the orientation accuracy since it should always be related to the sensor size of the camera.

The bounding box

When the sparse point cloud has been created, the bounding box will be computed as well. The bounding box corresponds to the volume in which all points that do not fall into said volume will be discarded in the next 3D reconstruction steps.

You can then change how Zephyr behaves by editing the bounding box settings (not just for "what" is being reconstructed, but also the discretization level changes when the volume changes too).

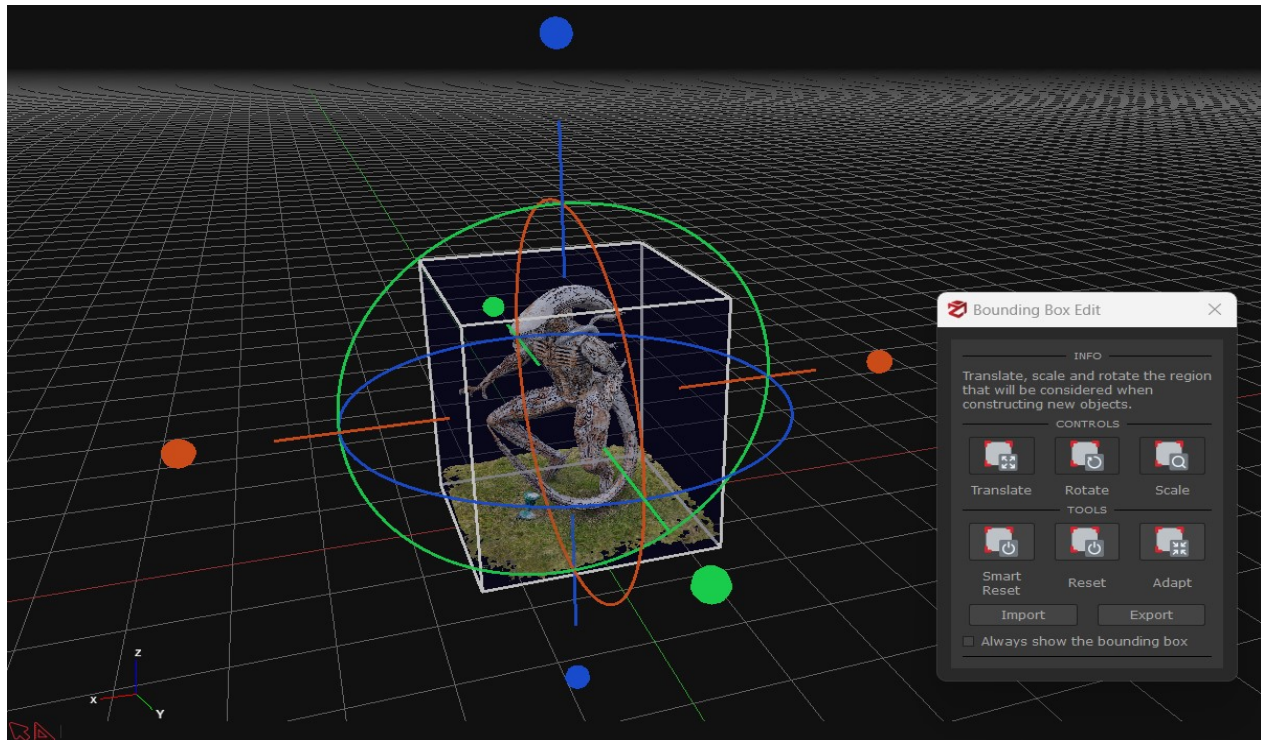
You can enable the bounding box visualization - and edit it - either from the **Scene** menu or by clicking the related icon in the top toolbar.



Once enabled, the bounding box will be visible in the 3D viewport and the bounding box edit widget will appear on the screen. You can toggle the bounding box controls using this widget.

We suggest to enable - and adapt if need be - the bounding box as soon as you complete the sparse point cloud generation. This way you are aware of what will be

affected in the next 3D reconstruction steps.



Translate: click and drag the desired gizmo to move the bounding box over the selected axis.

Rotate: click and drag the desired gizmo to rotate the bounding box over the selected rotation axis.

Scale: click and the desired face of the bounding box to scale the bounding box.

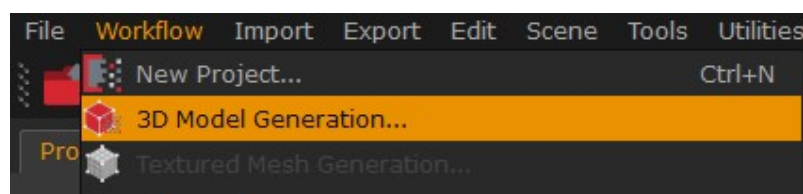
Reset/smart reset: resets the bounding box (the smart reset will try to automatically fit the bounding box to the computed point cloud).

Adapt: it allows to adapt the bounding box to one of the objects in the workspace (sparse point cloud, dense point cloud, mesh, etc.).

Always show the bounding box: keeps the bounding box rendered in the scene even when the bounding box widget is closed.

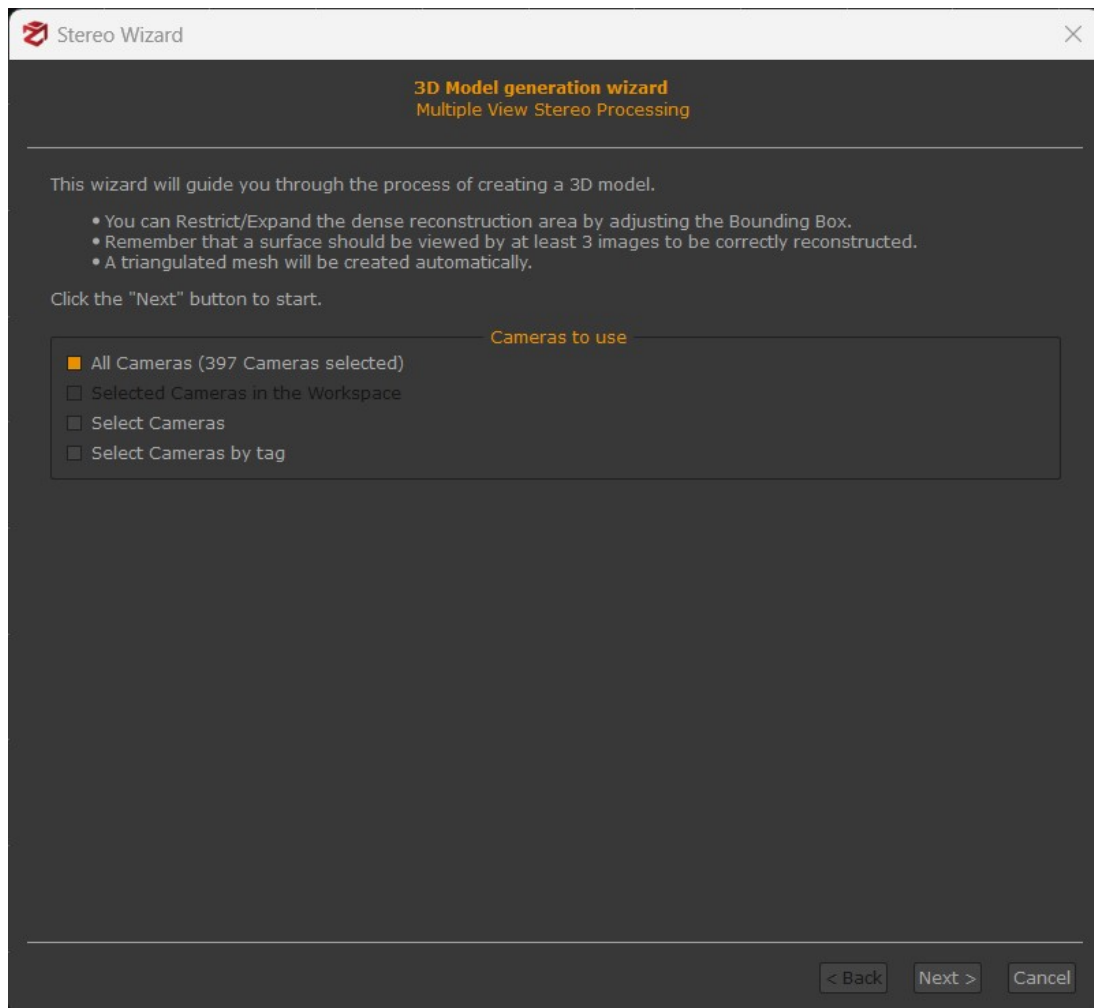
3D Model Generation

To start the process, simply click on **Workflow > 3D Model Generation** or click on the corresponding icon in the toolbar after the camera orientation phase has been completed.



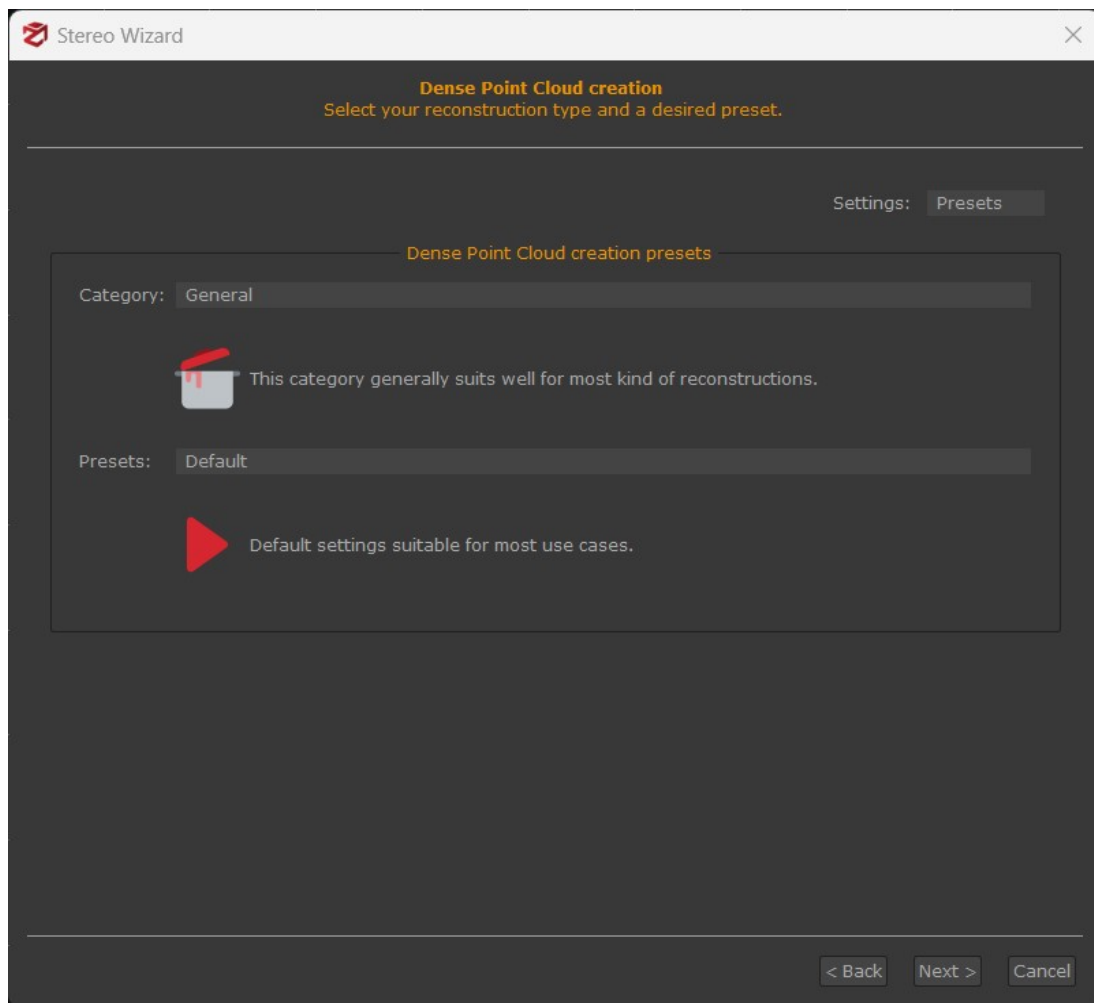
Tip: Before starting the 3D model generation, it is advisable to set the 3D reconstruction volume by [editing the Bounding Box](#). This step is an optional one as the bounding box is automatically generated. By adapting the bounding box, you can improve the results and speed up the computation time.

The first page of the 3D model generation wizard allows to pick the cameras to be used for the dense point cloud creation. You will notice the **"All cameras"** option is enabled by default, however, you can select a subsample of pictures choosing the **"Select cameras"** or the **"Select cameras by tag"** options. You can also manually select the cameras in the workspace by first using the **camera selection tool** from the **Editing** panel. Click the **"Next"** button when you are done.



Like the first 3D reconstruction step, the dense point cloud creation and the mesh generation phases can also be set using categories and presets, advanced or custom modes.

While categories and presets are described below, for the advanced settings please refer to [this document](#) for the dense point cloud generation, and [this document](#) for the mesh creation.

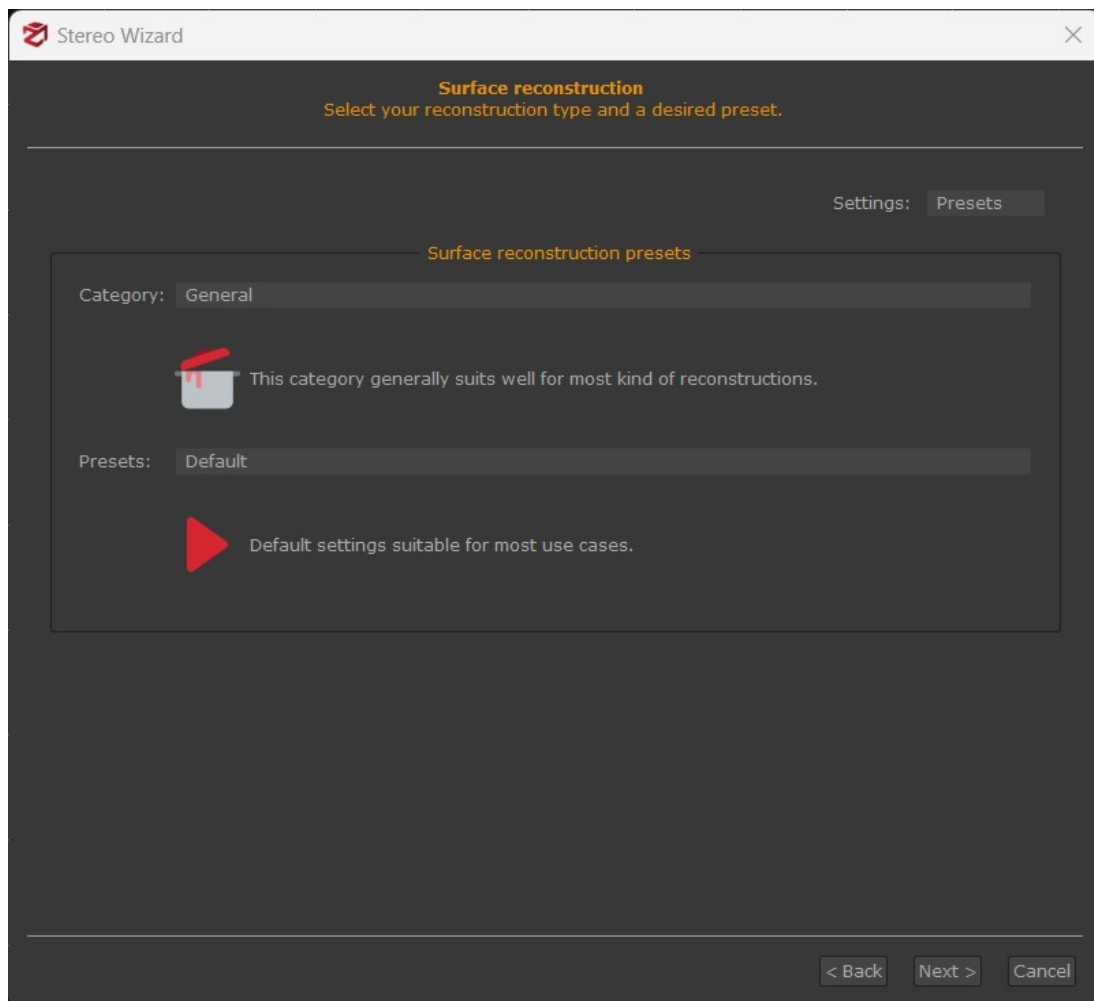


Dense point cloud categories

- **General:** works in most cases, to be picked even when you are undecided about which category to use.
- **Aerial - Nadiral images:** use this category when you are reconstructing a top-down view scenario, typically a UAV dataset.
- **Urban:** use this category if the pictures have not been taken from the same distance from the subject/scene, or if you have mixed different types of photos.
- **Human Body:** use this category when you are scanning human body parts, including closeups or full figures.
- **Surface Scan:** use this category to reconstruct flat surface closeups, like terrain or ground.
- **Vertical Structure:** use this category to reconstruct BTS / telecommunication towers or other thin vertical structures from UAV pictures.

Dense point cloud presets

- **Preview:** this preset skips the Stereo phase and uses the sparse point cloud as the dense point cloud.
- **Default:** to be used in most cases.
- **High details:** higher resolution, slower but produces a more dense point cloud.



Mesh generation categories

- **General:** works in most cases, to be used even when you are undecided about which preset to use.
- **Aerial - Nadiral images:** use this category when you are reconstructing a top-down view scenario, typically a UAV dataset.
- **Urban:** use this category if the pictures have not been taken from the same distance from the subject/scene, or if you have mixed different types of photos.
- **Human Body:** use this category when you are scanning human body parts, including

closeups or full figures.

- **Surface Scan:** use this category to reconstruct flat surface closeups, like terrain or ground.
- **Vertical Structure:** use this category to reconstruct BTS / telecommunication towers or other thin vertical structures from UAV pictures.
- **Laser Scan:** Use this category to extract meshes from laser scans point clouds.

Mesh generation presets

- **Preview:** default settings with no photoconsistency optimization.
- **Default:** to be used in most cases.
- **High details:** increased resolution during photoconsistency, slower but produces a mesh with more polygons.

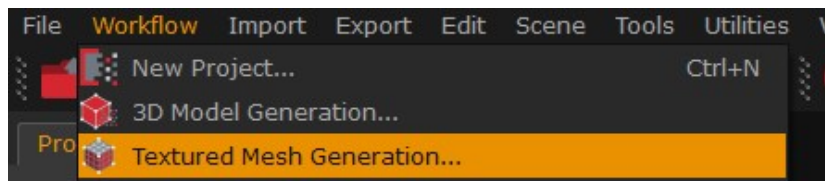
Once you have defined the above settings, you can click the **"Next"** button first and the **"Run"** button afterward.

The dense point cloud generation places the greatest demands on hardware capabilities along with the camera orientation phase.

Remember that you can reconstruct and add more dense point clouds and meshes in the same Zephyr project, even leveraging different parameters or reconstruction volumes.

Texture generation

The fourth and last 3D reconstruction step allows to run the **textured mesh generation**. Simply click **Workflow > Textured mesh generation**.



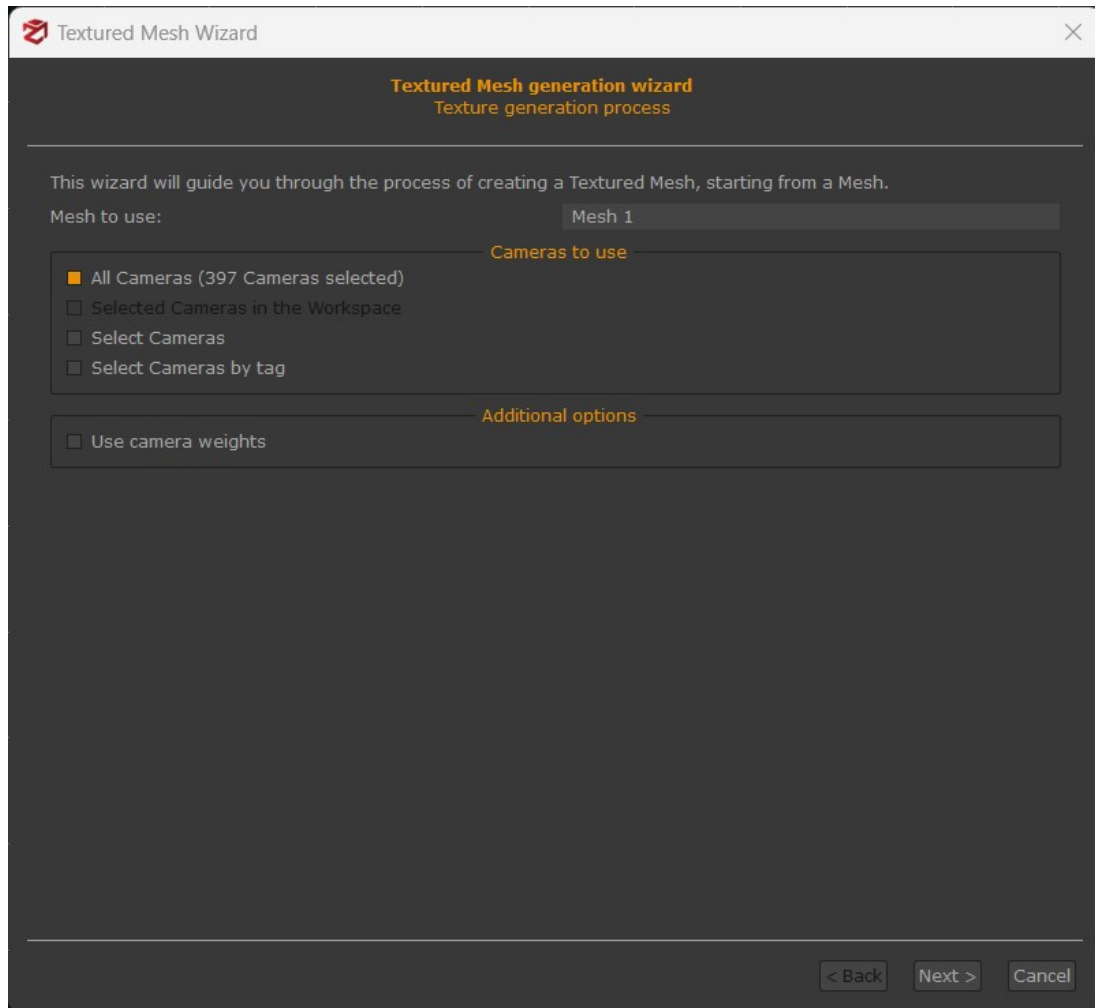
Like the previous 3D reconstruction steps, the textured mesh generation phase can also be set using categories and presets, advanced or custom modes.

The first page of the textured mesh generation allows to pick the cameras to be used for the texture creation. You will notice the **"All cameras"** option is enabled by default, however, you can select a subsample of pictures choosing the **"Select cameras"** or the **"Select cameras by tag"** options. You can also manually select the cameras in the workspace by first using the **camera selection tool** from the **Editing** panel.

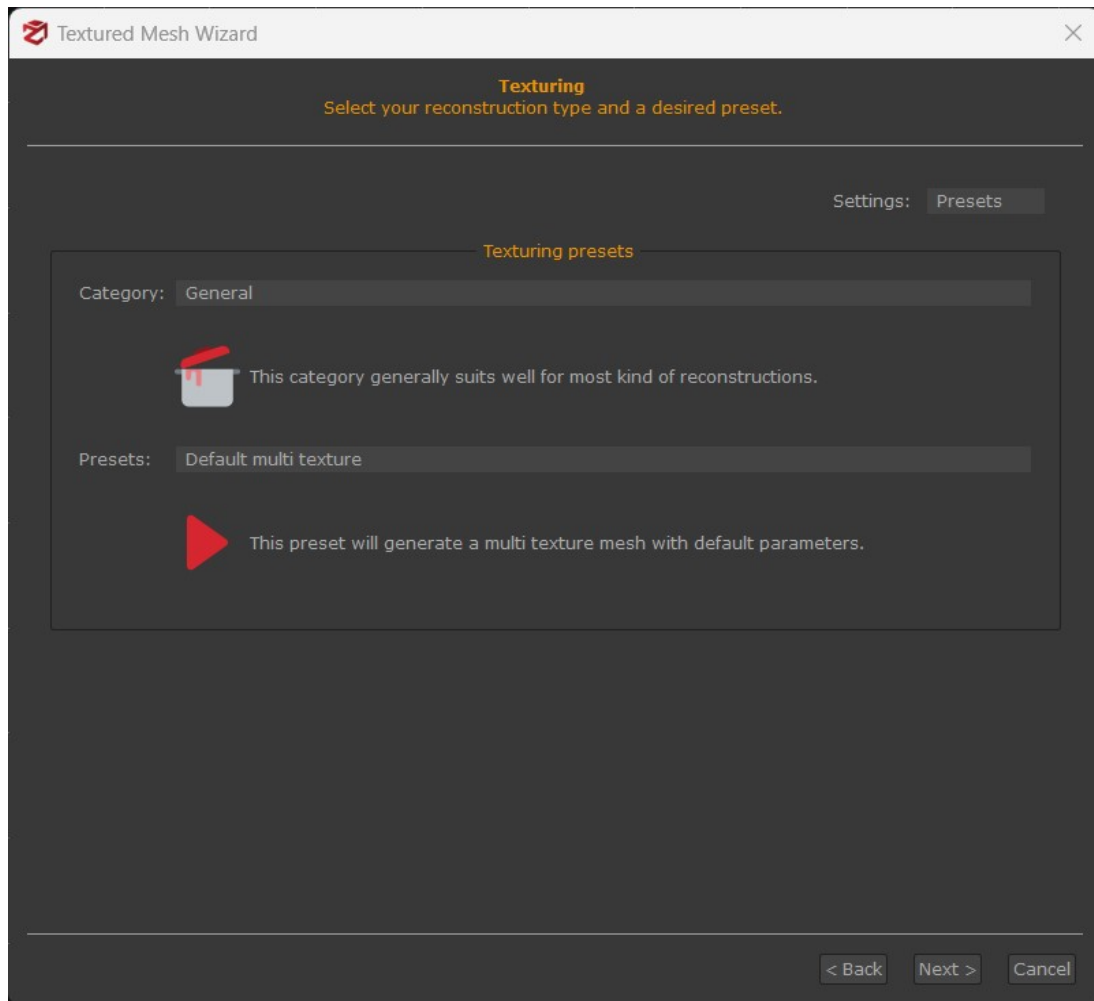
The **"Use camera weights"** option may be enabled if you want to assign a specific reliability value (0.1 to 1.0) for each camera. Please, consider that weights are taken into

account along with the camera visibility for each polygon.

Click the "**Next**" button when you are done.



Categories and Presets for the textured mesh generation are described below.



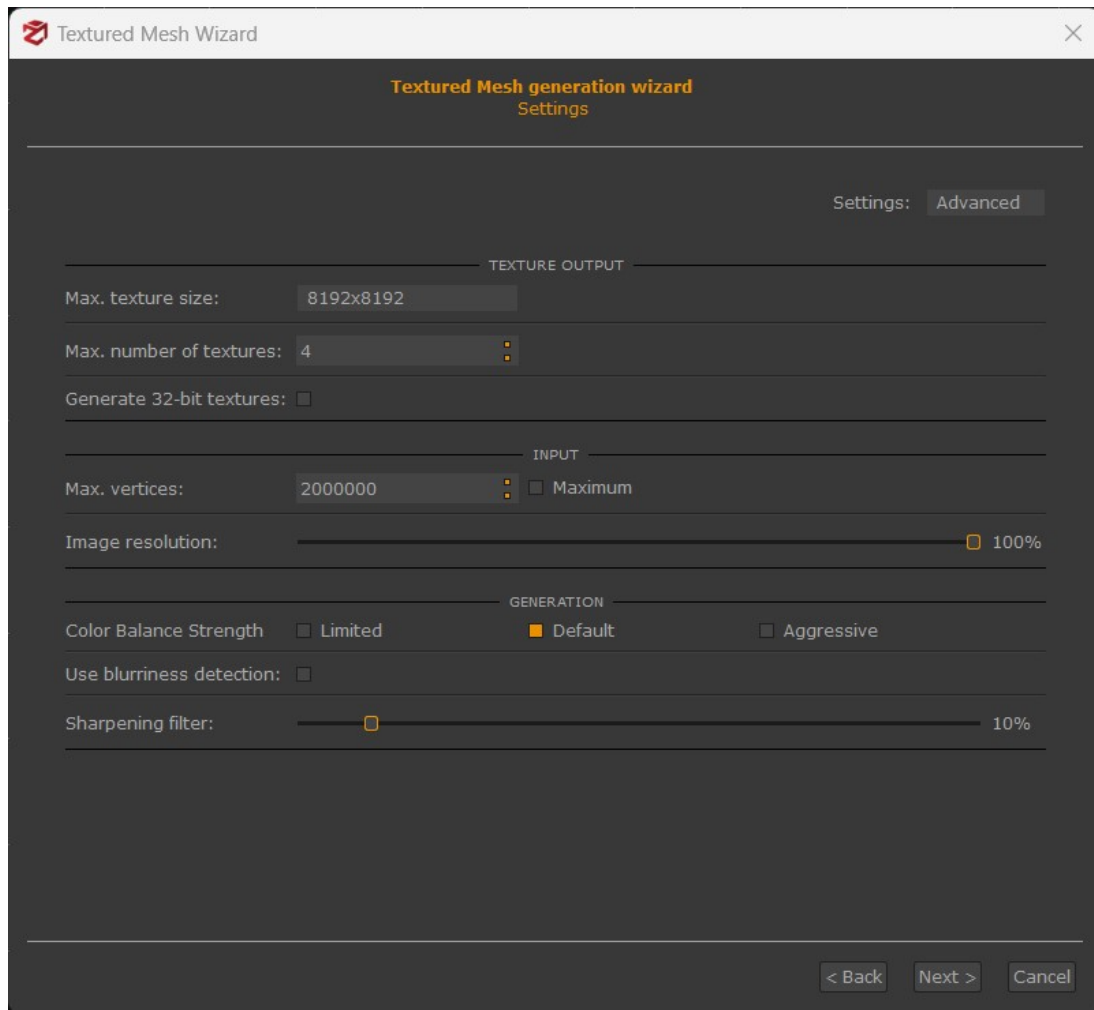
Textured mesh categories

- **General:** works in most cases.
- **Vertical Structure:** use this category to reconstruct BTS / telecommunication towers or other thin vertical structures from UAV pictures.

Textured mesh presets

- **Low Poly:** generates a single, low poly textured mesh.
- **Default Single Texture:** generates a single textured mesh with default parameters.
- **Default Multi Texture:** generates a multi textured mesh with default parameters.
- **High details:** generates a multi textured high-resolution mesh.

The below wizard will appear when selecting the **"Advanced"** settings from the drop-down menu on the upper right corner:



Max. texture size: sets the maximum size of the texture. Please note that a two-value power is not guaranteed, as it is just a higher limit value, although Zephyr will make it a power of two when the input images allow it to do so. Nevertheless, selecting a resize is possible when exporting the textured mesh (see the "Export menu" chapter).

Maximum number of textures: defines how many textures will be generated.

Generate 32-bit textures: enable this texture to save as 32-bit textures. If unsure, leave this unchecked, as it is used in specific workflows.

Max. vertices: defines how many vertices of the mesh are involved in the texture generation.

Image resolution: sets the resolution percentage for the texture generation process.

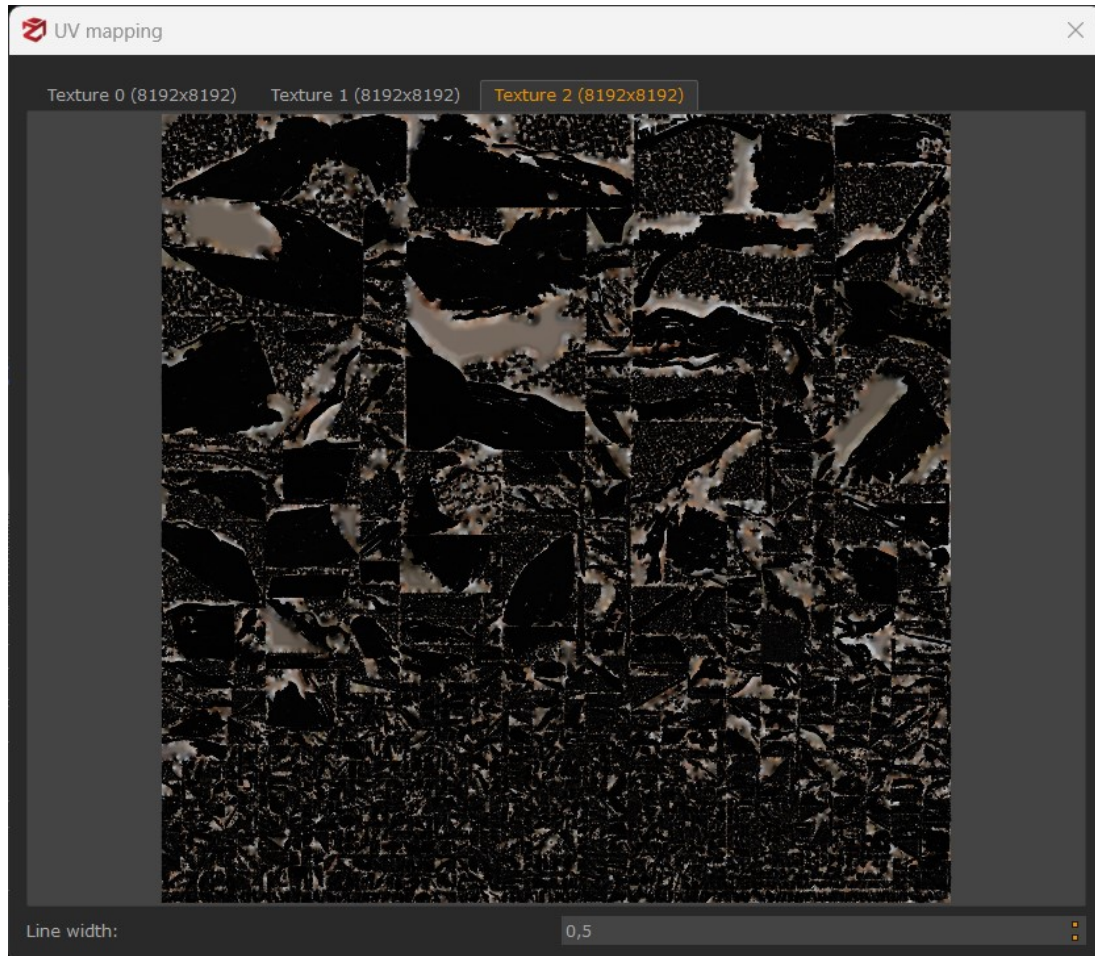
Color balance strength: adjusts the color balance strength according to the exposure values of the pictures.

Use blurriness detection: every picture contribution for each triangle will be weighted depending on its blurriness. That is useful when some of your photos are slightly blurred (e.g., the picture background).

Sharpening filter: weight of the sharpness filter that should be applied to the output texture(s).

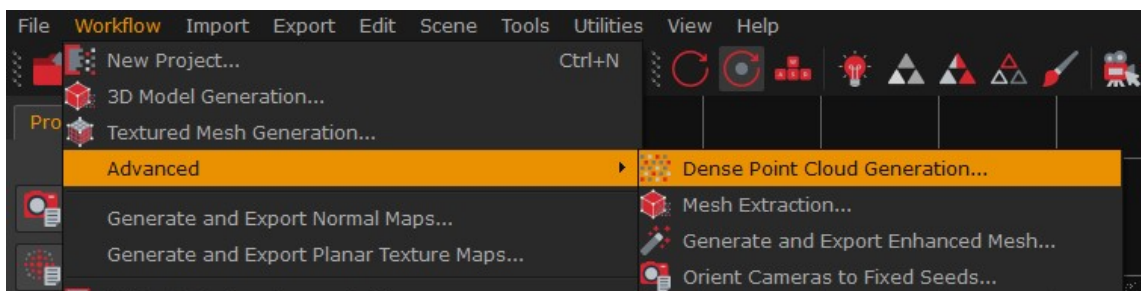
You can see the texture UV maps by right-clicking the textured mesh name in the **Project** panel and selecting the "**View UV mapping**" option.

UV maps are wrapped, so remember you can export a mesh, define your own UV mapping in an external software (e.g., Blender) and re-import the mesh to generate the texture again using your own custom UV maps from the "**Import**" menu ("**Import mesh with UV map**" tool).



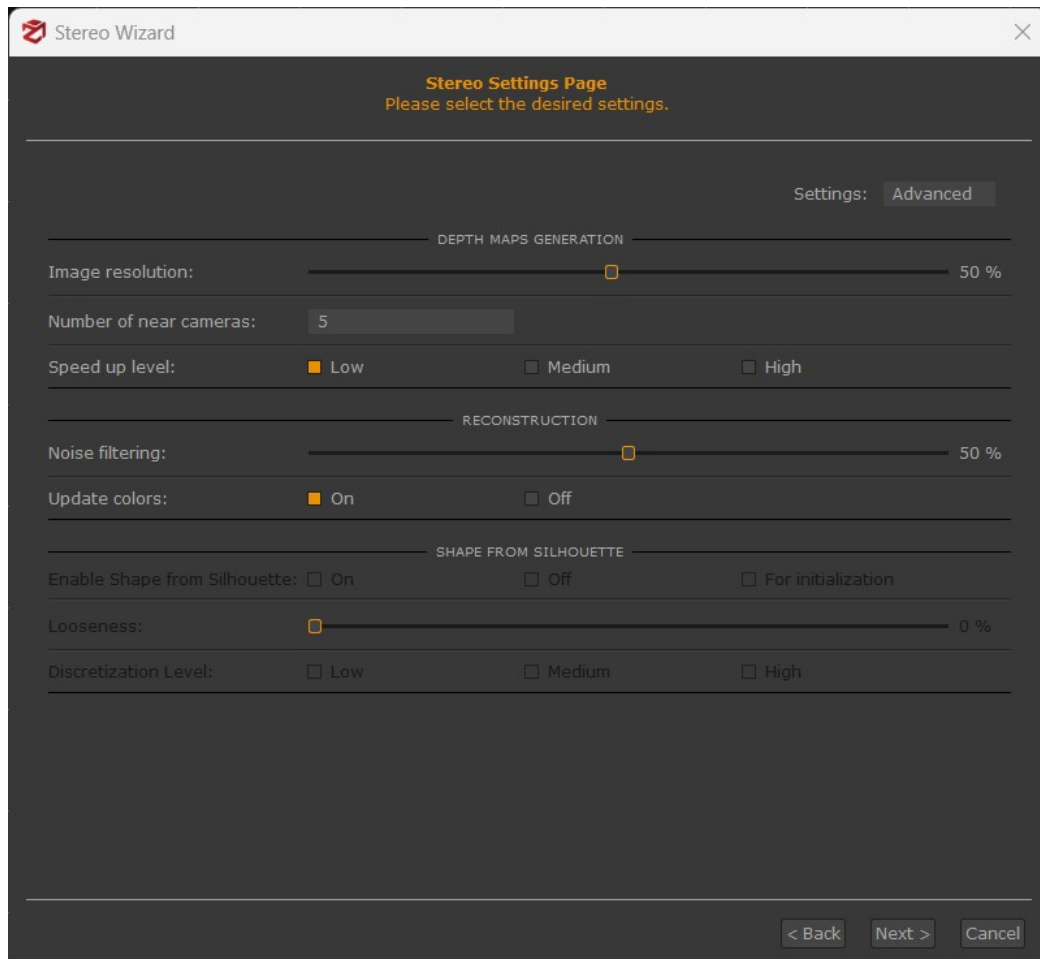
Extracting a dense point cloud

To start the process simply click on **Workflow > Advanced > Dense Point Cloud Generation** or click on the corresponding icon in the toolbar.



As of 3DF Zephyr 4.5 it is possible to access the dense cloud generation from the "**Advanced**" menu if need be. Repeating the dense point cloud generation using the generated model as an input for the dense cloud generation algorithm may yield better results, as a consequence of applying the photoconsistency-based optimization algorithm.

Advanced parameters are explained in detail below.



- **Image resolution:** defines the resolution used for the pictures. A higher resolution keeps more details, but it may produce noisy results if using low-quality photos. Processing time is strictly related to this parameter.
- **Number of nearest cameras:** the number of cameras used to create depth maps that is also linked to the number of oriented pictures. You should increase that value if you calculate that there are N photos for each camera that are aiming at the same point of the scene. Increasing the number of cameras may increase the processing time.
- **Speed up level:** allows a speedup factor that can be determined by preemptively discarding redundant pixels.
- **Noise filtering:** low values will produce much denser point clouds but with noisy

areas, whereas high values will produce cleaner clouds with fewer endpoints.

- **Update Colors:** updates colors once the computation is done.
- **Shape from Silhouette:** (feature available only in the full version of Zephyr) this is an image-based modeling technique that uses the profile, or silhouette, of the subject to create a virtual hull containing the subject. You must create the masks for all the pictures before running the dense point cloud generation phase using this option. This technique can be quite worthwhile when you need to deal with transparent or reflective surfaces which cannot be removed with 3DF Masquerade.
- **Discretization Level:** this parameter defines the level of accuracy of the dense cloud when it is extracted from masked images. Higher values will produce a more defined dense cloud, whereas lower values might be the best choice when masks are not super accurate.

Once you have defined the above settings, you can start the process by clicking the **"Run"** button.

3DF Zephyr uses multiple neighbors per reference camera during the multi-view stereo (MVS) process, leveraging three or more overlapping photos when available (sometimes referred as "multi-ray matching").

This is controlled by the "NumberOfNearestCameras" setting in the custom settings page. By default and in most presets, it's 4, meaning up to 5 cameras (the reference + 4 neighbors) can contribute to a single 3D point in a single depth map. Even if an area is viewed by only two cameras, it will still generate 3D points. However, areas with 3-4 cameras have much stronger support. This and all other settings can as usual be tweaked in the custom settings.

A further description of the advanced settings is available here:
<http://www.3dflow.net/3df-zephyr-parameters-tuning-guide/>

Raw and refined dense point clouds

3DF Zephyr may require to generate an intermediate dense point cloud in order to output a specific deliverable. This is called a "raw" dense point cloud in the context of 3DF Zephyr's workspace. The raw point cloud also allows us to compute the final deliverable faster as we can compute certain optimizations that we wouldn't be able in certain cases.

Since Zephyr 9, such temporary raw point clouds are directly stored in the workspace rather than being generated, used, and then discarded: this means that the whole context of your 3D reconstruction is never lost, and doesn't create confusion as to why a deliverable (for example, a mesh) comes out differently when doing the wizard workflow vs the advanced workflow (as in the older versions, you'd re-generate the mesh from a refined dense cloud in the workspace vs the intermediate raw point cloud from the wizard).

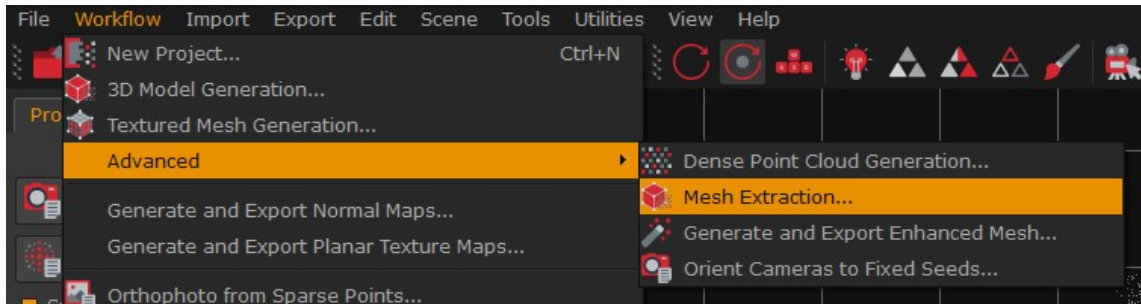
The drawback is that, this additional raw point cloud can take up some space on your

hard drive (which can be removed if not needed).

Raw point clouds are marked with the "raw" attribute within the workspace.

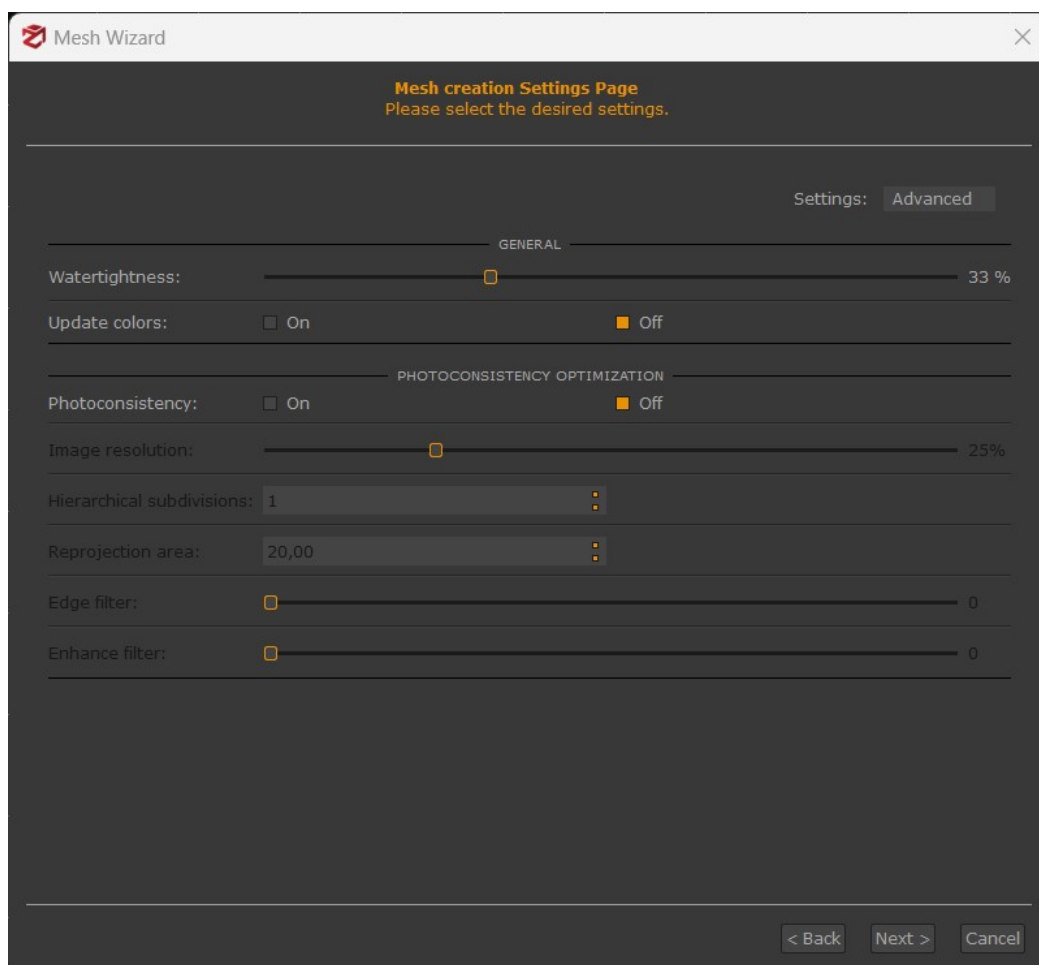
Extracting a mesh

To start the process simply click on **Workflow > Advanced > Mesh extraction** or click on the corresponding icon in the toolbar.



In the new window you need to select the dense point cloud you want to use to start the mesh generation. That is because you can create more dense point clouds in Zephyr.

Advanced parameters are explained in detail below.



- **Watertightness:** higher values will tend to close more holes.

- **Update colors:** updates colors once the computation is done.
- **Photoconsistency-based Optimization:** this algorithm improves the mesh details extracted by the mesh algorithm, and although it will require extra computation time, it's generally worth using it. Usually, you can get better results if the image resolution of the photoconsistency-based optimization is higher than the resolution used in the stereo step. You may also run the photoconsistency-based optimization as a [mesh filter](#) from **Tools > Mesh filters**. The same Photoconsistency parameters can also be found in the context menu to the workspace window's right, from the **Editing** tab > **Filtering > Photoconsistency**.
- **Image resolution:** controls the image's scale resolution used internally by the photoconsistency algorithm. If you already have suitable initial geometry, it is reasonable to run the photoconsistency with a high resolution (50% – 75%). If the input is of poor quality, it is advisable to leave a low resolution (25%).
- **Hierarchical subdivision:** if this value is greater than 0, the photoconsistency algorithm will be sequentially applied more times, automatically adjusting the image resolution and the iteration number. This means that the same results can be obtained by running the same algorithm multiple times with different and appropriate settings. More details on this setting are available at <https://www.3dflow.net/tutorial-point-cloud-and-mesh-filters/>
- **Reprojection area:** controls the size that every triangle will try to obtain at the end of the photoconsistency process. Given a triangle, its final reprojection area (in pixels) to the nearest camera will tend to get near the specified value. Lowering this value will make a denser mesh: the final mesh will then have a variable level of detail, with a higher vertex point cloud corresponding to those areas viewed by nearer cameras. In most cases, the default value will work well; in case you are dealing with a mesh that is already very good (for example, one that has already finished a photoconsistency step). This parameter can be lowered to get more detail; instead, it can be raised in very noisy meshes and low-quality images.
- **Edge filter:** it is a post-processing method that can generate “fake details” by increasing the number of mesh triangles. Depending on the result you want to obtain and the photo's quality, you need to carefully adjust the slider to avoid creating additional noise instead of additional details.
- **Enhance filter:** this parameter is used to emphasize edges; the more the mesh is angular (buildings, objects, etc.), the more you can increase this value. Usually, it can be kept at a value of 0.5.

You can start the mesh reconstruction by clicking on **Next** and then on the **Run** button.

Timing may vary depending on the number of polygons you have previously selected.

You can create several surfaces in the same Zephyr project using different parameters.

A further description of the parameters above is available here:

<http://www.3dflow.net/3df-zephyr-parameters-tuning-guide/>

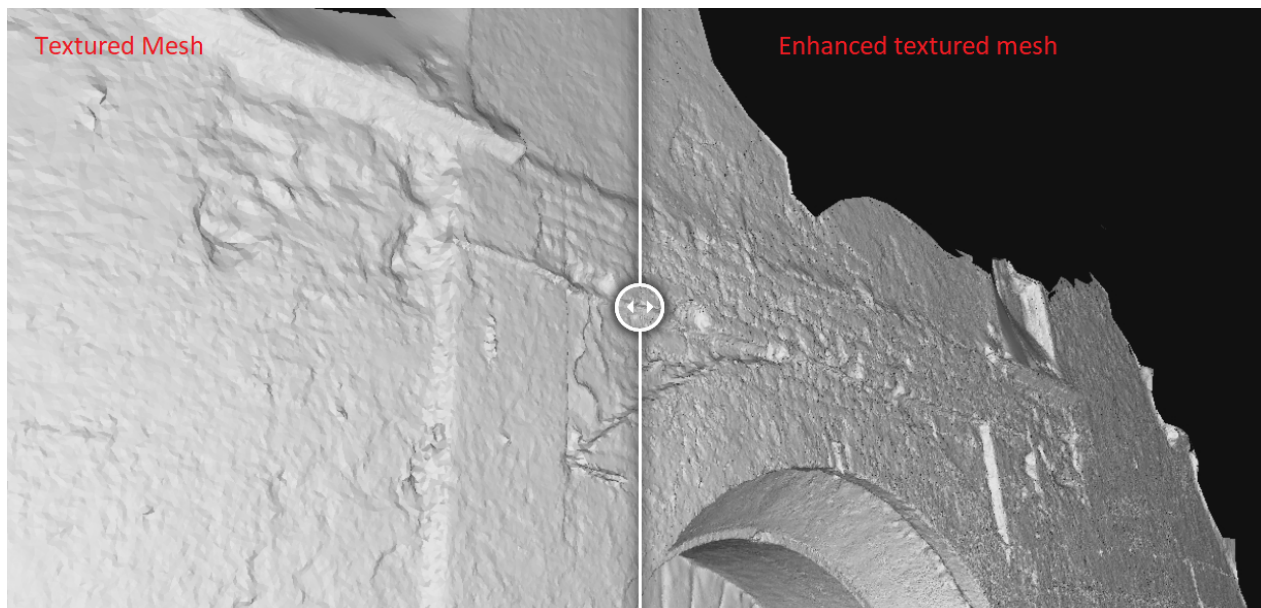
Mesh enhancement and densification

Polycount alone is never a good heuristic to understand the quality of a 3D reconstruction. However, there are some specific workflows where it is necessary to obtain very dense mesh (hundred millions of polygons) in order to generate displacement maps or for similar post-processing techniques. If you are wondering why you may need such a high polygon count, then you most likely do not need this feature and can happily skip this paragraph.

Since 3DF Zephyr 4.0, a new additional step after the textured mesh generation, called “Generate and export enhanced mesh” is available in the workflow > Advanced menu: this is not a photogrammetry process but rather a post processing that can lead to what is commonly known as fake detail (for example, a drawback is that tattoos get heavily carved in human bodies as well as plain text gets carved in papers, etc.).

This process is not aimed at engineering, science and survey users of 3DF Zephyr or any other field where accuracy is important. Although it is more prone to high-frequency noise, this densification process to many millions (or in very niche workflows, even billions) polygon can be useful sometimes.

Below is a simple example from a 35 photos dataset that has been enhanced from 2 million triangles to almost 100 million: on the left, the raw textured mesh and on the right, the enhanced textured mesh. In this case, the enhanced method wasn’t very helpful as all it did was extract more noise.



However in some cases, for example when there is a very low amount of cameras that see the same point, this feature may extract “fake” detail that is actually noticeable (albeit some additional noise). This is a similar example (31 images) enhanced from 370.000 triangles (left) to 4 million triangles (right).



As a final note, the high-frequency gain is not mandatory (as it is controlled by a parameter from 0% to 100%) so eventually, this feature can be used simply to densify a mesh or a textured mesh to an arbitrary polycount if desired (the other densify tool already available in Zephyr works differently and is capped to 50M points)

Gaussian Splatting

Since version 9.0, 3DF Zephyr also supports a Gaussian Splatting workflow that ties directly within the established photogrammetry pipeline.

Gaussian Splats in Zephyr are always generated from an underlying geometric structure that has to already be present in the workspace: any structured point cloud is valid.

- the initial sparse point cloud from the SfM result
- raw dense point clouds (coming from our own photogrammetric MvS pipeline)
- external dense point clouds (e.g. coming from laserscan) that is then structured
- for best result, a dense cloud refined by our photoconsistency meshing algorithm

All of the above are all valid input data to generate a Gaussian Splat.

Keep in mind that Gaussian Splats yield view synthesis visualization, not a new geometric deliverable like a dense cloud or mesh.

Please note that at this time multiple GPUs are not supported for Gaussian Splat generation (so even if you have multiple GPUs you'll be processing only one one). CUDA-enabled cards will perform the best. Running via OpenCL is possible, but with lower performances compared to a CUDA card. CPU processing is strongly not advised as it will be **very** slow.

Gaussian splatting generation is very GPU memory intensive: depending on your datasets size, a modern NVIDIA GPU is recommended with a high amount of VRAM available.

Gaussian splatting can be queued directly in the new Project Wizard, or can be triggered

from the **Workflow > Advanced > Dense Point Cloud Generation** menu or by clicking on the corresponding icon in the toolbar. As usual, the wizard will guide you through the preset selection or you can switch to the advanced mode.

Advanced parameters are explained in detail below:

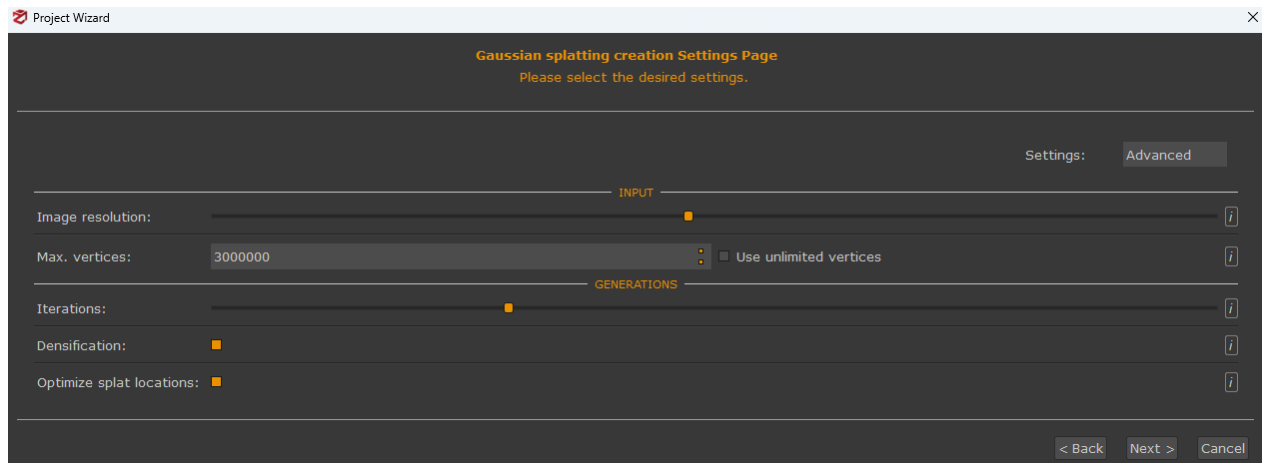


Image Resolution: Controls the percentage of the input images resolution .

Max. Vertices: Maximum number of vertices used from the input point cloud. The input point cloud will be decimated if necessary, and it is possible to check the "use unlimited vertices" if desired. Computational cost scales steeply with this value, and pushing it too high causes computation time to explode.

Iterations: Number of iterations for the optimization procedure.

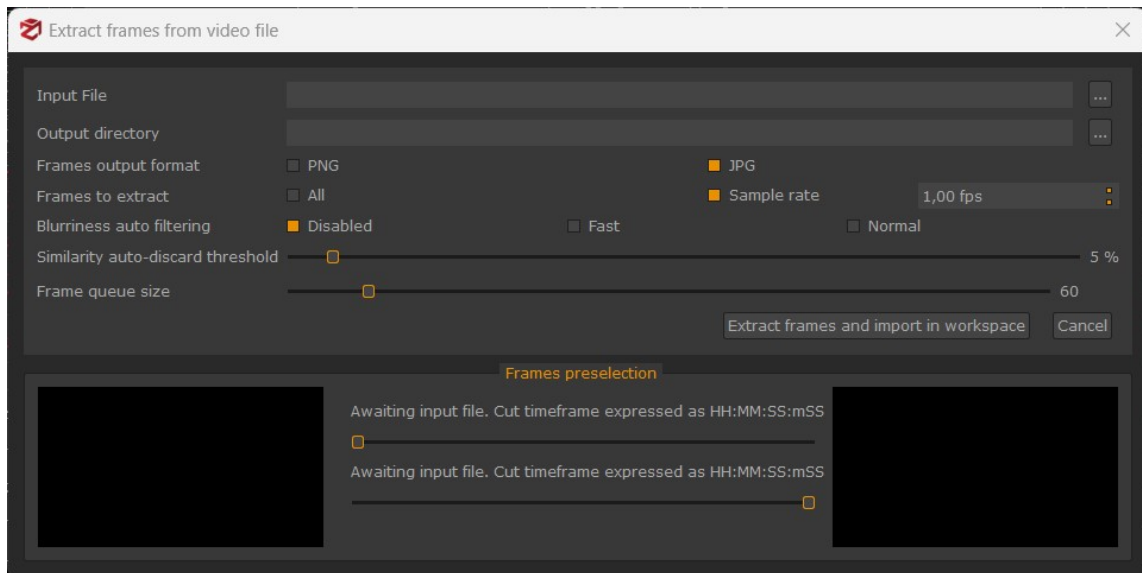
Densification: Set to densify the point cloud inside the optimization procedure. This allows the algorithm to grow the number of splats during optimization using internal heuristics, creating new points where none existed before. This is why simply starting with more input points is not equivalent: the algorithm can generate splats in regions that didn't exist in the original input, something no initial point density can replicate

Optimize splat locations: Set to optimize the splats locations during the optimization procedure. It's suggested to leave this option enabled initially, as the splats move relative to their initial positions. In some cases, however, this may create artifacts; if this occurs, it's recommended to disable this option.

Starting a project from a video

3DF Zephyr can work with images and video data. Although videos usually come with lower resolution, having a continuous video feed ensures overlap, making some datasets much easier to acquire that way. 3DF Zephyr will almost always yield better results with photos, but it's a useful feature to keep in mind.

3DF Zephyr offers an intelligent frames extraction tool: in the new project wizard, simply select **"Import pictures from video"** and the following window will appear:



Zephyr will automatically extract frames from videos (you can set a sampling rate indicated as frames per second or simply extract all the frames of the video, based on the framerate of this one) and treat them as normal images. Missing EXIF data is not a problem for Zephyr, as it is 100% autocalibrated. However, providing a manual device calibration may help, especially when dealing with fisheye lenses such as those of action cameras.

You can also enable a blurriness auto-filtering, which will discard frames that are too blurred and an auto similarity discard filtering, which will automatically discard frames that are too similar to each other.

The "frame queue size" is used to define the amount of memory to be used for frame queuing.

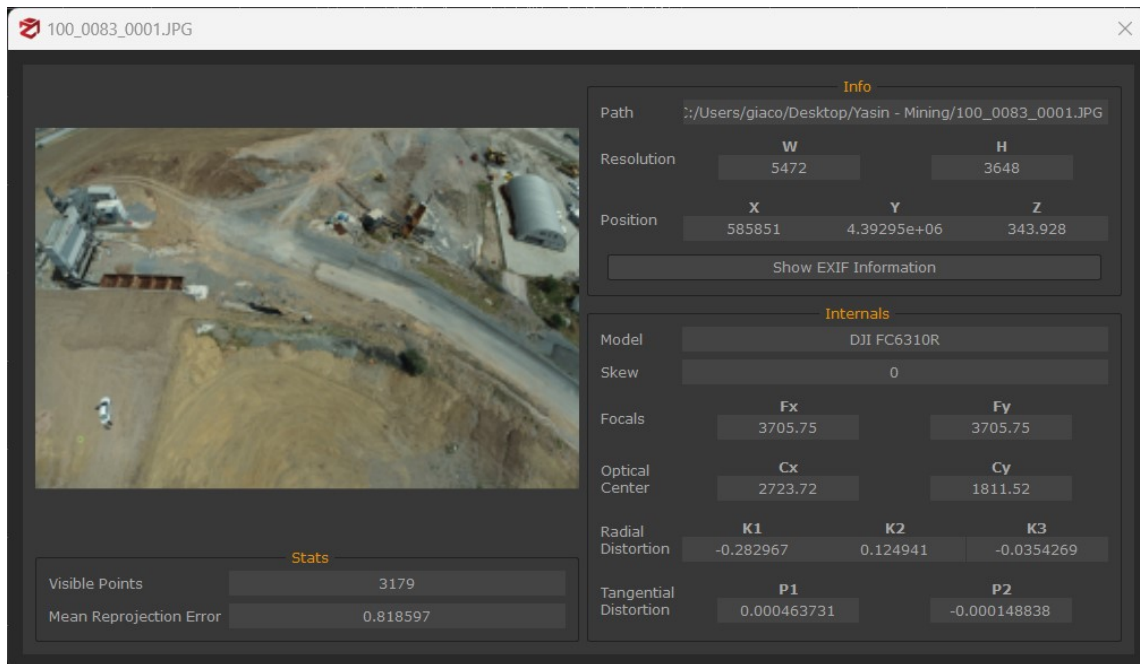
You may use the frame preselection toolset only to select a specific video part.

Project Panel

The Project panel is located in the left sidebar of the main Zephyr interface. This panel gathers the most important parts of the .zep file.

In the **Cameras section** you can find thumbnails of the images imported in Zephyr, both those that were successfully oriented and those that failed the orientation step. By double-clicking with the left mouse button on a thumbnail the properties window will appear with:

- information about the resolution and the position in the Zephyr coordinates system
- internal calibration parameters
- statistics about the keypoints that Zephyr managed to find during the SfM phase and the mean reprojection error;



By right-clicking one or more pictures it is possible to:

- try again to re-orientate the cameras that have not been orientated
- see the picture as an overlay, by changing the point of view
- see the picture thumbnail at a bigger resolution
- rotate and rename the camera thumbnail
- change the camera picture file
- change the mask linked to the camera
- open the properties window
- export external and internal parameters of the cameras;
- export the undistorted images;

The Sparse Point Cloud, Dense Point Cloud, Meshes and Textured Meshes

sections all allow users to access the properties of the reconstructed 3D object (double-click with the left mouse button) which will show:

- statistics about the point cloud/mesh with the total number of points/polygons;
- information about the generation process of the cloud/mesh (settings, running time, Zephyr version, generation date and time);
- detailed data about the reconstruction settings as they can be used in .xml files;
- the log file about the reconstruction phase;

Tip: in the sparse point cloud properties you can find the **Mean Square Error** which shows the quality of the reprojection in the orientation phase. As a rule of thumb, when this value is lower than 1 then the orientation can be considered valid and you can

proceed with further steps. With values higher than 1, you may want to execute the orientation phase again by:

- excluding pictures with a very high reprojection error (you can find that value in the properties of every single camera);
- adding control points on the images, exporting them, and then using them as constraints in the first phase;

By right-clicking the generated **sparse point cloud** it is possible to:

- rename the sparse point cloud;
- reset the bounding box volume;
- export the sparse point cloud;
- view the sparse point cloud properties;
- Modify the order of elements in the project tab;

By right-clicking the generated **dense point cloud** it is possible to:

- rename the dense point cloud, clone it or delete it;
- export the dense point cloud;
- see confidence information (3DF Zephyr Pro and 3DF Zephyr Aerial only);
- view the dense point cloud properties;
- Modify the order of elements in the project tab;

By right-clicking the generated **mesh** it is possible to:

- rename the mesh, clone it or delete it;
- export the mesh;
- compute the mesh volume (this feature is not present in 3DF Zephyr Lite and Free - the value will be saved in the mesh properties);
- view the mesh properties;
- Modify the order of elements in the project tab;

By right-clicking the generated **textured mesh** it is possible to:

- rename the textured mesh, clone it or delete it;
- export the textured mesh;
- view the textured mesh properties;

The full version of 3DF Zephyr also features the **Orthophoto**.

By right-clicking a generated **Orthophoto** it is possible to select the following options:

- **Open in DEM Viewer**: opens the orthophoto in the DEM viewer;
- **Open in Multispectral Viewer**: opens the orthophoto in the Multispectral viewer tool;
- **Edit**: opens the Orthophoto Editor;
- **Relocate**: allows you to locate the orthophoto to a new pathway;
- **Bands**: enables viewing the orthophoto according to the selected band;
- **Export**: opens the orthophoto export tool;
- **Rename, Clone, Delete**;
- **Properties**;

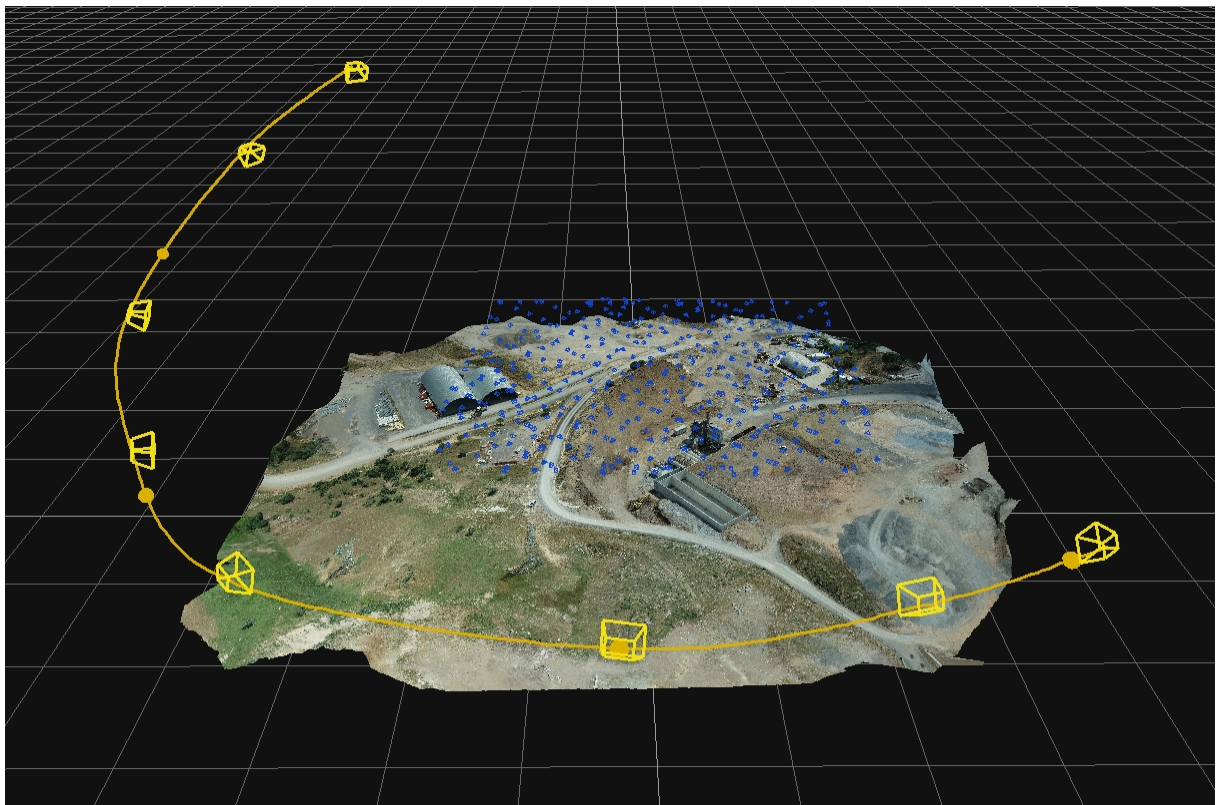
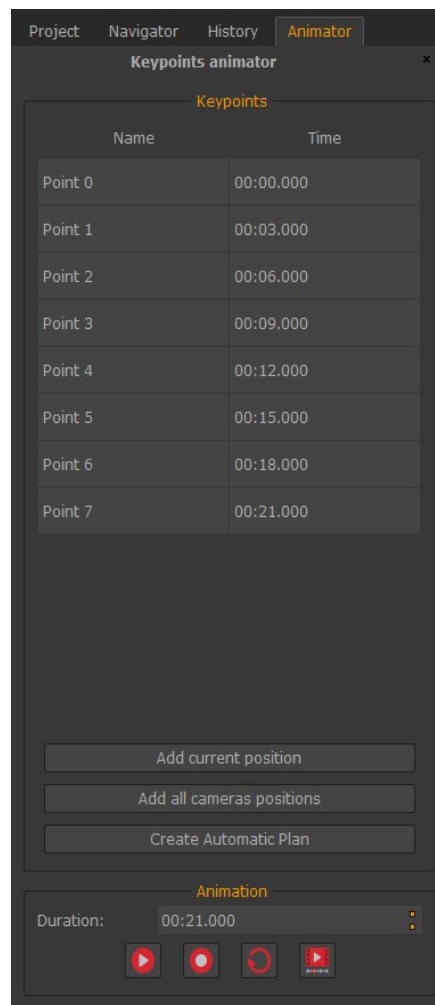
The full version of 3DF Zephyr also features the **Drawing Elements** subsection including sections, contour lines or vector graphics.

By right-clicking a generated **drawing element** it is possible to:

- rename the drawing element;
- change the color of the drawing element;
- export all the drawing elements or those visible/selected;
- access the drawing element properties;

Animator panel

The Animation panel is located in the left sidebar of the main Zephyr interface. This function allows to easily create video animations of your 3D models in Zephyr and export them in different file formats (avi, wmv, mp4) or upload them to YouTube directly.



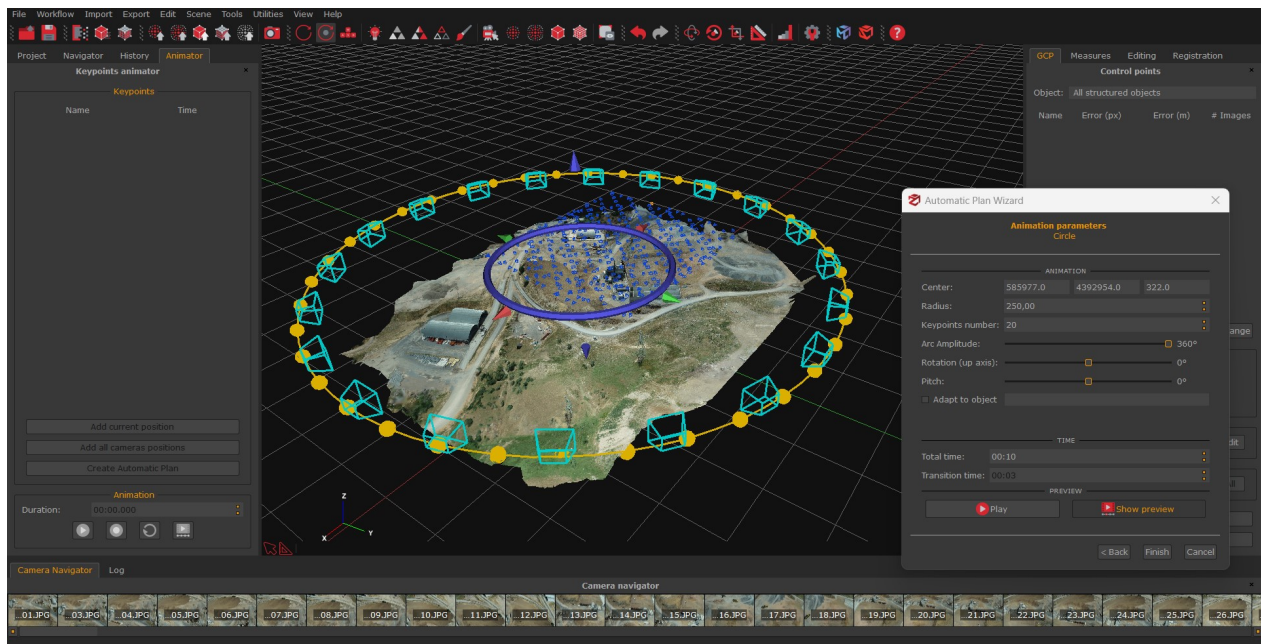
To manually create an animation, simply click the **"Add current position"** button in the Animator panel and move the workspace camera to the desired position(s). By enabling

the **"Show keypoints"** option, every (manual) keypoint position will be identified in the workspace by a yellow frustum.

To automatically create an animation, click the **"Create automatic plan"** button in the Animator panel and choose among four different animation paths (circular, spiral, panning, fly over). Each automatic plan comes with its own settings page and the related keypoint track will be identified by a light blue frustum sequence.

Automatic animation paths:

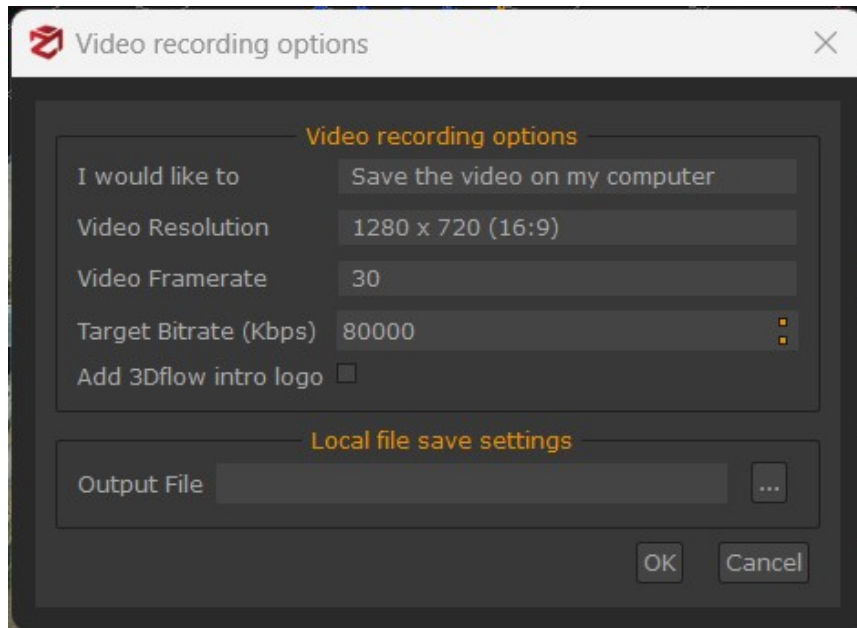
- **Circular:** circular trajectory around the target element. Radius, height, and axis of rotation can be defined;
- **Spiral:** multiple orbits going up around the mesh. Basically extends the previous type, stacking multiple circles with decreasing radius;
- **Panning:** movement parallel to the current view plane: the camera moves perpendicular to the pointed direction;
- **Fly Over:** Smooth cascade motion on top of the mesh coming with adaptable parameters of slope and trajectory length (useful for Aerial datasets involving nadiral pictures);



Once the keypoints have been placed, you can either click the **Play** button to get a preview of the animation or edit the single keypoint by right-clicking its name in the animator panel and selecting the **Edit** option. You can also set the whole animation length using the **Duration** field.

A new window will appear by clicking the **Record** button, allowing you to define those settings such as the video resolution (up to 4K), the framerate, the target bitrate and the

saving options. You can also add the 3Dflow animated logo to your animation's intro enabling the dedicated option.



Notes:

1. Animations are scalable in time: you can choose the total length and the transition time used to blend the new trajectory with the existing keypoints;
2. In order to easily edit the automatic sequences, the workspace 3D gizmo allows to move the keypoints at once by setting the parameters of the wizard;
3. You can delete or edit the keypoints and part of the animation sequence. In case the result is not as desired, you can undo any operation of the editing process;
4. You can join multiple animation sequences into a single one;

In case the trajectory comes with sharp edges along way, you may try to increase the **Total time** parameter to allow a smoother interpolation.

Control Points panel

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Control points allow you to define specific coordinates; that can be used then to calculate the distance between other points and cameras and use them as constraints for the alignment of the point clouds or mesh.

Control points, alignment, and model scaling with known control points (or known distances) can be managed from the panel on the right labeled **GCP (Ground Control Points)**, where the **GCP** created or imported in **3DF Zephyr** will be listed with their information.

GCP
Measures
Editing
Registration

Control points

Object: All structured objects

Name	Error (px)	Error (m)	# Images
GCP 1	0.5019	0.0126	103
GCP 2	0.4624	0.0032	136
GCP 3	0.4476	0.0038	108
GCP 4	0.5228	0.0061	119
GCP 5	0.5244	0.0060	141
GCP 6	0.5423	0.0079	123
GCP 7	0.7803	0.0021	73
GCP 8	0.5151	0.0053	103

☐ Show control points coordinates

CRS: WGS 84 / UTM zone 32N
Change

Options

☒ Show control points
☒ Show control points name
☐ Always show all control points
☒ Add visible cameras to picked points

Add control point

From images
Pick
Pick -> Edit

Import / Export

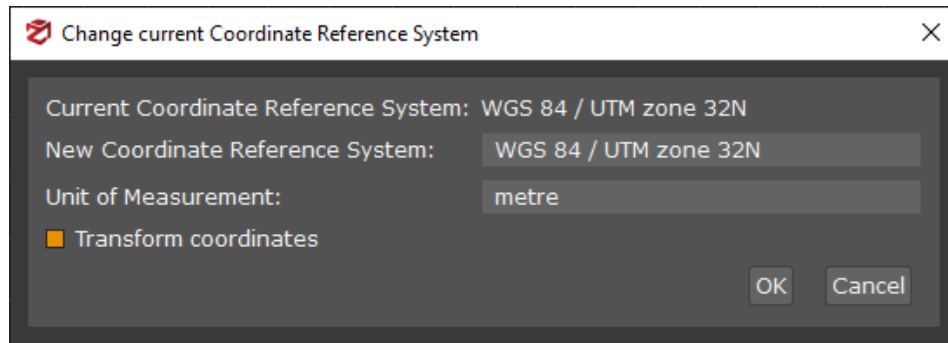
Import 2D
Import 3D
Export All

Align model with 3D Constraints

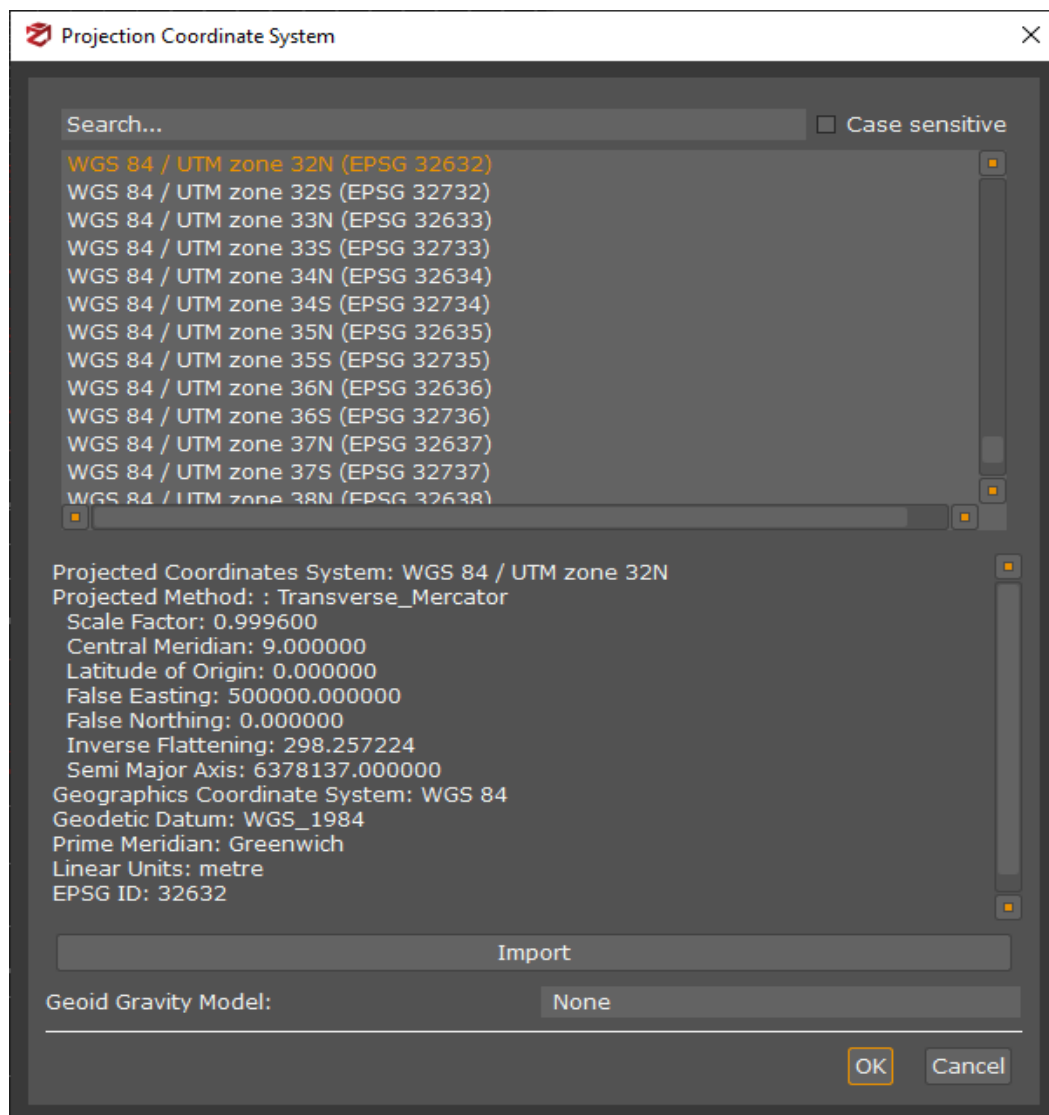
Constraints report

Coordinates Reference System (CRS) section

This section will display the current reference system used. It can be changed by clicking the **"Change"** button and opening the **Change current coordinate reference system** window.



Clicking on the **"Select Projection CS"** option in the **New Coordinates Reference System** drop-down menu, will open the **Projection Coordinates System** window:



Select the new correct **coordinate reference system** from the 3DF Zephyr database, or import a new one from an external source by clicking the **"Import"** button, and click **"OK"**.

Optionally, a **Geoid Gravity Model** can be loaded as well, in relation to the **Coordinate Reference System**. This feature can be helpful if you have taken **GPS coordinates** in a different **reference system**, which will cause a wide metric error compared to the GPS coordinates obtained from the pictures.

To complete the reference system's change, be sure that the **"Transform coordinates"** flag is checked, and click **"OK"** in the previous window.

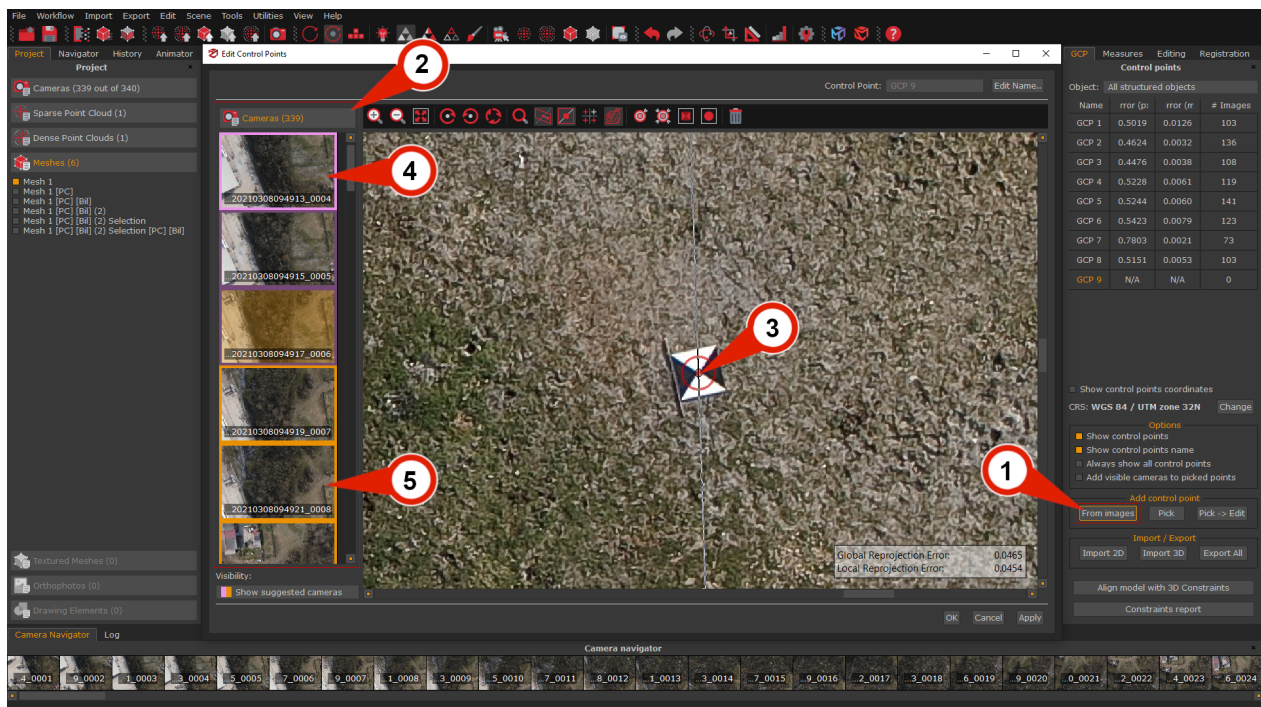
Add control point section

These functions will allow the placement and movement of the GCPs in the project.

- **"From images" Function:** Allow to add control points by picking on photos.

A much more accurate way to add **control points** is to pick them directly from the photos. You need to pick the same coordinate on at least two pictures in order to triangulate and make Zephyr calculate the control points.

If necessary, it's possible to clear all previously created control points by right-clicking on the point list and left-clicking **"Delete All"**, and **"Yes"** to confirm. Each control point can also be removed individually by right-clicking on the appropriate row and clicking **"Delete"**.



From the **GCP** panel, in the **Add control point** section, click the **"From images" (1)** button: the **Edit Control Points** window will appear.

In the **Camera list (2)**, **left-click** a picture to view it in the **Control Point Picker Selector**.

Left-click where you want the control point, and an **Red dot (3)** will appear. A violet border will highlight the **first selected image (4)**, but the **"OK"** button won't be available yet: remember, at least two images to define a control point in the 3D space are needed.

Click on another image in the **camera list (2)**: this time the *epipolar line* will also appear (highlighted by the color inversion in the picture), which will help to position the second 2D coordinate by left-clicking, the **available images will be highlighted by a yellow border (5)**. It's possible to add as many coordinates as wanted (usually, the more coordinates the better the accuracy) and click **"OK"** to complete the control point selection.

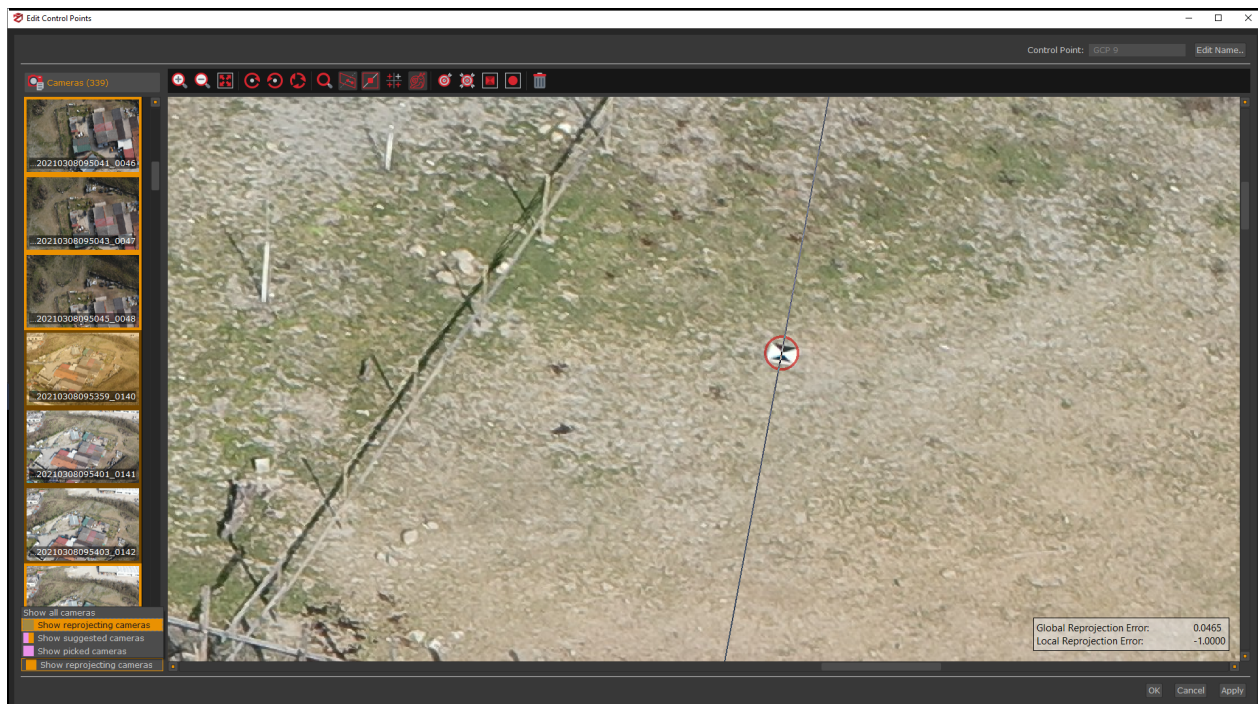
As the positions of the selected 2D points are changed, you can see the **Global Reprojection Error** and **Local Reprojection Error** of the control point in real time.

The **Advanced Tools** can provide valuable help with **control point** placement in the editing window:

Advanced Tools	
	Fit in view: resize the image to fit in the view.
	Rotate 90 degrees clockwise, counter-clockwise, reset rotation: rotate the image and reset the initial position.
	Show magnifier: show/hide the magnifier on the cursor while placing control points on images.
	Show reprojection error: show/hide local and global reprojection errors of the current control point.
	Show epipolar line: show/hide the epipolar line.
	Show other points: show/hide previously placed control points.
	Automatic matching on current image: automatically find and place a control point on the current image.
	Automatic matching on all images: automatically find and place a control point on all the pictures
	Detect marker: It automatically detects the center of a rectangular marker placed in the scene. By clicking the "Detect marker" icon and drawing a rectangle upon

	Fit in view: resize the image to fit in the view.
	the center of the marker you want to be found, 3DF Zephyr will automatically place the control point at the center. Note: Using the tool with a check-board style marker will improve the automatic detection.
	Detect sphere: it allows to detect the center of the spheres placed in the scene. By clicking on the "Detect sphere" icon and drawing a rectangle over the sphere you want to be found in the image, 3DF Zephyr will automatically place the control point at the center. Note: This feature is expressly designed for the forensics industry, i.e., to support the analysis of the line of fire in crime scenes where a laser scanner scans the spheres on the trajectory rod.
	Clear point: remove control points placed on the image.

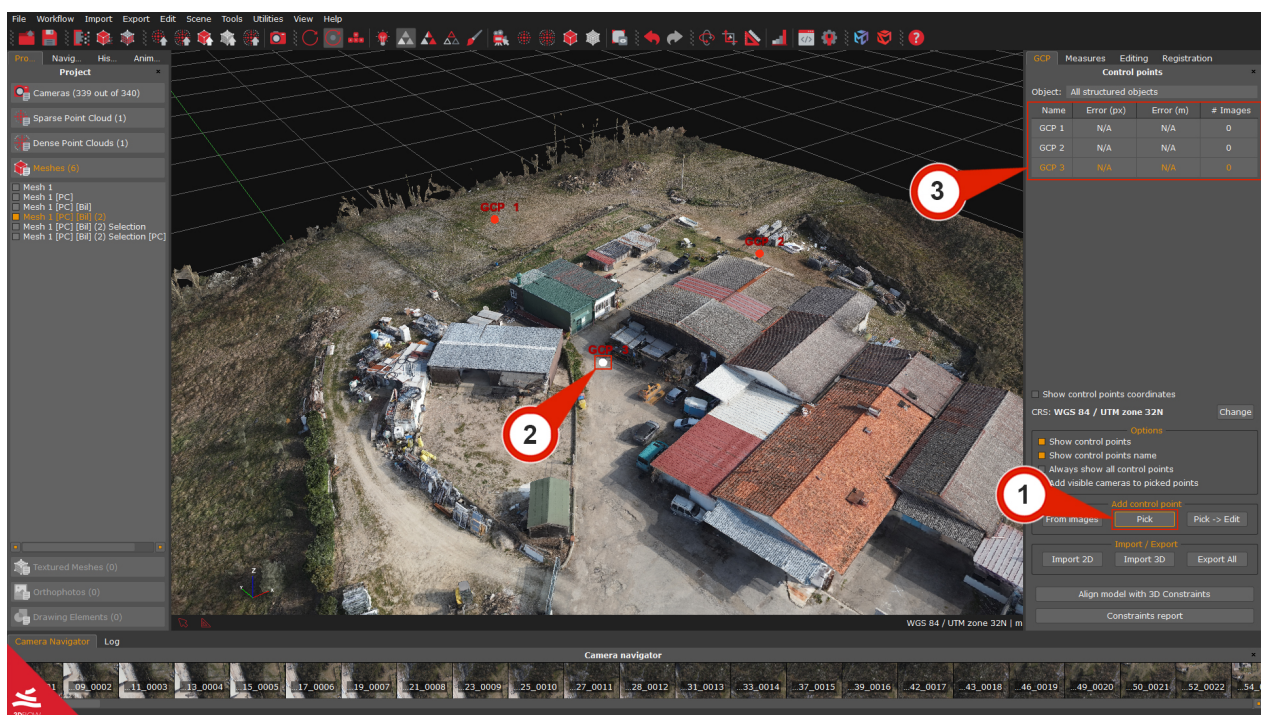
You can change the camera "**Visibility**" by selecting the "**Show reprojection cameras**" option from the drop-down menu in the bottom left corner of the editing window, that's filter will permit to place the control points on "**far cameras**" (dull yellow frames) as well. In some cases, this method could improve the accuracy, especially when a few cameras come with and a high reprojection error. The "**Show picked cameras**" option will shows cameras (violet frames) where the control point is already placed.



- **The "Pick" Function:** allows to add control points by direct picking in the rendering window and it's the easiest way (albeit the least accurate) to insert a new control point from the 3D reconstruction directly.

From the **"GCP"** panel go to the **"Add control point"** section and click the **"Pick" (1)** button. The mouse cursor will be displayed as crosshair icon (+): move it on the scene and **left-click (2)** the desired control point position. A new control point will be added to the **control points list (3)** and will be automatically shown in the scene.

Note: This control point selection mode cannot be done on a textured mesh.



- **"Pick → Edit" function**

From the same section **Add control point**, it is also possible to find the **"Pick → Edit"** button: this function allows the user to select a control point by directly picking it on the scene (exactly like the **"Pick"** function) and then modify the position of the control point by editing its position with the **"add control point from images"** interface, with the control point already in place in all the possible cameras.

Import / Export section

In this panel section will be possible to import control points from *atext* or *csv* files.

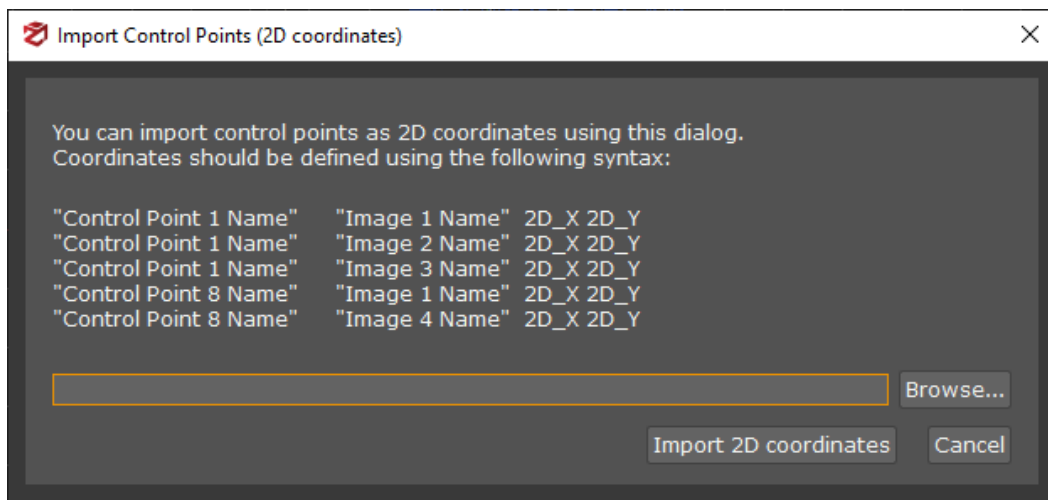
- **The "Import 2D" function**

Importing control points from text files allows the user to add control points exported from 3DF Zephyr, or other applications automatically: to do that, click on the **"import 2D"** button, pick the desired text file and then click **"Open"**. A window will appear to confirm that the import phase has been completed successfully: click **"OK"**.

Example: for each imported control point, it is necessary to define coordinates for at least two images. For example, to import a control point named *"Point1"* seen by the camera *"PictureA.jpg"* at the (x,y) coordinates 100,600 and from a second camera *"PictureB.jpg"* with coordinates (x,y) 200,660, the file has to be formatted in the following way:

Point1 PictureA.JPG 100 600

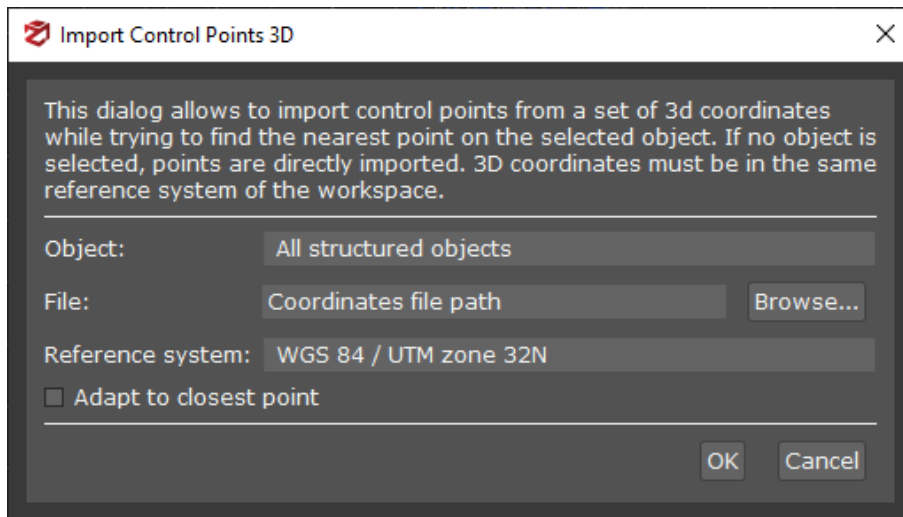
Point1 PictureB.JPG 200 660



- **The "Import 3D" function**

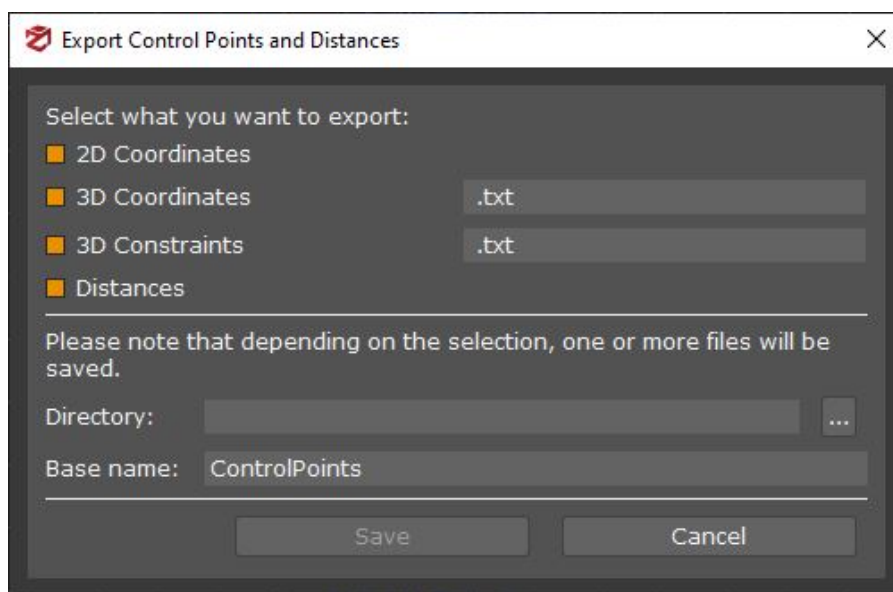
This tool allows the user to define **control points** by using **3D coordinates** directly, without detecting any control points in images. In order to exploit this tool the **3D coordinates** must have the **same reference system as the workspace** where the 3D model is being processed. Afterwards **control points** can be defined for each **2D coordinate** as needed.

It is necessary **to specify a reference object** if users want to get the **metric error** between their model/cloud and the 3D coordinates.



- **The "Export All" function**

Next to the **"Import 3D"** button it is possible to access the control point (and distances, defined in the **"Measures"** tab) export function.



From this window it is possible to export:

- **2D coordinates**

It creates a ***ControlPoints2D.txt** file - it defines the control points as **2D images coordinates**, as:

"Control_Point_1"	"IMG_3319.jpg"	4.33473658e+03
2.24061730e+03		
"Control_Point_1"	"IMG_3320.jpg"	3.30352087e+03
2.42468881e+03		
"Control_Point_2"	"IMG_3319.jpg"	3.01642756e+03
3.16114630e+03		
"Control_Point_2"	"IMG_3320.jpg"	1.68567672e+03

2.14786953e+03

- **3D Coordinates and 3D Constraints**

It creates a *ControlPoints3D.txt .scr\ .dx\ .ncn files - it defines the control points as 3D coordinates, as:

```
"Control_Point_1"      8.18880729e-01   -5.14516149e-01
4.54143586e-01
"Control_Point_2"      -5.64690812e-01   -5.65085273e-01
1.09244112e+00
```

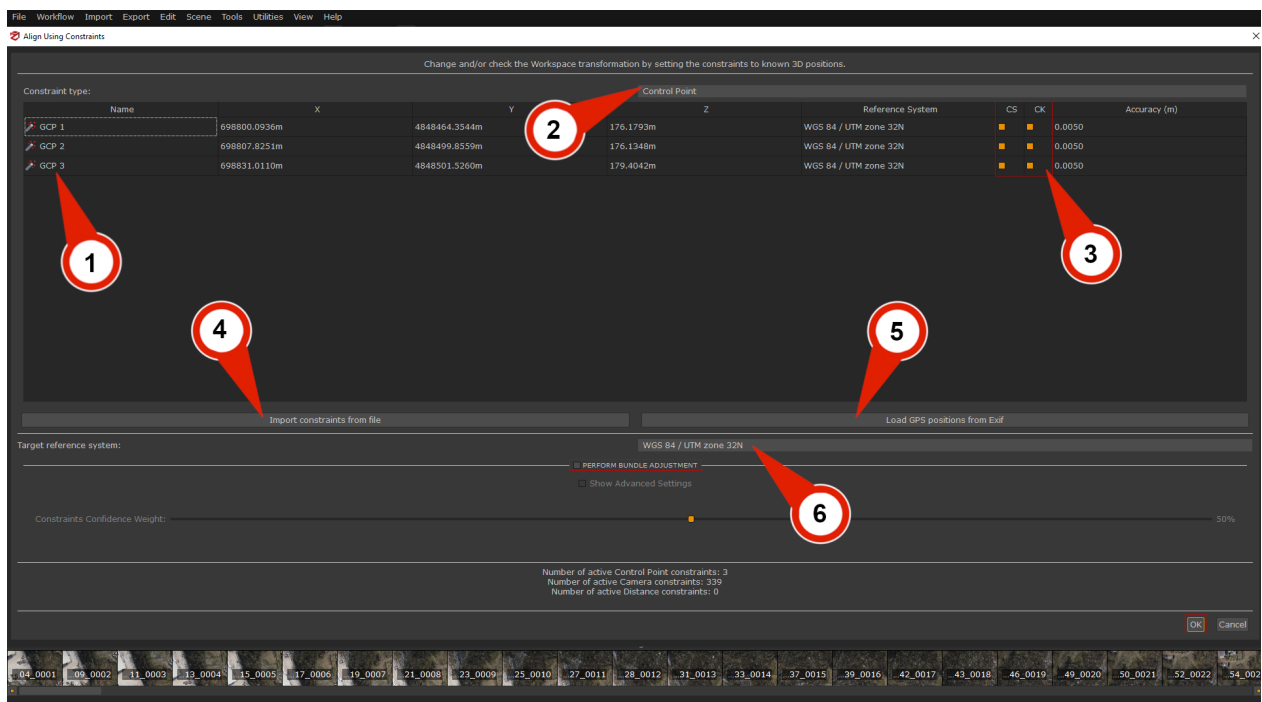
- **Distances**

It creates *ControlPoints_Dist.txt file - it defines the distances as seen in the measurements tab, as:

```
"Control_Point_2"      "Control_Point_1"   2.33824531e+01
```

- **The "Align model with 3D Constraints" tool**

This feature is similar to the **Import Constraints** page when creating a new project in 3DF Zephyr. It allows you to scale and georeference your project after creating a sparse point cloud using cameras, constraints, or control distances.



After defining at least **three constraints (1)** in the **GCP Panel**, you can scale the model by using them individually or together with image positions or control distances.

Changing the **Constraint type filter (2)** to:

- **Camera** option will allow viewing each image's GPS coordinates.
- **Control point** option will allow viewing the imported constraints from an external source.
- **Control distances** option will allow viewing the distances created in the Measures panel.

Pressing "CTRL+A" will allow selecting all the tab rows, and "Right-click" with the cursor will allow you to Change *Reference system* and *Accuracy* for each camera or control point.

Constraints and Check Points column (3)

Each control point can be set as Checkpoint (to measure the residuals), Constraint (used in the bundle adjustment), or both by using the check-boxes on the left of each point. It's always a good idea to include some checkpoints that are not set as constraints.

- **Constraints (CS)** are those points you are most confident of in terms of accuracy level, and 3DF Zephyr relies on them to drive the scaling process.
- **Checkpoints (CK)** are references that the software only considers while scaling to monitor the error value.

Example:

*Let's think about an aerial survey where you have both coordinates taken using the drone's GPS system and coordinates taken on the ground with a total station for instance. Once you have placed your points in 3DF Zephyr, you can choose which points must be the **constraints**, namely the points you are confident (of their accuracy) the most, and which points will be taken into account as simple references to keep the error value monitored.*

Import constraints from a file button (4):

this function allows directly set constraints from a text or .csv file via the "Import constraints from file" button; the imported coordinates and the GCPs you have added to the project must have the same name/label.

Coordinates should be defined using the following syntax:

"Control_Point_1"	8.18880729e-01	-5.14516149e-01	4.54143586e-01
"Control_Point_2"	-5.64690812e-01	-5.65085273e-01	1.09244112e+00

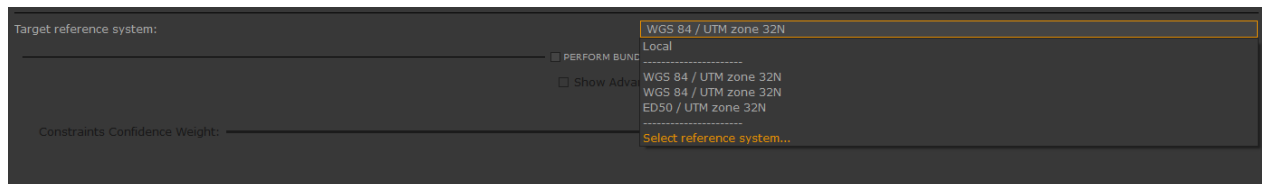
.

Load GPS position from Exif button (5):

This button import camera positions by loading them from Exif information and using them as constraints.

A common scenario is when loading information from images taken by drones or UAV systems that record the GPS coordinates of the shots in Exif data.

It's possible to change the **Target reference system (6)**, in a similar way seen in the **GCP tab**.

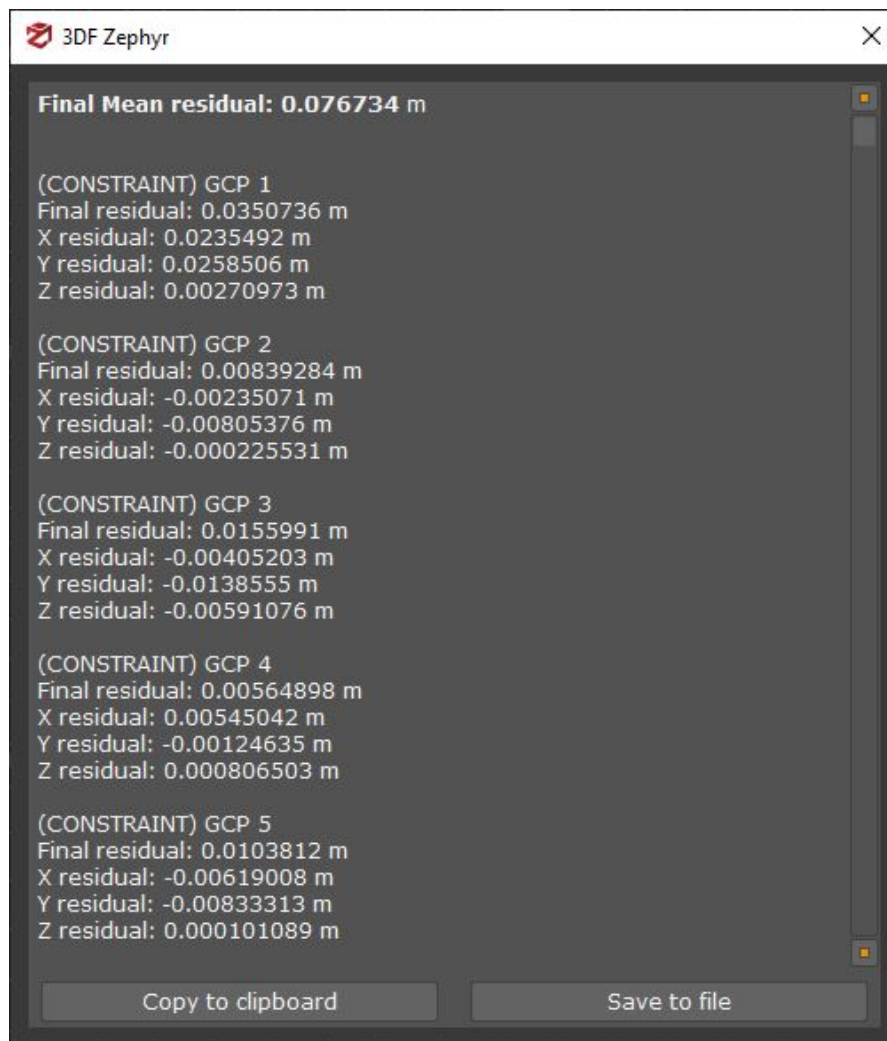


Clicking on "**Select reference system**" will open the "**Projection Coordinate System**" window:

You can select the suitable coordinate system from the 3DF Zephyr database, or import a new one from an external source by clicking the "**Import**" button.

Once the correct reference system has been set, you may also perform the Bundle Adjustment by checking the "**Perform bundle adjustment**" option. This can be done by using a slider that will assign a confidence weight in the defined constraints and an advanced mode option.

Click the "**OK**" button to start the scaling process, and an **Error report** will automatically appear when it is finished. If you need to find and save the report, you can go to the menu: **Tools > Control Points > Show Alignment Info**.



Constraints Report

This button will open a summary window to display all constraints with their positions, errors and accuracy values.

Tabella vincoli									
Tipo di vincolo:					Punto di controllo				
Nome	X	Y	Z	Errore (X)	Errore (Y)	Errore (Z)	Errore	Errore di Ripr.	Accuratezza (m)
GCP 3	698831.0110m	4848501.5260m	179.4042m	-0.0044m	0.0024m	-0.0007m	0.0051m	1.2731px	0.0050
GCP 2	698807.8251m	4848499.8559m	176.1348m	0.0067m	-0.0001m	0.0010m	0.0068m	1.1528px	0.0050
GCP 1	698800.0936m	4848464.3544m	176.1793m	-0.0023m	-0.0023m	-0.0003m	0.0033m	1.2449px	0.0050

Measures panel

Quick measurements

You can quickly pick and measure directly in 3D space using the "quick measurement tool".

This tool allows for measuring both the horizontal and slope distance, elevation and inclination of a segment.

The following functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

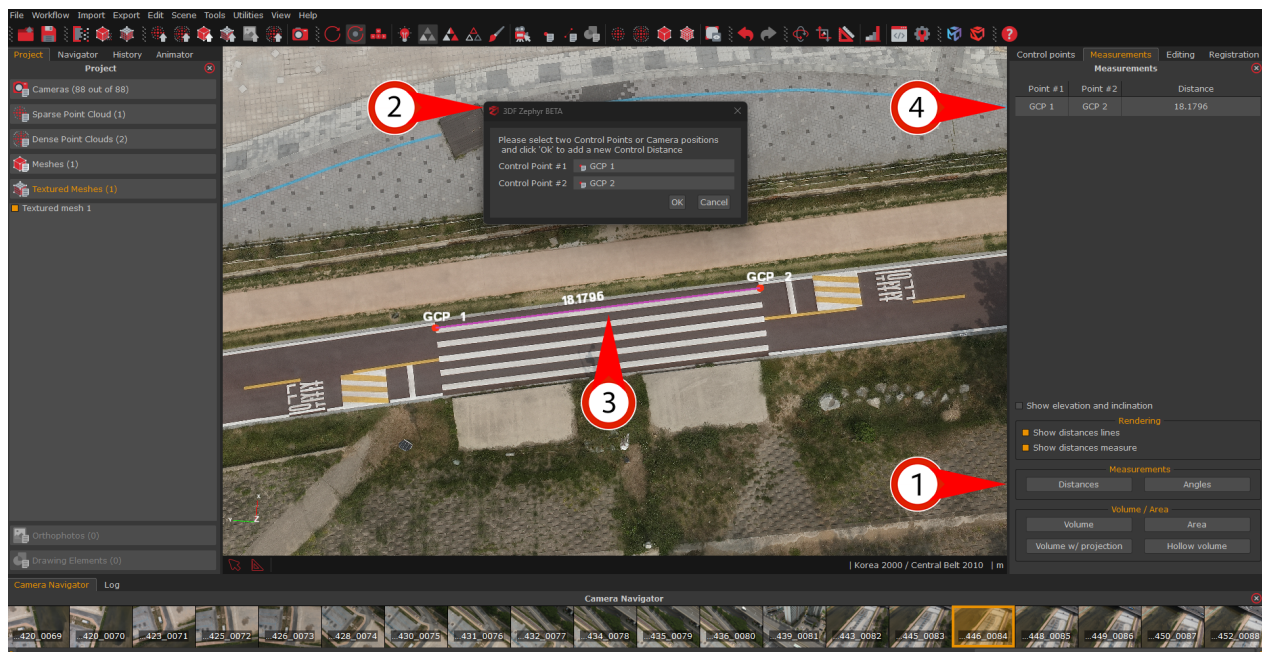
Control Points & Distances

Control distances can be defined as the distance between two control points, the distance between a control point and a camera, or the distance between two cameras. With 3DF Zephyr you can easily define control distances and even scale the world with control distances.

The "Add control distance" function

To add a new control distance, click on the "Distance" Button (1). The "control point selection window" (2) will pop up. From this window, pick the two control points needed from the Control Point #1 selection menu and the Control Point #2 selection menu. Once you click "OK", the distance will be drawn as a green line (3) and rendered onto the screen (in this case, 18.1796).

The control distance (and the relative used control points) will also appear as a list on the right side of the panel (4).



Scale world with control distances function

It is possible to scale the model using control distances: to do so, simply click on the "Scale model with control distances" button: in the window that will pop up, simply set the wanted distances as constraints. When completed, the residue error will be shown.

Import control distances from txt file

It is possible to import control distances directly from text file: every line of the text file must be formatted as

"Control Point #2" "Control Point" 2.18197

Measure mesh volume

It is possible to compute the mesh volume using the dedicated button. If the mesh is not completely closed, all holes will be automatically filled and later shown with a red color - it is possible to save that mesh as a separate workspace object.

You may also compute the volume of a dense point cloud rather than a mesh: by selecting the desired dense point cloud as target for the computation, please note that a mesh will be internally computed anyways.

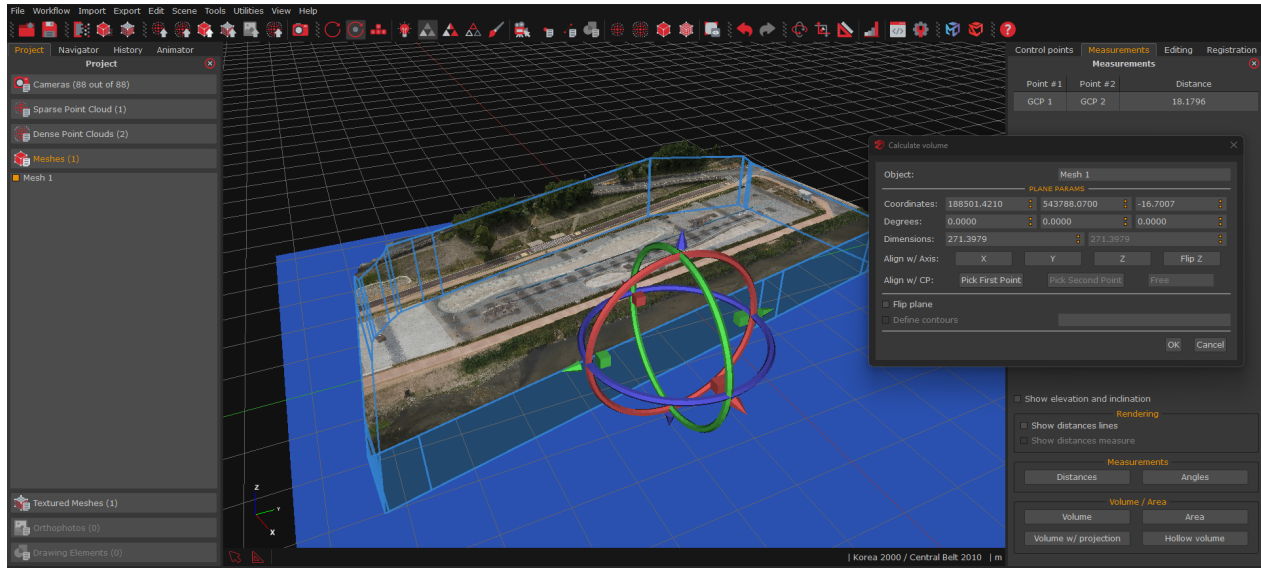
Once you have selected the reference mesh from the menu, simply click the "Compute" button.

Measure volume after projection

This tool allows calculation of the volume of a mesh or a point cloud by considering the points distance and the position of a plane chosen by the user. Points under the plane are not considered, while those above are projected on the plane's surface.

This tool streamlines volume calculation of elements such as embankments and

excavations and it is handy for applications like 3D printing for instance. The calculated mesh can be exported as a standard surface in the main formats provided in 3DF Zephyr.



Volume after projection on a urban area: here the direction of the plane's normal is up

Hollow objects volume

This tool allows calculation of the volume of a cloud/mesh when the photographic survey has been carried out from the inside of the acquired object itself, as in the case of a room or a tank. Unlike the standard volume computation, this algorithm entails that the normals of the objects point towards the inside. This also means that any other objects cluttering the inner space will not be considered during this specific computation.

Volume between two sections

You can compute the volume between two sections: simply select the two reference contour lines from the drawing elements panel, right click, and select "compute selection volume"

Measure mesh area

Similar to the "measure mesh" function, clicking this button will compute the area of a given mesh. Just select the mesh and click the "Compute" button.

Measure Angles

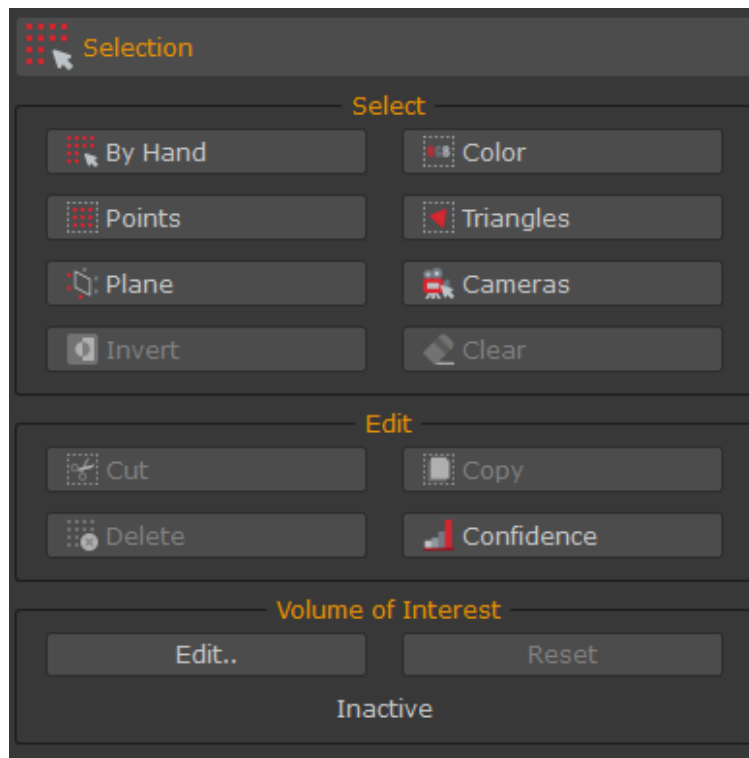
When at least three control points have been selected, you can compute the angle between control points. The interface of the window that will appear will allow you to set control points as A,B and C and then compute the angles between the vectors BA and BC. A checkbox will allow you to change the output to radians or degrees.

Editing panel

The editing panel allows to access the Selection/Editing tools, Filtering tools and the

drawing tools (this last function is not available in 3DF Zephyr Lite and 3DF Zephyr Free).

- **Selection/editing tools**



These functions allow to select elements from the workspaces so that they can be edited/managed directly in 3DF Zephyr:

- the **manual selection** allows to select points (for sparse clouds and dense clouds) or triangles (for mesh and textured mesh) through different selection modes (rectangle, polygon, ellipse, lasso, box). By selecting the desired mode and the desired elements in the 3D space, it will be possible to combine selected elements using the appropriate action (add, remove and eventually by using pause to freely move in the workspace). Those elements will be highlighted in red - once selected, it will be possible to manage them using the appropriate commands in the "Edit" section.

- the **selection by color** will be applied similarly to both points and triangles: given a certain color (that can be added manually or by picking it directly on the target object from the 3D workspace) all points within a certain threshold will be selected.

- the **selection by plane** allows to select all elements above (or below) a certain user defined plane.

- the **selection by points** allow to select all those points (from sparse or dense clouds) that are within the search parameters. The search parameters vary depending on the selected algorithm between:

- Visible cameras;
- Reprojection error;

- **X84 Statistic:** this algorithm selects those points whose density doesn't meet the X84 statistic criteria. It calculates which are the nearest points or not useful to remove those too far from the correct solution, e.g. the points describing the sky;
- **Main plane fitting:** this algorithm selects those points which lie well on a plane. It fits a plane using the desired point cloud (decimated due to pc performance). It selects those points whose distance from this fitted plane is under a certain threshold;
- **Cloth simulation:** it selects those points that according to this algorithm "Cloth Simulation Filter" (see <http://ramm.bnu.edu.cn/projects/CSF>) appear to be terrain.

- the **selection by triangle**, similarly to the previous point, allows to select all those triangle within the search parameters depending on the selected algorithm between: longest edge, area, connected components (this last one is very useful to quickly remove all the "floating" noise from the reconstruction).

- the **camera selection** allows to select cameras directly in 3D space.

Once elements have been selected, it is possible to handle them using the editing tools:

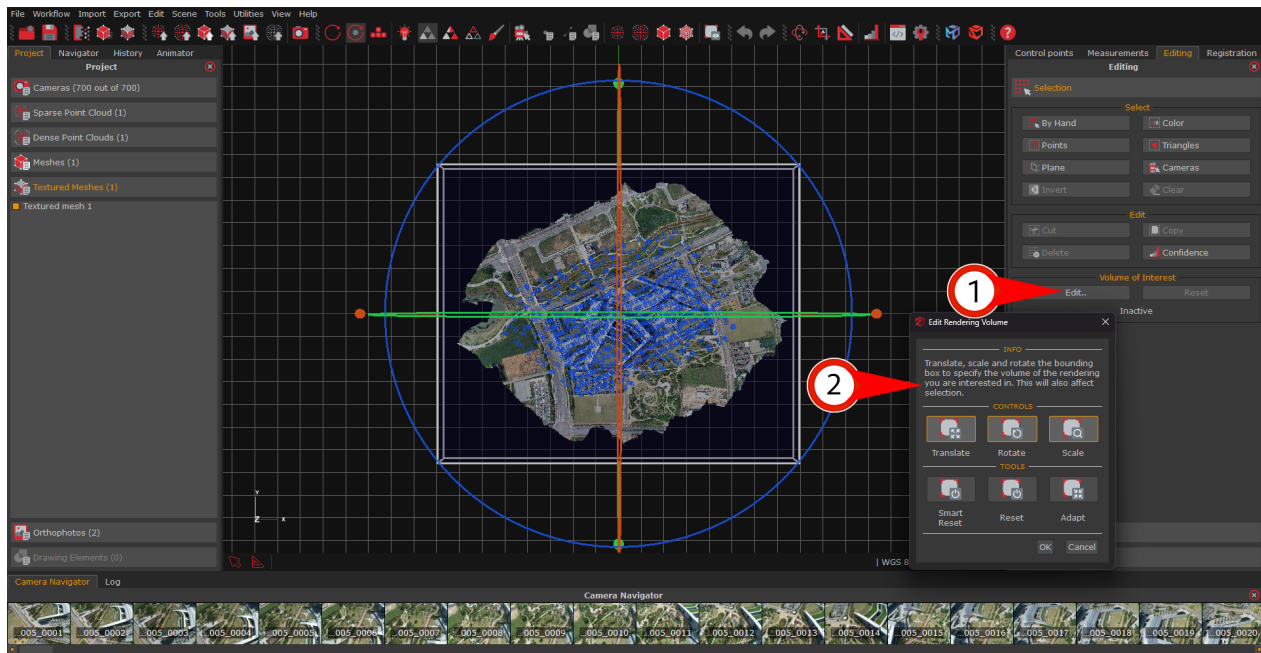
- **delete:** deletes the select elements from the workspace
- **invert:** inverts the selection from the workspace
- **cut:** create a new element by removing the selected elements from the current element
- **copy:** create a new element by copying the elements from the current element.
- **selection:** allows to apply a filter only on the selected elements (smoothing, bilateral filtering, retopology).
- **confidence:** allows to select (and eventually, remove) all the points below a certain confidence threshold.

• Volume of Interest

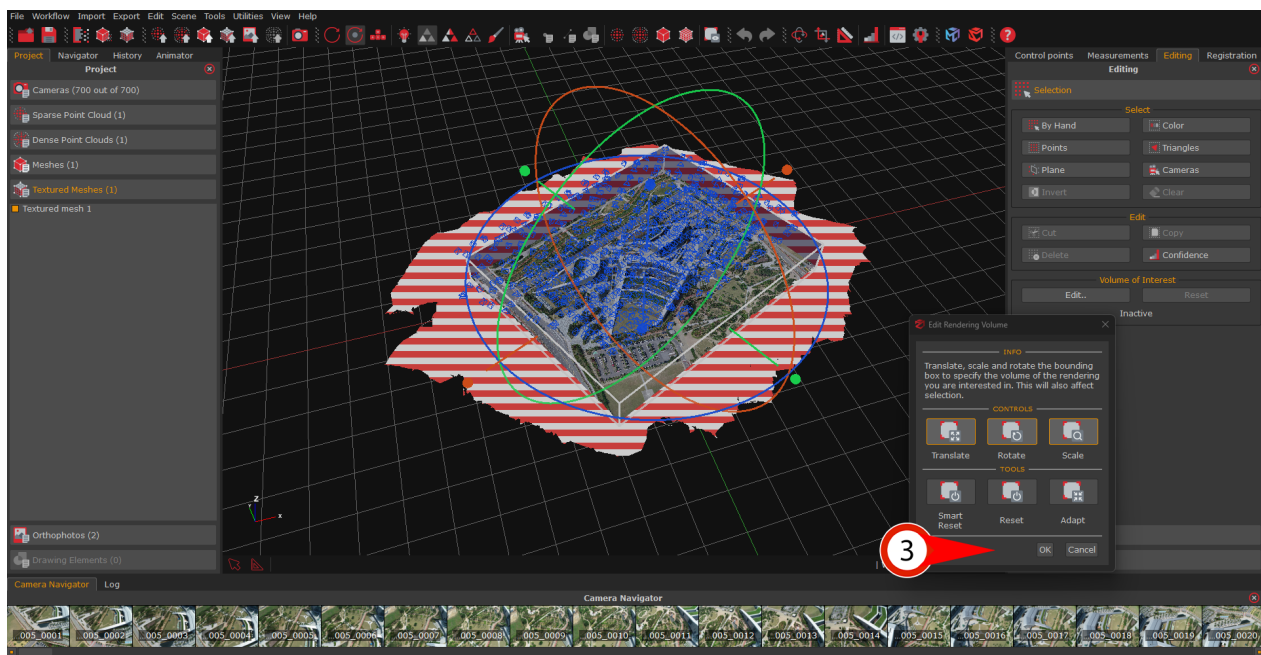
As of version 6.0, the Volume of Interest (VoI) is a new experimental feature designed to aid users during the visualization and editing of huge datasets.

The user specifies a three-dimensional clipping region by visually editing it (this tool works very similar to the bounding box editing tool).

The Volume of Interest tool is located in the Editing panel and you can click the **Edit** button **(1)** to enable it and open the "Edit rendering volume" window **(2)**.

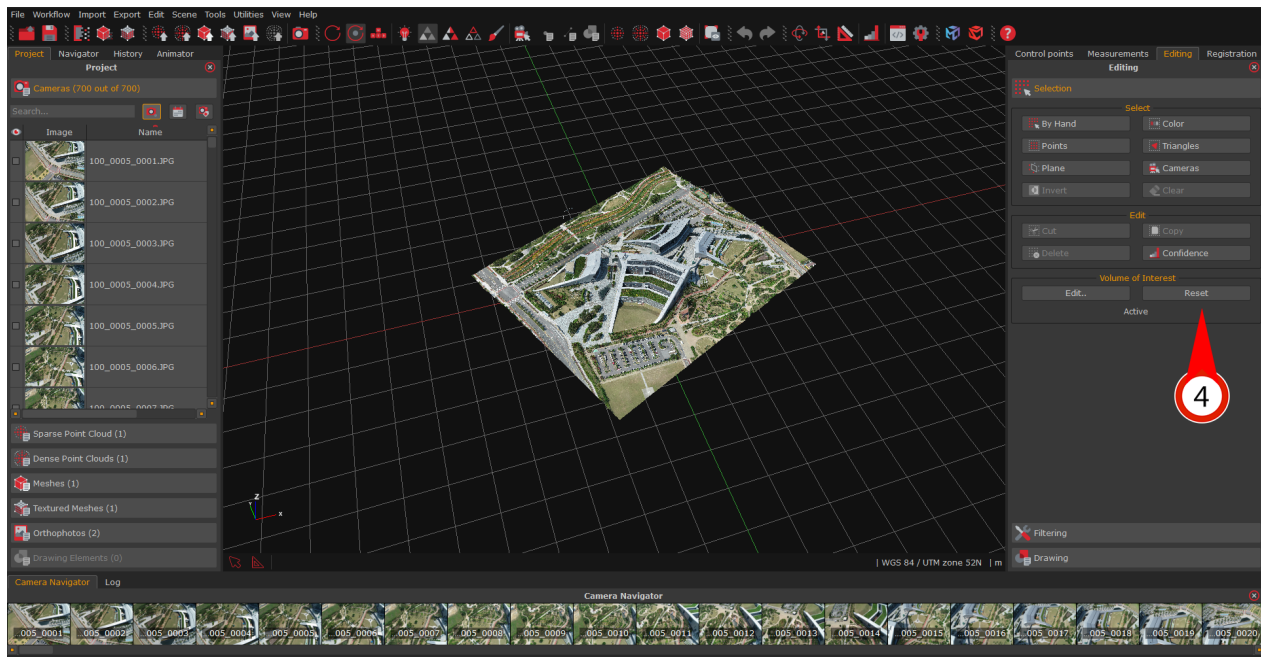


The clipped area will be highlighted by a pink and black waving layer. Once you are done with editing the volume, simply click the **OK** button **(3)**.

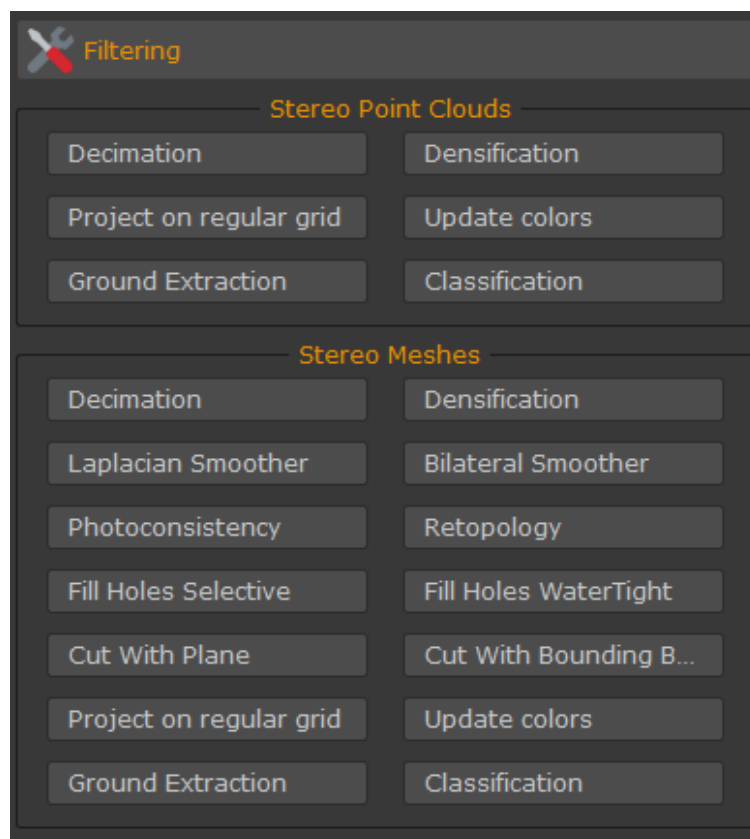


The point cloud/mesh will be trimmed in terms of rendering only, and the user will be free to leverage other tools while the Vol is running (i.e., sections, contour lines or the orthophoto generation can be performed).

Simply click the **Reset** button **(4)** to let Zephyr render the original 3D model.

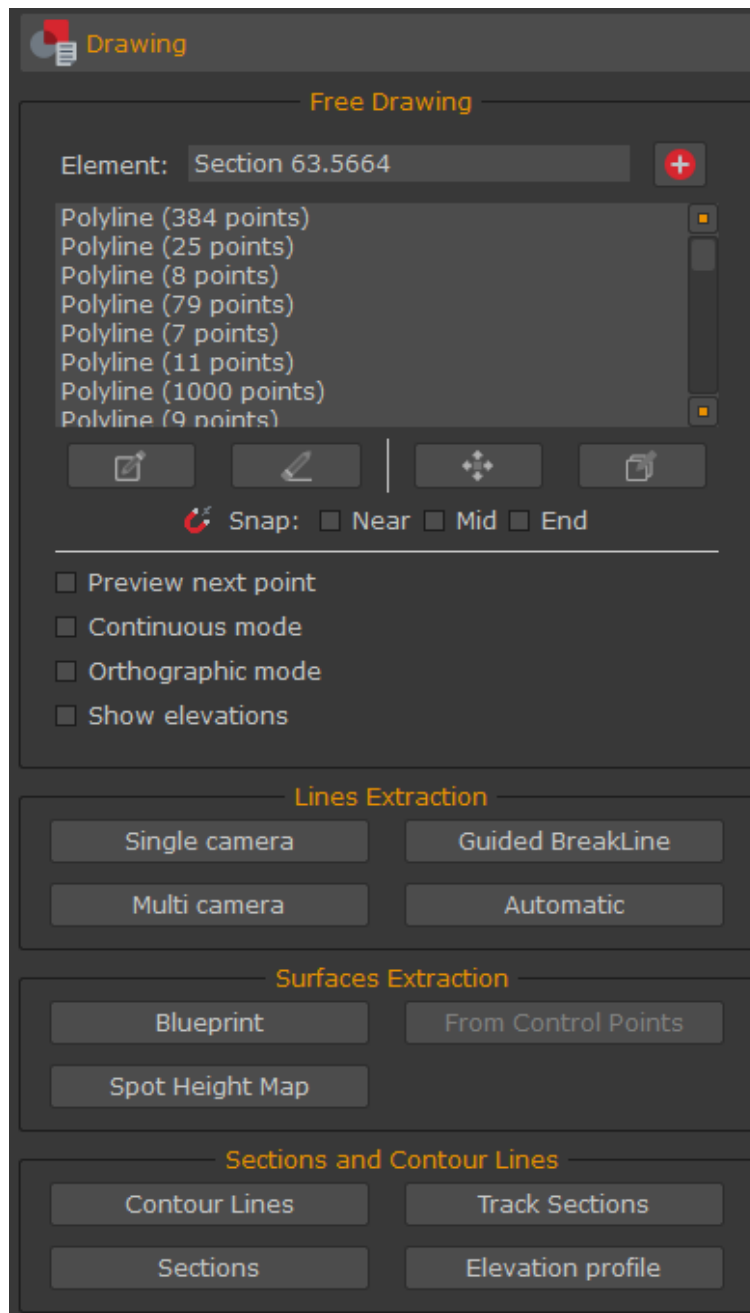


- Filtering tools



These filters affecting both point clouds and meshes are also available in the **Tools** menu. You can learn more about these function in the point [cloud filters chapter](#) and in the [mesh filters chapter](#).

- Drawing elements tools



This panel includes the four CAD-dedicated tools available in 3DF Zephyr: the free drawing, the lines and surfaces extraction, and the sections, contour lines and elevation profile generation.

To create a new drawing element, simply click the "+" button - the new element will be automatically added to the **"Drawing Elements"** section in the Project tab.

Once an element has been created, the drop-down menu to select the current drawing element will be enabled (in this case, it will be shown the only drawing element available, the "Drawing Element" right under the **"Create new element"** button). This allows you to select and edit previously created drawing elements.

When the drawing element has been selected, it is possible to navigate the scene to the

desired position (eventually by making use of the "Orthographic mode" checkbox).

When ready, it is possible to select the middle points that will define the shape of the drawn element, by picking them directly on the mesh using the "Pick" button. You may also use the "continuous mode" checkbox that won't ask for many clicks (each for every middle point) but instead it will draw the line as long as the left click is kept pressed and the cursor is on top of the mesh.

Press "ESC" to exit the drawing mode.

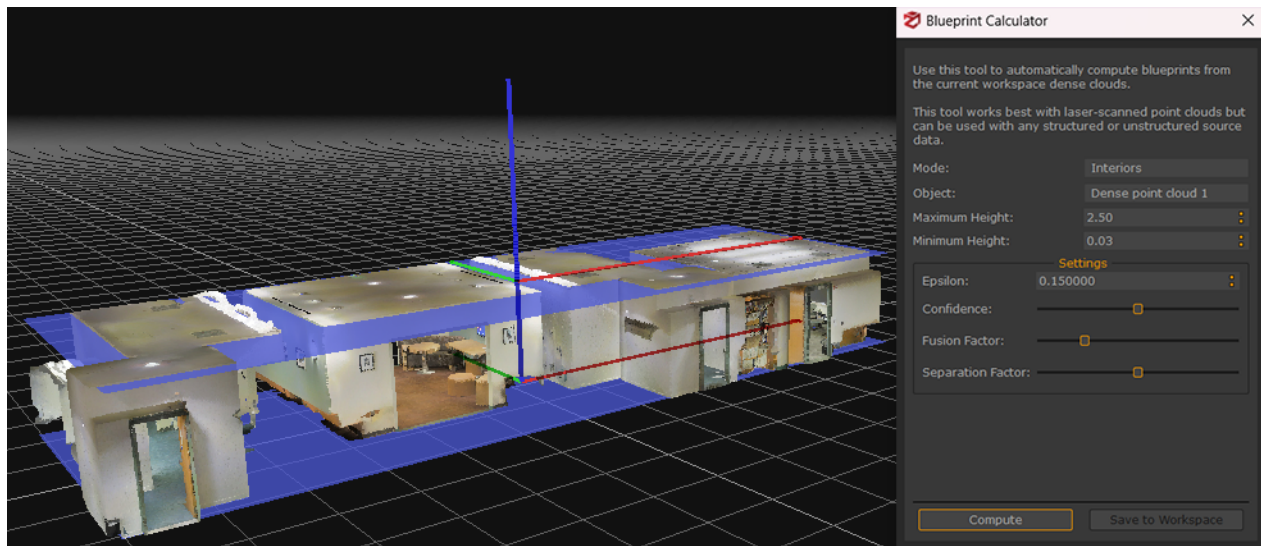
You can change the color of one (or more) drawing elements by selecting and right-clicking the desired element(s) from the "Drawing Elements" section in the Project tab and selecting the **"Change selection color"** option.



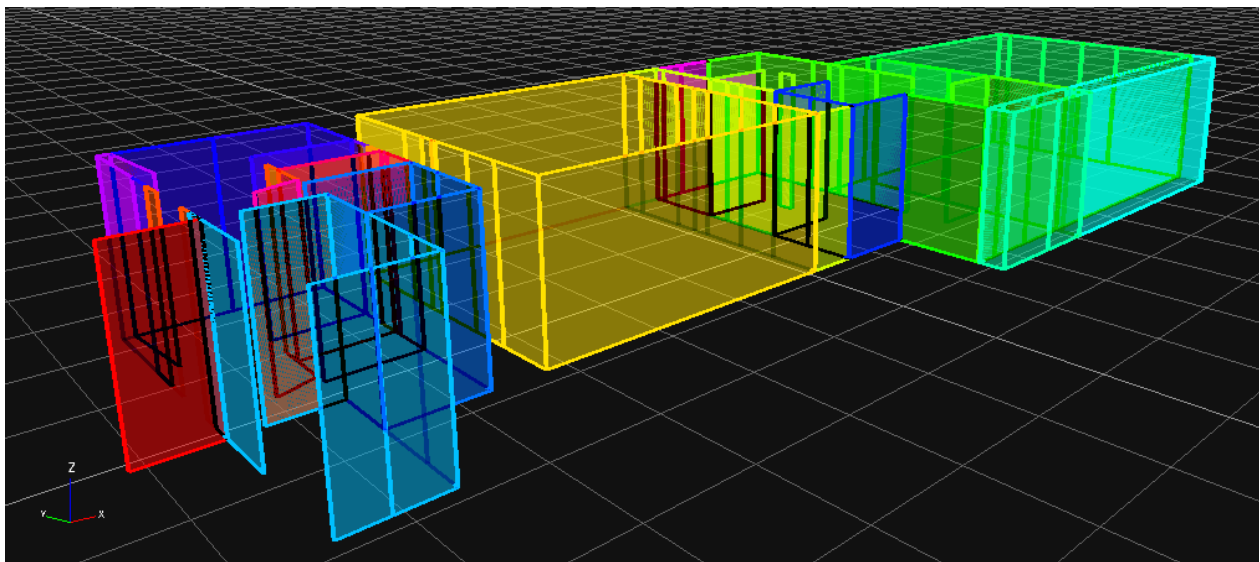
It is also possible to **generate a polyline from control points** simply right click a control point and select **"Make a polyline"**. You will be then be able to select the points of the polyline.

Similarly, you can also create surfaces from this very same tool, and again, you can create them also by using control points.

3DF Zephyr also allows to automatically generate **blueprints**. This functionality works better with laser scanner imported point clouds but can be used also with photogrammetry-generated point clouds.



Once the user has selected the appropriate mode (interiors vs exteriors) and confirmed the automatically detected floor and ceiling planes, 3DF Zephyr will automatically compute and save the blueprints (polylines and surfaces).

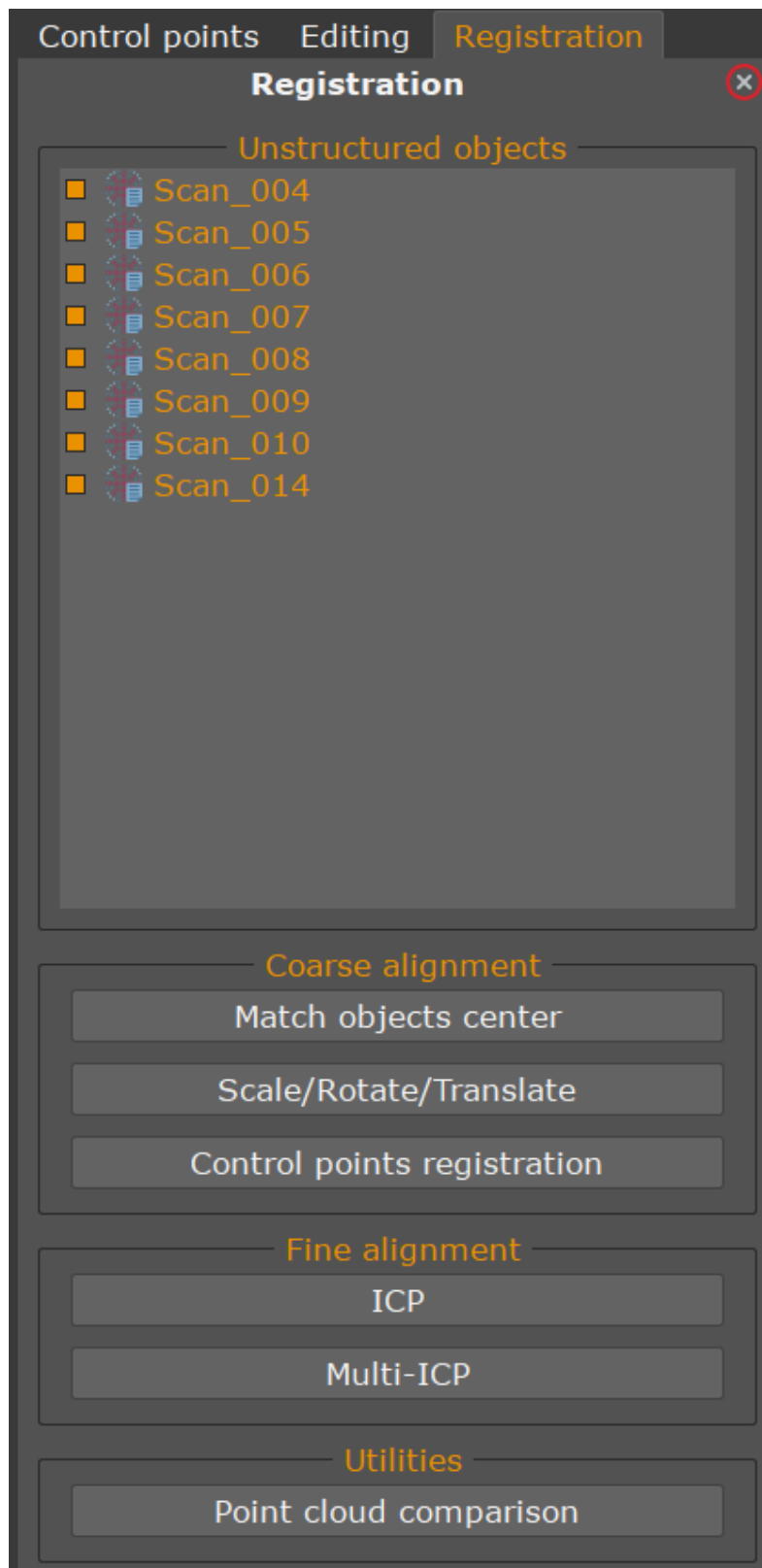


Registration panel

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The **Registration** menu allows the user to handle point clouds registration. From this menu you can access to the:

- Coarse alignment functions
- Fine alignment functions
- Utilities



Match objects center

This tool is useful when a photogrammetric dense point cloud has already been created and a laser scan is then imported into the project. In some cases, the scan may have

been acquired in a different coordinate reference system than the photogrammetric dense point cloud, causing it to appear displaced or entirely invisible in Zephyr's 3D workspace.

The **Match Objects Center** tool resolves this by repositioning the imported scan so that its center aligns with that of an existing structured object, typically the photogrammetric dense point cloud, making both datasets visible and spatially close to one another.

Scale/Rotate/Translate

If the point clouds are too far apart to be aligned automatically, the tool will activate the



Gizmo

together.

, allowing you to manually bring them closer

For a visual walkthrough of this process, refer to the online tutorial [#A07. Laser Scan Management > Method 1: Manual Alignment via the 3D Gizmo](#) on 3Dflow.net.

Bundle adjustment

What is the bundle adjustment?

The bundle adjustment is a non-linear minimization procedure that adjust points and cameras by minimizing the reprojection error of points. It's performed at the end of each merge and a final bundle adjustment with all points and cameras is always performed at the end of the structure from motion procedure.

3DF Zephyr (except for 3DF Zephyr Lite and 3DF Zephyr Free) allows running of additional bundle adjustment steps manually by feeding 2D or 3D constraints.

Since the bundle adjustment works on the camera internal and external parameters, keep in mind that only the sparse point cloud will be affected by the bundle adjustment. Any existing element such as dense clouds or meshes that are already in the workspace will not be changed at all. It is strongly advised to run the bundle adjustment after the sparse point cloud until the camera orientation looks right, before moving to the dense point cloud generation.

Zephyr offers an easy to use slider to control the bundle adjustment process, in which you can define the confidence in the constraints. It's worth noticing that the more confidence you put into the manual constraint, the less confidence will be made by Zephyr in its automatically generated points.

- **Running the “Workspace > Optimize Camera Parameters” menu option**

This option only uses the 2D control points as constraints for the bundle adjustment. This is weaker than using 3D constraints, however if you lack any 3D information (such as ground control points) this is your only option.

- **Running the “Align model with 3D Constraints” option**

Similarly, you can run an additional bundle adjustment when scaling the model with control points. Having additional 3D information will help Zephyr to drive the reconstruction towards the correct solution.

The minimum number of control points set as constraints to run the bundle adjustment is 3. However, a higher number is advised, especially when accuracy is important.

You should only increase the bundle adjustment slider value as you increase the number of control points defined in the workspace accordingly, otherwise the final geometry will be closer to the defined constraints only in proximity of the aforementioned constraint points, thus registering high deviation in all the automatically generated points.

Typical usage is when the reconstruction shows an unexpected “rounded” effect due to drifting after the sparse point cloud has been generated, you should try running this type of additional bundle adjustment. If the employed camera/s has/have a very high radial distortion (i.e. fisheye lenses) make sure that “adjust radial distortion” is enabled.

When doing this, again, make sure to use a congruous amount of control points. It's also suggested that you use some control points as constraints, as well as some control points only as control so that you have a way to verify that the solution has been improved (the residual value should obviously get lower).

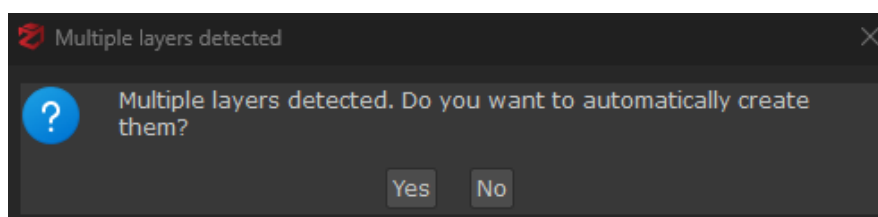
Setting the confidence of the constraints to 99% (or similar) is generally a bad idea.

Layers and multispectral images

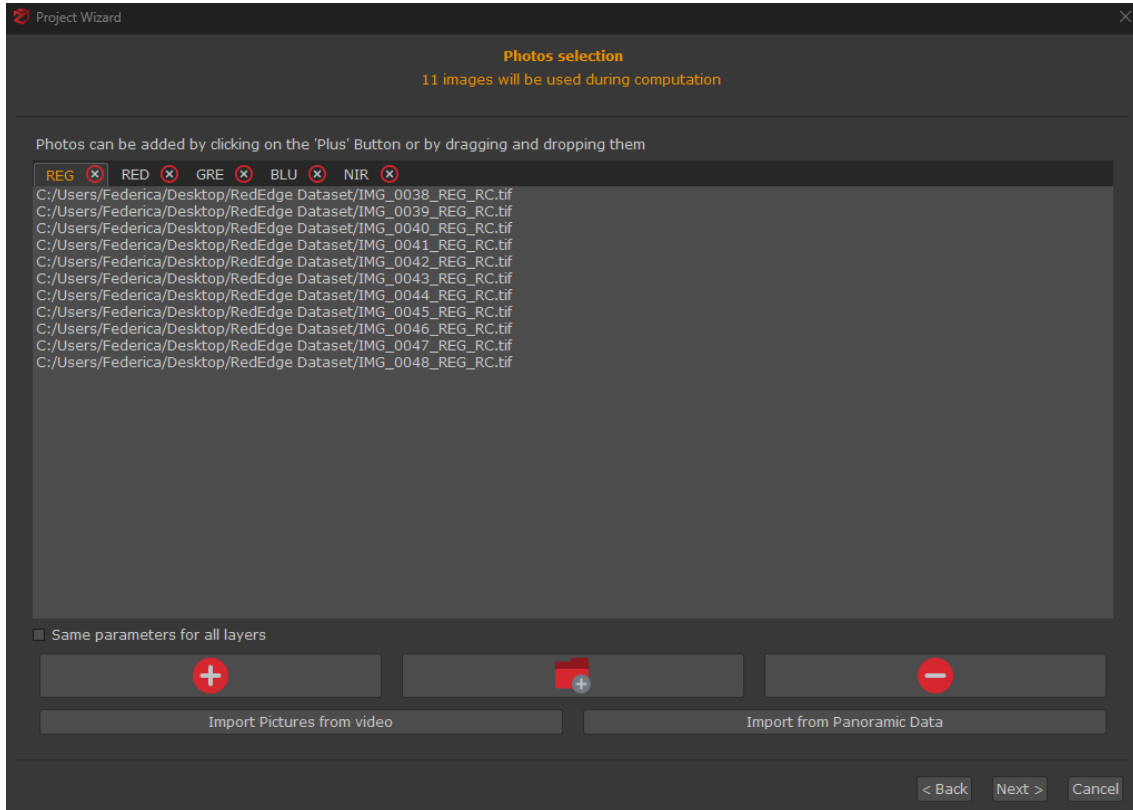
3DF Zephyr supports multi layers. You can select a main layer (which will be used for Structure from Motion) and have secondary layers that can be switched when needed.

Multi layers are often used with multispectral imagery data (see also the photometric calibration chapter if this is your case) or with fixed shooting rig (for example to handle two layers, one with projected patterns and one with RGB images).

Both cases are handled the same way in Zephyr: when images have a suffix (e.g. myfile000_layerone.jpg and myfile000_layertwo.jpg) that may seem like a layer and are added to the project Wizard, Zephyr will ask if you wish to create a multi-layer project.



If you answer yes, Zephyr will automatically split the files into an appropriate number of layers according to the suffix. If you say no, you will still be able to create layers by right-clicking and selecting **"Add layer"**.



You can select the main layer (which will be used for the structure from motion phase) by right clicking and selecting "set as main". Once layers have been set up, you can proceed normally.

The "File" menu

The "File" menu manages the opening and saving of Zephyr project files, as well as few other functions.

In addition to the self-explanatory open/save, other functions are:

Load Model

This function allows loading of a model into Zephyr to use it as a viewer. Loading a model will force the current workspace to be closed. The following file formats are supported:

- ply
- las
- ptx
- obj

- e57
- collada (xml, dae)
- pts
- xyz
- rcp
- fls, fws (Faro)
- zfs (Z+F)
- dp (Dot Product)
- rdbx (RIEGL)

Please note that the Faro, RIEGL, DotProduct and Z+F require the installation of additional plugins available for free at the URL <http://www.3dflow.net/native-laser-scanner-support-plugin-3df-zephyr-download/>

Load 3DK file

3DK files are Zephyr compatible projects made with the 3Dflow's SDK FlowEngine (<https://www.3dflowengine.com>).

Open, Save and Load a project

Each project created with Zephyr is saved as .zep format.

Each workspace also includes the photographs used for the 3D reconstruction, therefore it is possible to open, send and edit the path of .zep files irrespective of the location of the image files. Nevertheless it will not be possible to start one of the four phases of 3D reconstruction or make changes involving photograph usage.

Click on **File > Open or Open Recent** to open a .zep project, or click on **Save or Save As** to save your work.

If you have a command-line reconstruction made with 3DF Samantha, the Structure from Motion algorithm, you can import that by selecting **File > Load from 3DF Samantha**

• Load .psz files

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Within Zephyr you can load psz project by clicking on **File > Load from .psz file**.

Cameras, sparse point cloud and mesh of psz project are imported in Zephyr and you can now start some 3D reconstruction phases such as the dense point cloud or texture generation.

• Load pictures with known camera parameters

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

In Zephyr you can manually import all the parameters of a camera before starting the cameras orientation phase; cameras will be calibrated without being adjusted by the

Structure from Motion algorithm.

To load the parameters just click on **File> Load images with known camera parameters**.

It is also possible to use .XMP files to import a specific camera configuration and skip the sparse 3D reconstruction: this is the preferred workflow for fixed rigs.

The "Workflow" menu

The workflow menu allows users to undertake major actions within the 3D reconstruction workflow, such as starting a new project, completing a reconstruction step or adding photos.

The "New Project" function

By clicking "New project" the current workspace will be cleared and the new project wizard will appear, as shown earlier in the "Starting a new project" chapter.

The "3D Model Generation" function

Starts a new dense point cloud wizard and, after that, a new mesh generation wizard.

The "Textured mesh extraction" function

Starts a new texture mesh extraction wizard. See the "Extracting a surface" chapter as reference. More than one textured mesh can co-exist in the same workspace.

The "Orthophoto from sparse point cloud" function

Starts a new orthophoto creation wizard from sparse point cloud called orthomosaic.

The "Orthophoto from dense point cloud" function

Starts a new orthophoto creation wizard from dense point cloud called orthomosaic.

The "True orthophoto from Mesh" function

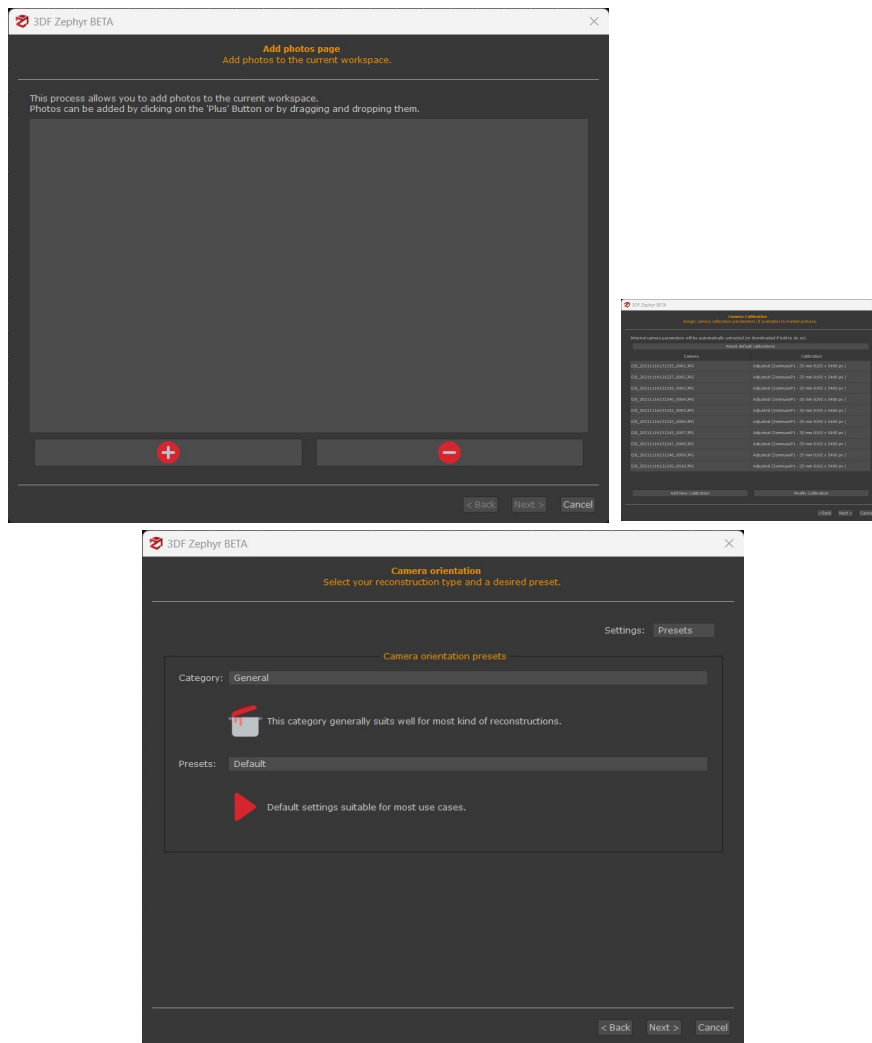
Starts a new orthophoto creation wizard from Mesh called "True Orthophoto".

The "Quick Project" function

This dialog allows to quickly start a new project with a compact interface that allows to skip many of the dialogs shown in the classic workflow wizard.

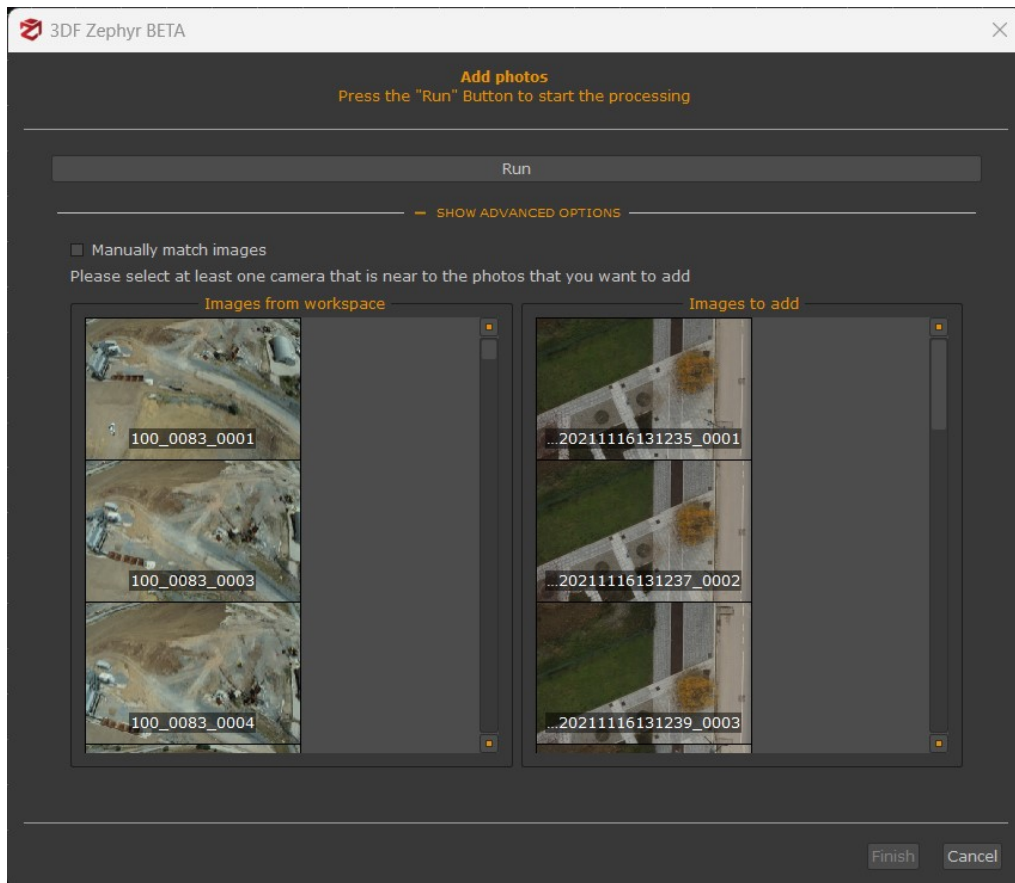
The "Add photos" function

This process allows for adding extra photos to the current project. Pictures must be taken with the same camera rig as the one you previously used for the images you have already processed in the current project. The "Add photos" dialog is similar to the "New project" wizard, so you simply have to add photos by browsing or by dragging and dropping them.



Once the pictures have been imported, click the **Next** button to scroll the camera calibration page and the camera orientation presets page. Select the category and the presets you want to use, click Next and Run the process.

The **Show advanced options** section in the last wizard page allows you for manually match the images.



All that is required to do, is to simply select at least one camera on the left panel (by left-clicking it) framing more or less the same area as the one displayed in the photos you want to add. Once done, the new pictures will be listed in the "Cameras" section and the "Sparse point cloud" will be replaced with the new one, computed using the new cameras in the workspace. Any other workspace element (such as dense point clouds and meshes) won't be affected automatically by this action.

The "Add photo with control points" function

Note: at least three control points have to be placed on the 3D model before running this function.

Choose the pictures you want to add to your current dataset. Into the new window you are requested to find the control points you have previously placed on the 3D model as well as to provide the tool with a camera calibration file of that specific picture if it has been captured with different camera settings.

You can reach the same function by right-clicking on a non-oriented picture inside the Project panel and selecting the **"Orient selected from control points"** option.

The "Advanced" menu

The **Advanced** sub menu offers some extra features:

> The "Dense Point Cloud generation" function

Starts a new dense point cloud generation wizard. See the "Extracting a dense point cloud" chapter as reference. More than one dense point cloud can co-exist in the same

workspace.

> The "Mesh extraction" function

Starts a new mesh extraction wizard. See the "Extracting a surface" chapter as reference. More than one mesh can co-exist in the same workspace.

> The "Generate and export enhanced mesh" function

This function allows to regenerate a mesh (or textured mesh) while arbitrarily densifying the polycount and eventually by intensifying high frequencies details - please note these are fake details as they are not generated with a photogrammetric process. This is a niche feature developed for very specific workflow.

> The "Automatic register images to scans" function

This tool allows adding UAV and/or ground pictures to a set of colored laser scans. Once done, a new sparse point cloud from photogrammetry data will be created and added to the project. The sparse point cloud and the laser scan you have previously selected in the tool settings will be registered together.

Please note that the laser scans must come with RGB data and origin coordinates (i.e., native file formats or .e57 format) and must be aligned before using this tool.

This tool saves time by avoiding creating a photogrammetry project from scratch as well as the registration step between LiDAR and photogrammetry data.

[Automatic register images to scans](#)

In **3DF Zephyr**, it is possible to add UAV and/or ground pictures to a set of registered laser scans, which remain fixed.

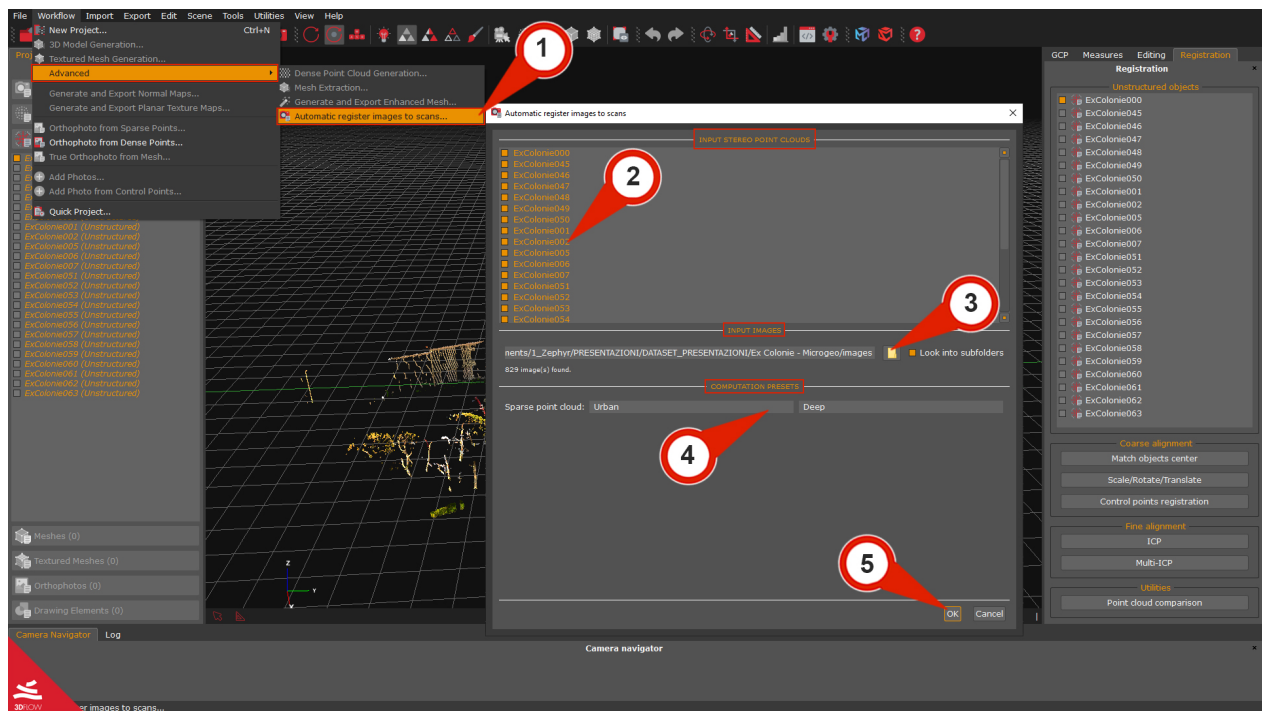
The accuracy of the automatic registration tool increases with the number of laser scans. Before using the tool, laser scans must be aligned and include RGB data and origin coordinates (e.g., native file formats or .e57).

The tool is available from the **Workflow** menu > **Advanced** option > "**Automatic register images to scans (1)**".

In the **Input stereo point clouds (2)** section, you can choose the registered laser scans to use as reference (it's better to use many as possible).

The **Input images (3)** section allows searching the directory where the images are located, while in the **Computation preset (4)** section, you can set the reconstruction **type category** and **preset** according to the used case.

Once you are done with the settings, click the "**OK**" **(5)** button. A new **sparse point cloud** will be created and registered over the selected laser scans.



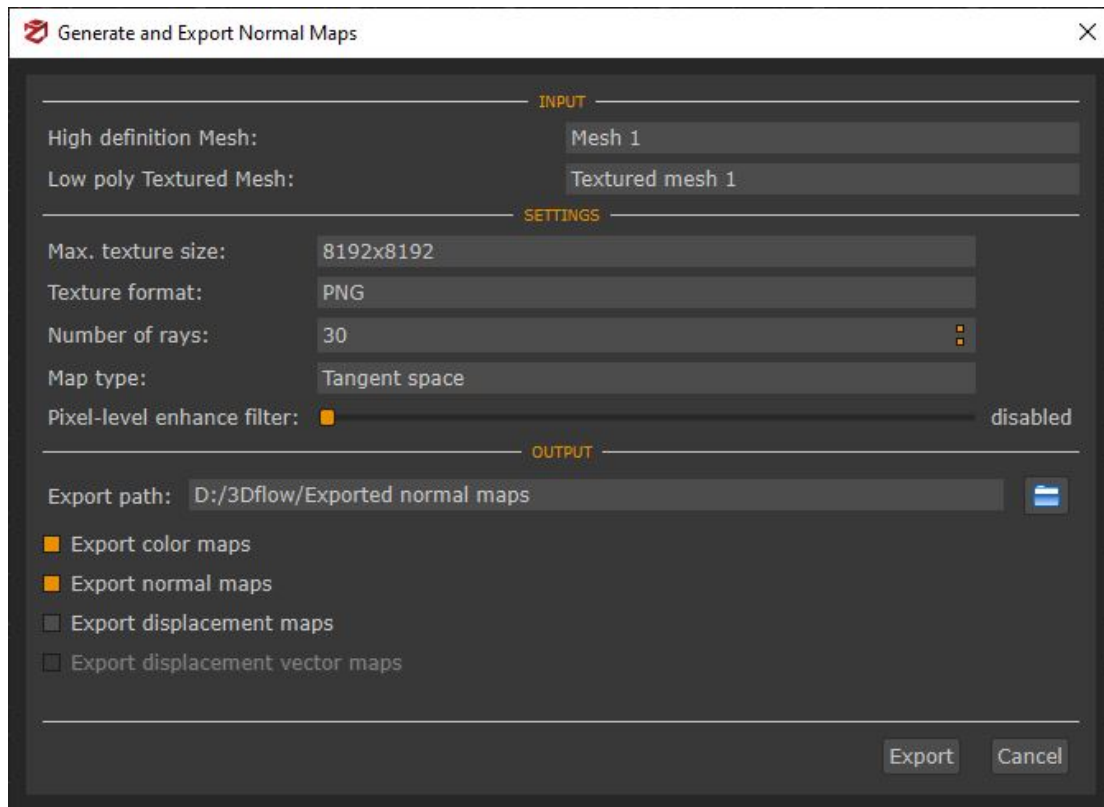
Generate and exports normal maps function

The Generate and exports normal maps function

This function opens the window that allows the generation and export of normal maps and displacement maps. It's necessary to have a high poly mesh and a low poly textured mesh in the workspace in order to create any of these maps.

Additional settings can be tweaked so that the exported maps are compatible with your desired destination: make sure to double check how the exported maps should be ingested (e.g. by a destination rendering engine) as some software might specifically require normal maps to be formatted in a specific way.

Displacement maps can also be optionally generated by checking the appropriate checkboxes in this dialog.

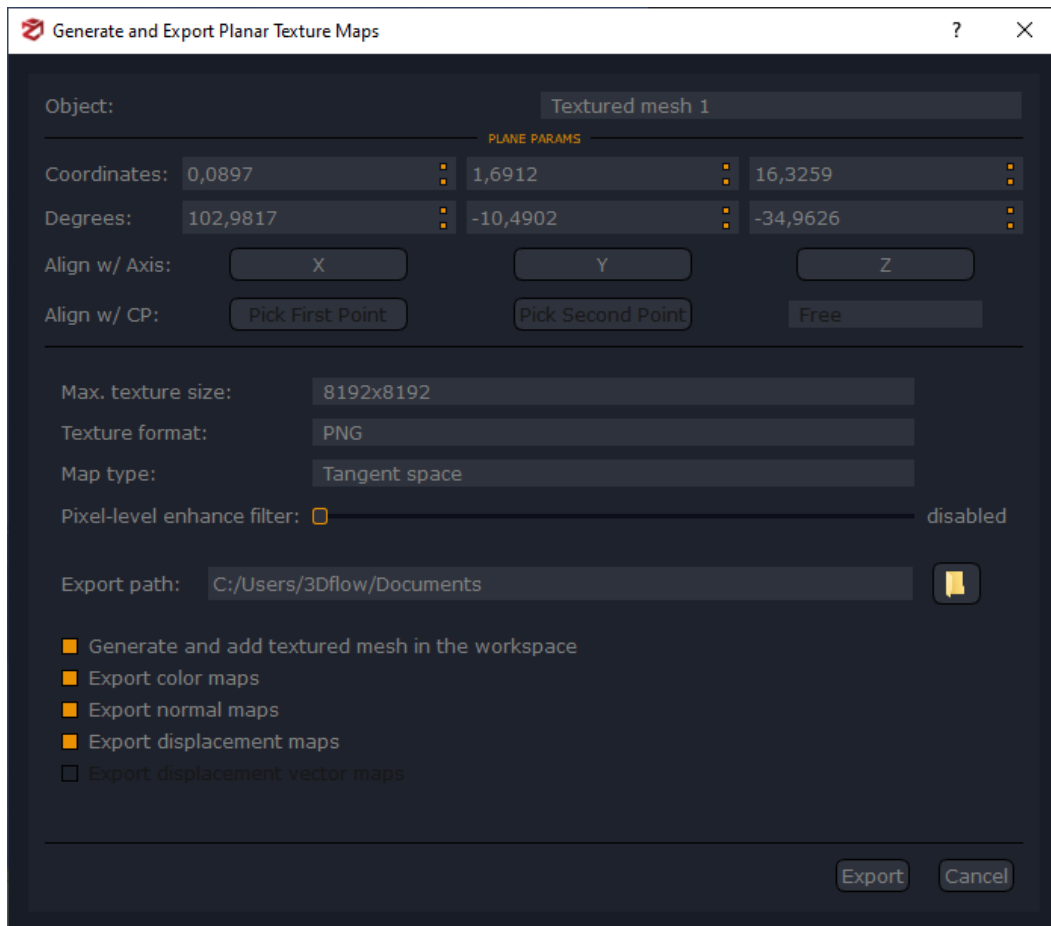


Generate and Export planar texture maps

It's possible to generate and export planar texture maps of a textured mesh in 3DF Zephyr.

You should select a planar parts of the mesh with the **Selections tools** and use the **Cut tool** in the editing tab.

Open the "**Generate and Export Planar Texture Maps**" window under the **Workflow** menu.



In the **Object** section choose the selected planar part of the textured mesh. A blue square plan detector will be shown in the workspace window. It's possible to set rotation, position, size, and the axes of the blue square plan detector.

If there are **control points** present on the mesh, you can use them to align the blue plan detector on the target mesh part with **Pick First Point** and **Pick Second Point** button.

The **Max texture size** and **Texture format** can be set below the previous options.

The **Pixel-level enhance filter** densifies the mesh to have one triangle per pixel of the final map and applies the enhancement filter (similar to photoconsistency).

The **Map type** can be used to set coordinates system (**Tangent space**, **Object space**) to export normal maps.

In the export path space, you can set the folder for saving the exported textures.

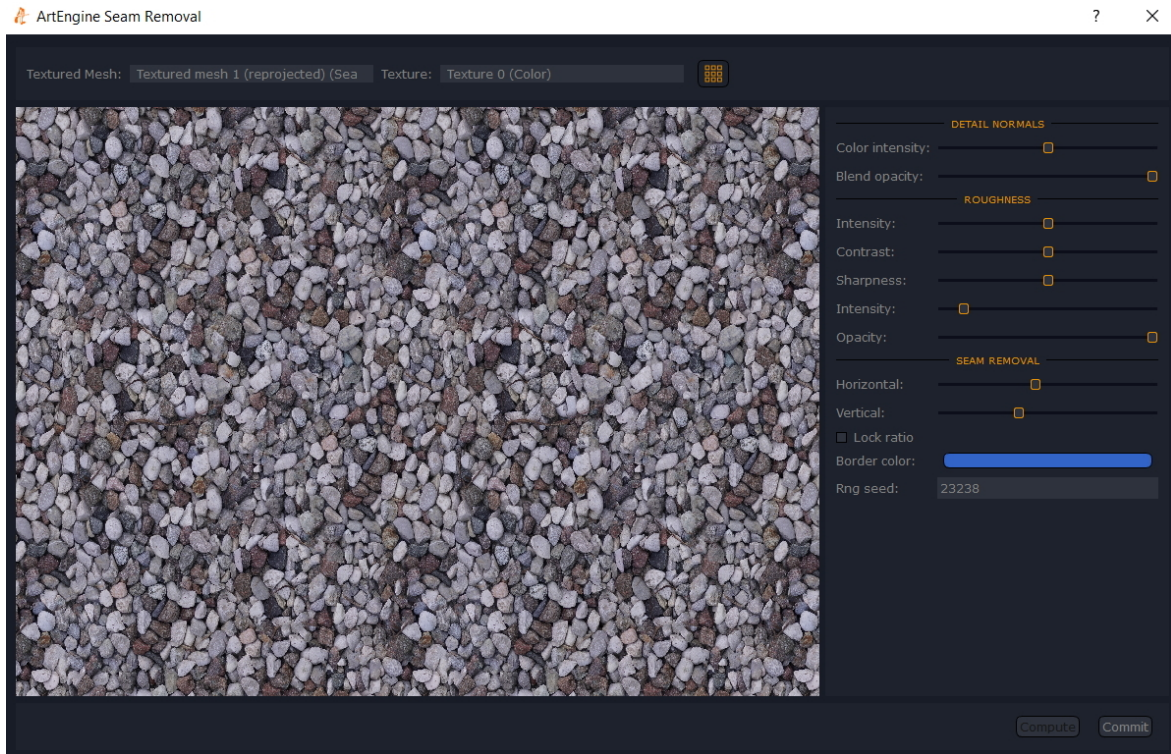
You can decide which part of the texture can be exported (color maps, normal maps, and displacement maps) or add the generated texture in the workspace

ArtEngine Seam Removal

3DF Zephyr has a native integration with ArtEngine, the material authoring toolsuite by Unity3D.

If you own an ArtEngine license (including Betas) you can access ArtEngine features

directly within 3DF Zephyr, which can significantly speed up material scanning workflows. For this reason, this feature is generally used after you have generated a planar texture map.



In order to access this feature, you must right click the desired textured mesh: once the context menu is open, simply left click on "ArtEngine Seam Removal".

Please note that this menu option won't be available unless ArtEngine is installed correctly on your system. If you do not see this option, you may need to install a newer version or beta depending on your license

Use the "**Textured Mesh**" selector to choose the desired element, and the "**Texture**" selector to choose the desired texture to be rendered in the tool window. You can also toggle the "**Repeating Texture**" functionality with the dedicated button on the right of the "**Texture Selector**".

The functionality of the tools is pretty straightforward: you can directly edit the border selection either with the "**Seam Removal**" control on the right side of the window or drag and drop the border limits visually in the left side of the window.

You can control ArtEngine's parameters as well by using the appropriate sliders for Normal Details and . For more information on ArtEngine's setting, please refer to their documentation.

Once you are ready to proceed, simply click "**Compute**". You can evaluate the results and repeat the process by changing parameters and clicking "**Compute**" again. Once you are happy with the result, simply click "**Commit**" to export the results.

Orthophoto generation

These functions are not available in **3DF Zephyr Lite** and **3DF Zephyr Free**.

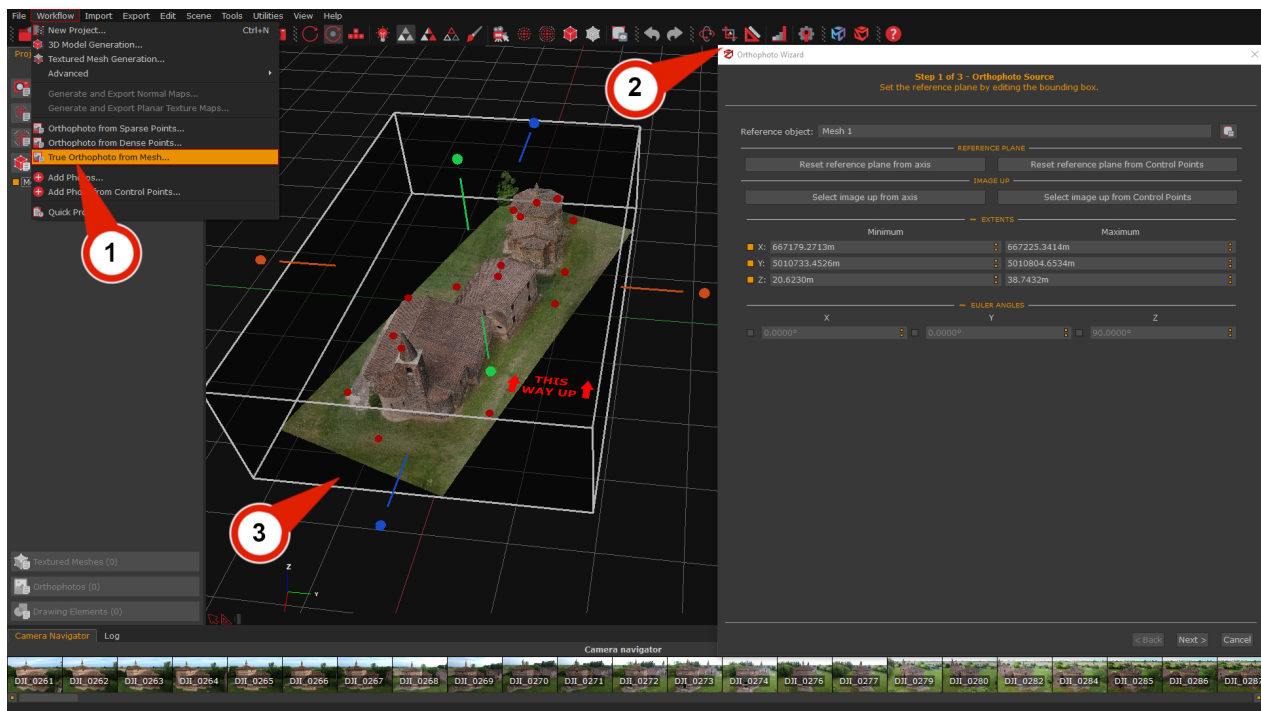
3DF Zephyr is used in various geographic measurements, including **orthophoto generation** that results from the application of drones to support topographic and land surveying activities. The generated orthophoto use the camera information to ensure that the dimensions represented are correct, without concerns about image distortions.

Starting the Orthophoto Creator Wizard

From the **"Workflow"** Menu , you can find three different orthophoto generation options :

- **Orthophoto from sparse points** (requires to have generated sparse points cloud).
- **Orthophoto from dense points** (requires to have generated dense points cloud).
- **True Orthophoto from Mesh** (requires to have generated the mesh).

When you select **"True Orthophoto from Mesh"** (1) option, the **Orthophoto Wizard** (2) window will open, and a **Bounding box** (3) will also appear in the 3D workspace.



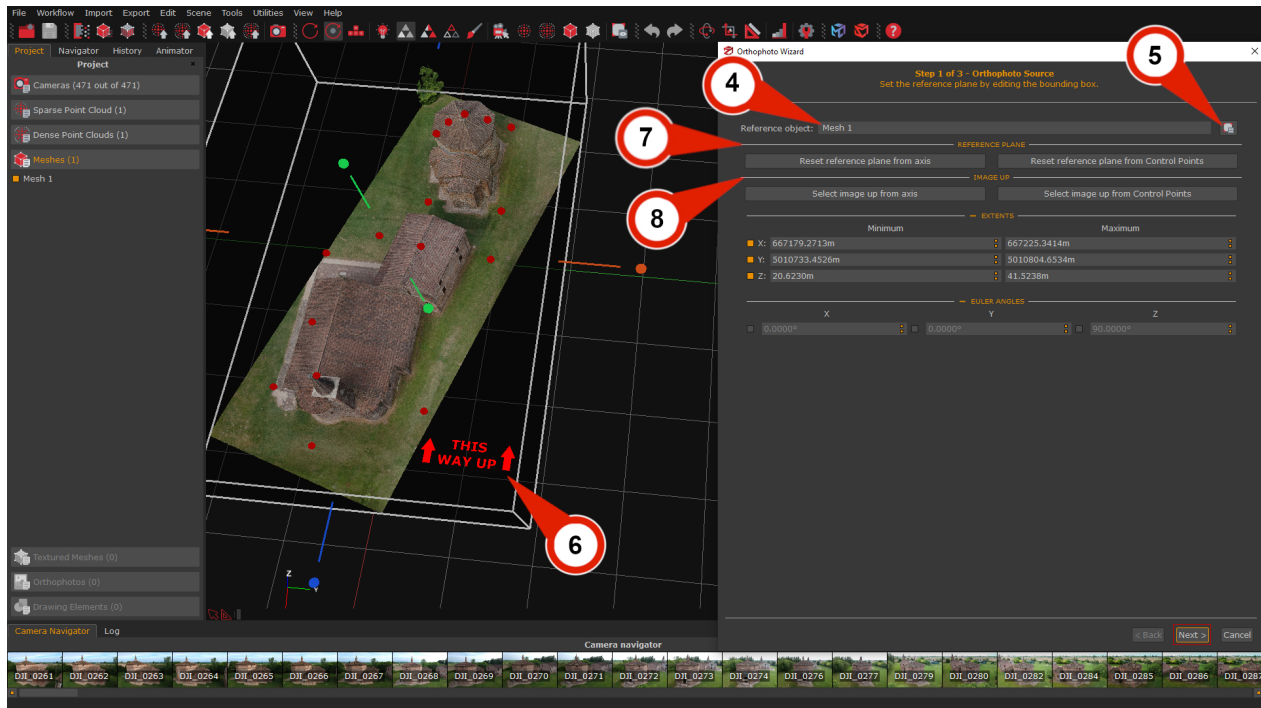
Step 1 - Orthophoto source

The first orthophoto wizard page will allow to define orthophoto's limits by changing the dimensions of the bounding box in the workspace, and it will be possible to set the reference plane from another axis or at least 3 GCPs. The first step is to choose the **Reference object (4)** among the created meshes; the **Adapt Bounding box (5)** button allows to change the mesh's bounding box size automatically.

The Orthophoto wizard's default settings will create an orthophoto of the entire 3D object

with the reference plane on the Z axis. The functions below will allow to set the reference plane from another axis or use GCPs as a reference. While changing the reference plane or the image up direction, it will be possible to see a preview on the bounding box represented by the red text: **THIS WAY UP** (6) .

Note: for practical reasons, it is best to change the Reference Plane and Image Up directions first, as this will reset the bounding box size each time.



Reference Plane section (7)

- **Reset reference plane from axis:** this function allows to set the normal of the orthophoto's reference plane from a chosen axis.
- **Reset reference plane from Control points:** this function use at least three control points to define a plane on which you want to generate the orthophoto. The plane normal will be the new world up vector, and yellow line will be visible in the workspace as a preview during the GCP's placement.

Image Up section (8)

- **Select image up from axis:** This function uses the chosen axis to orient the image up direction of the orthophoto.
- **Select image up from Control points:** This function uses two chosen GCPs to orient the image up directions of the orthophoto.

Extents section

These commands allow you to resize the Bounding box on the XYZ axes. Through the check-boxes, it is possible to restrict one or more axes on which to resize the Bounding Box.

Euler Angles section

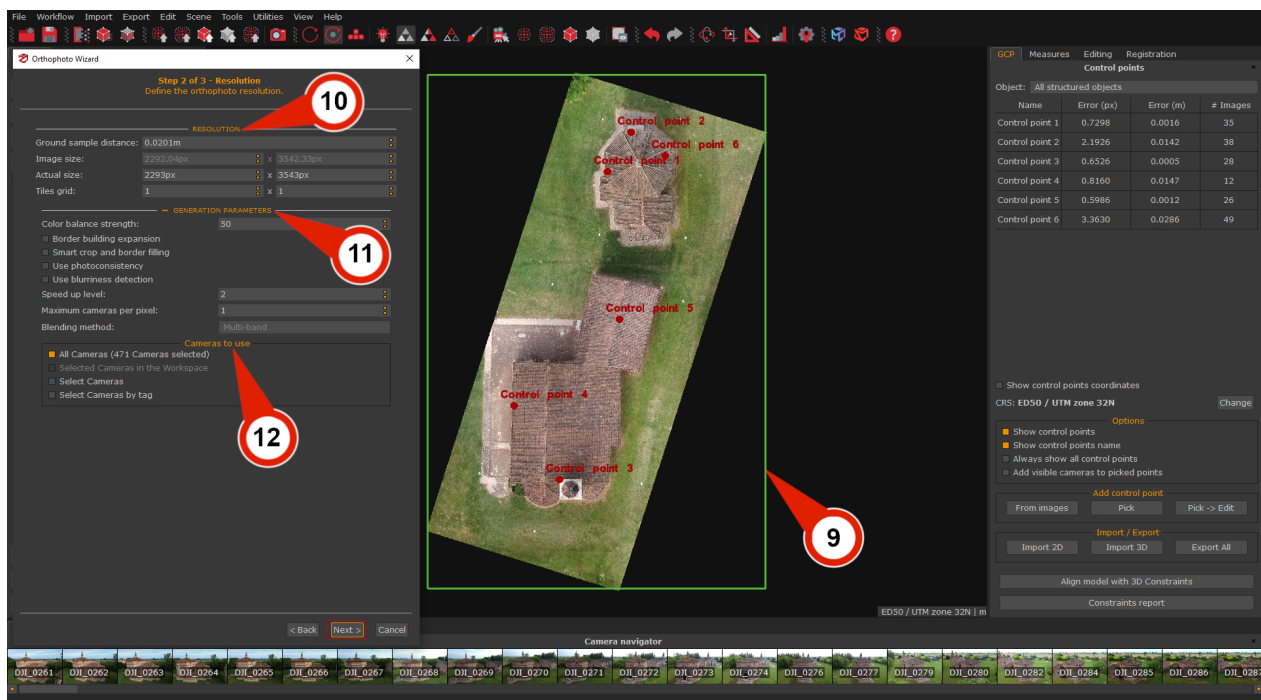
These commands allow you to rotate the Boundingbox on the XYZ axes. Through the check-boxes, it is possible to restrict one or more axes on which to rotate the Bounding Box.

Once the source of the Orthophoto has been set, you can proceed with the **"Next"** button.

Step 2 - Resolution

This page of the orthophoto wizard will present a set of options to define the orthophoto resolution by changing the Ground sample distance and other parameters, or can also set the resolution by specifying the image size.

A preview will be shown in the rendering window, while the green **rubber band (9)** will define boundaries within the orthophoto image.



The orthophoto wizard **Resolution** page is organized settings are organized into 3 sections:

- **Resolution (10):** This section defines GSD and the actual size of the orthophoto. The orthophoto **Width** and **Height** are possible to adjust according to the desired **Ground**

Sample Distance, or you can set the **GSD** directly and let 3DF Zephyr calculate the parameter(s) for you. The Tiles Grid parameters allow setting the Tiles per height and Tiles per width to define the numbers of vertical and horizontal tiles used to split the orthophoto. Setting these parameters could be fundamental for huge orthophoto or computers with a low amount of memory).

- **Generation parameters (11):** allows controlling every pixel's color generation mode. This system is very similar to the texture generation system. We advise leaving the color balance with **1 camera per pixel**; however, if you wish, you may use more cameras for a different color weight. If this happens, you may choose between an **algorithm blending method**:

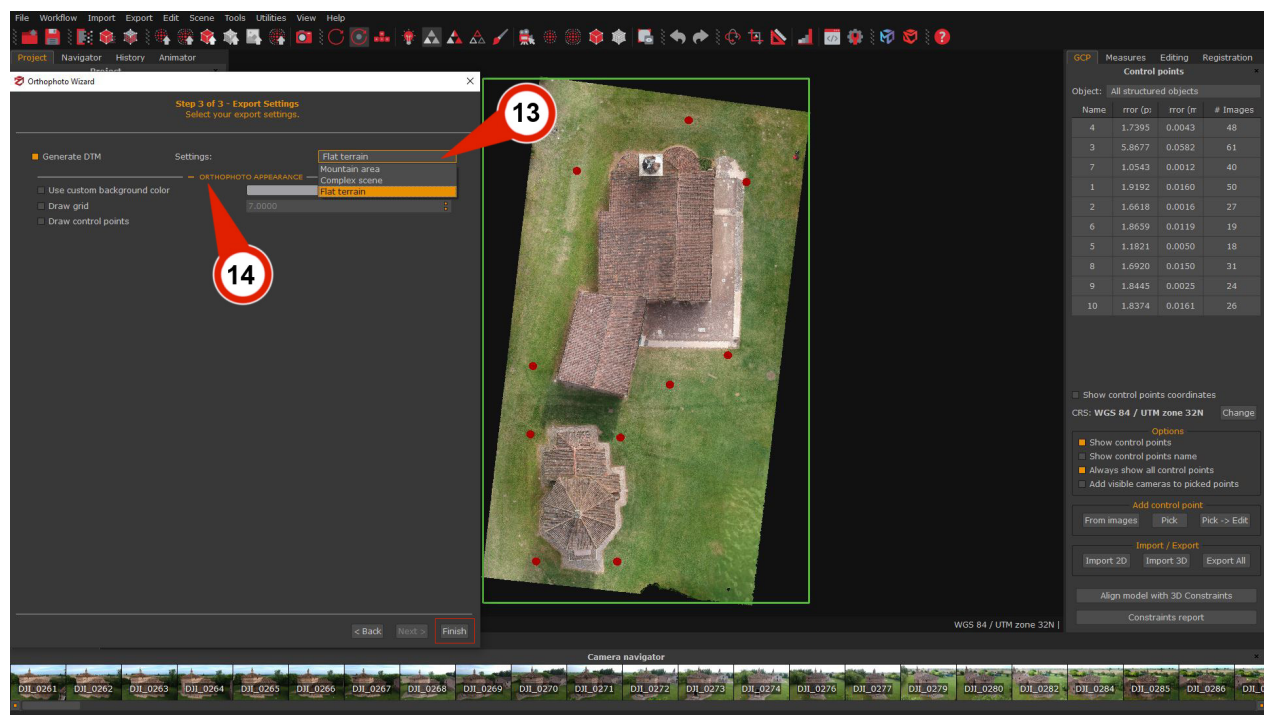
Multiband: will use the mean to compute low frequencies and the best images to compute the high frequencies. This is usually a better choice than **Mean** because although it is less prone to lighting changes (usually just a little worse than mean), the resulting image will be more in focus and sharp by preserving high frequencies.

Mean: will weight the color source depending on the view angle and the distance. Although it's robust to lighting changes, the mean won't keep high frequencies, so will be less in focus and sharp.

- **Camera to use (12):** allow the choice to ignore cameras during the generation process by cameras directly or by tags.

Step 3 - Exporting settings

This section allow to choose the export settings and the appearance of the orthophoto.



- **Generate DTM (13):** selecting this flag will automatically generate a DTM (Digital Terrain Model) file according to the scene type. It's possible to choose three different scenarios (***Mountain area***, ***Complex scene***, and ***Flat terrain***).
- **Orthophoto appearance (14):** this section enables/disables the drawing for customizing the control points and grid on the orthophoto if desired.

When everything is ready, click "**Finish**".

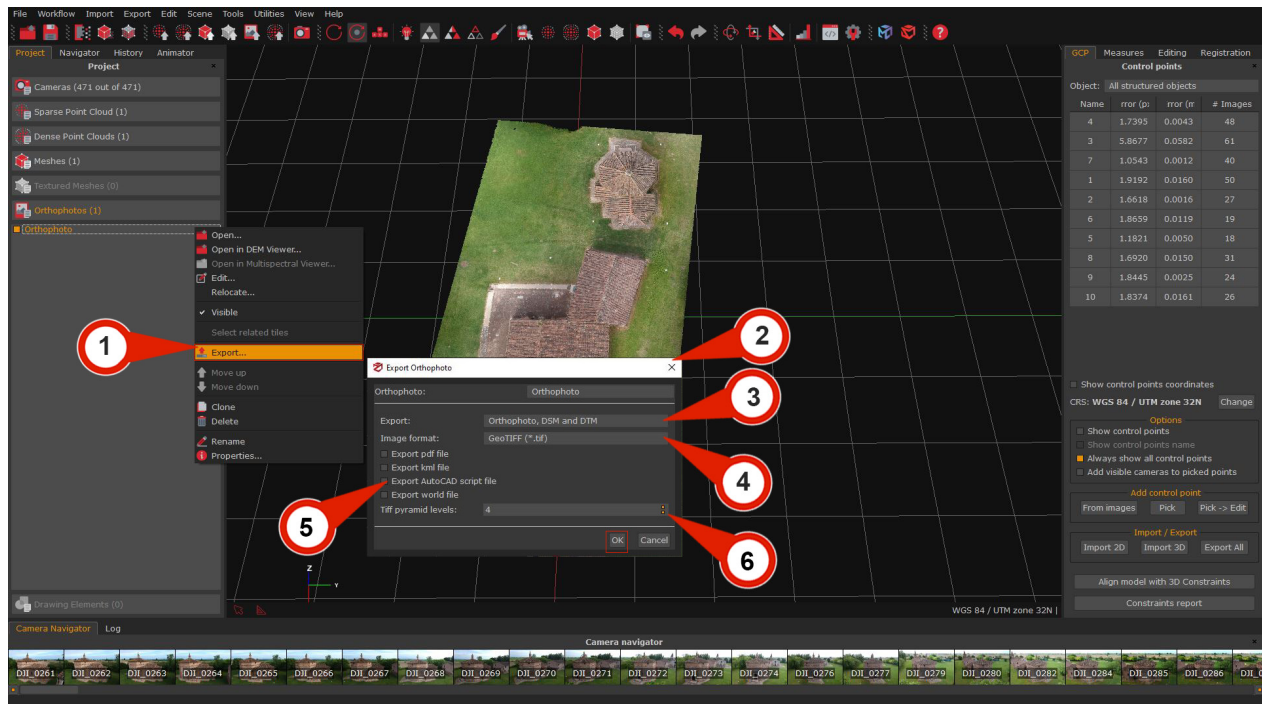
Note: Zephyr will automatically open its **DEM viewer** utility when the process has finished.

Save the orthophoto outside Zephyr

At the end of the generation process the new orthophoto will be listed in the **Project** tab under section **Orthophoto**.

By right-clicking on the orthophoto will be possible to chose the option "**Export**" (1), and the **Export orthophoto (2)** window will appear.

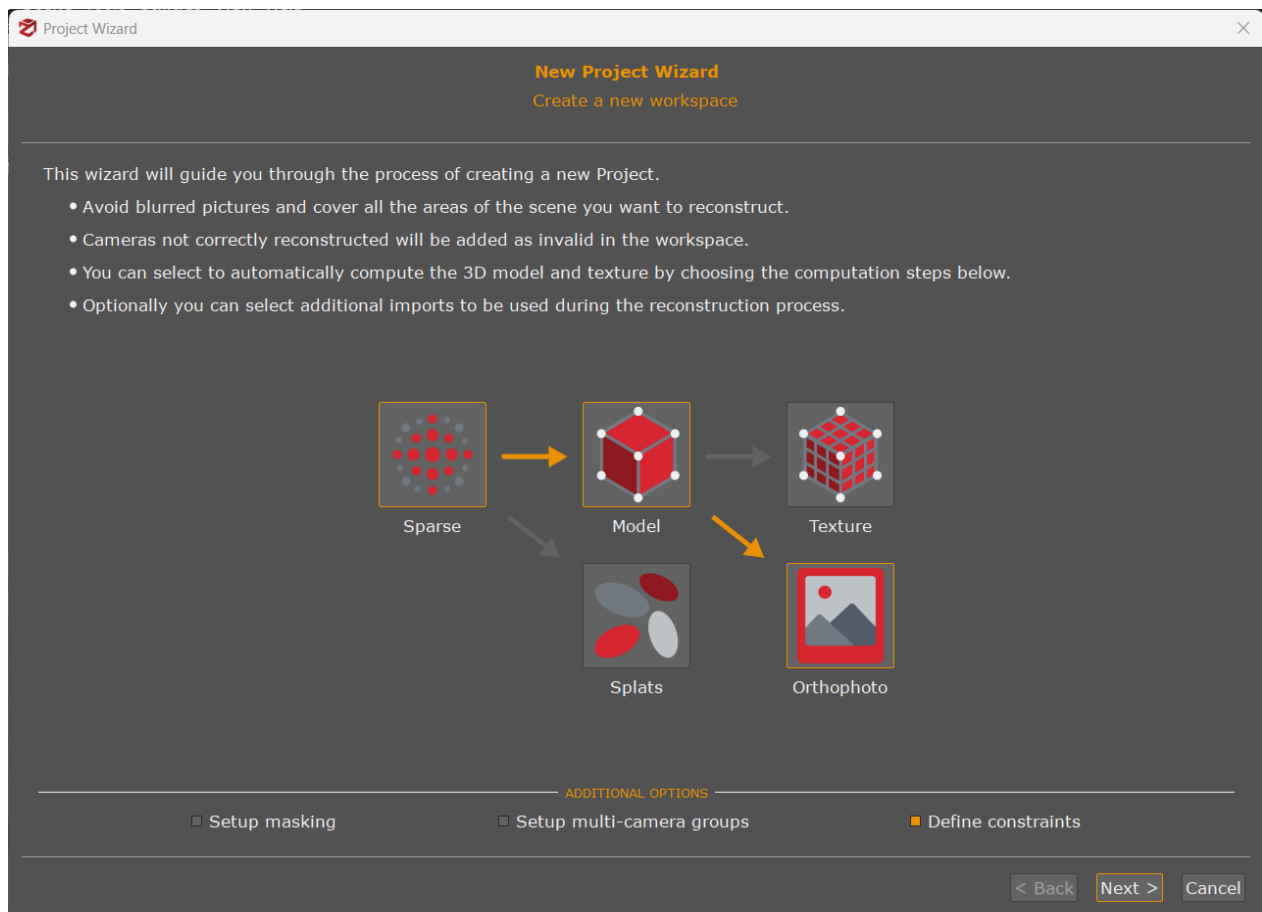
- **Export (3):** the drop-down menu offers the option to export only the orthophoto, the DSM, DTM or all the files.
- **Image format (4):** this drop-down menu allows you to save the orthophoto in these image formats: *jpg*, *png*, and *tiff*.
- **Export Pdf file:** exports the orthophoto in *Pdf* format.
- **Export KML file:** by enabling this checkbox, you can export an orthophoto in *KML* format for Google Earth.
- The **Export Autocad Script File (6)** flag allows the export of a *.scr* file that will automatically load the orthophoto within Autocad, with the correct scale settings set in 3DF Zephyr.
- **Export World file:** exports the World file.
- The **Tiff pyramids level (5)** parameter will allow storing inside the generated tiff orthophoto a pyramids levels layers, which can improve the display of raster data by retrieving only data at a specific resolution required for display.



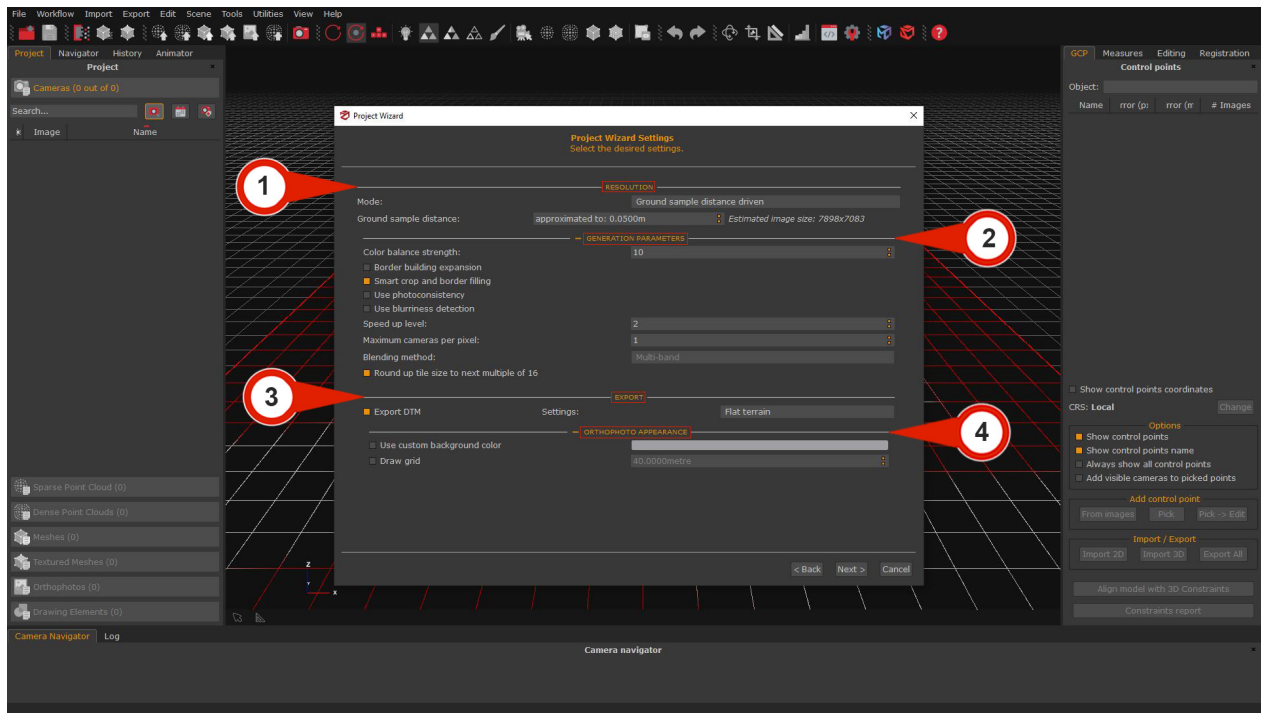
After establishing the parameters for saving the orthophoto, click "**OK**". A **preview (6)** of the exported files will be shown in the **Save As** window, Select the file name and destination folder, and then the "**OK**" button to save.

Generating orthophoto via new project wizard

It's possible to generate directly an orthophoto from the Z-axis (map) in the project wizard.



On the initial page of the project wizard, select the "**Orthophoto**" phase from the available options in the scheme.
By clicking the "**Next**" button, you can navigate through the wizard's pages until you reach the orthophoto settings page.



RESOLUTION SECTION (1)

Switching the **Mode** drop-down menu between "**Ground Simple Distance Driven**" or "**Image Size Driven**" will enable you to define either the **Ground Sample Distance** or the **Image Size (largest dimension)**.

GENERATION PARAMETERS SECTION (2)

It allows controlling every pixel's color generation mode and other tweaks. This system is very similar to the texture generation system. We advise leaving the color balance with **1 camera per pixel**; however, if you wish, you may use more cameras for a different color weight. If this happens, you may choose between an **algorithm blending method**:

- **Multiband:** will use the mean to compute low frequencies and the best images to compute the high frequencies. This is usually a better choice than **Mean** because although it is less prone to lighting changes (usually just a little worse than mean), the resulting image will be more in focus and sharp by preserving high frequencies.
- **Mean:** will weight the color source depending on the view angle and the distance. Although it's robust to lighting changes, the mean won't keep high frequencies, so will be less in focus and sharp.

EXPORT SECTION (3)

Export DTM: selecting this flag will automatically generate a DTM (Digital Terrain Model) file according to the scene type. It's possible to choose three different scenarios (**Mountain area**, **Complex scene**, and **Flat terrain**).

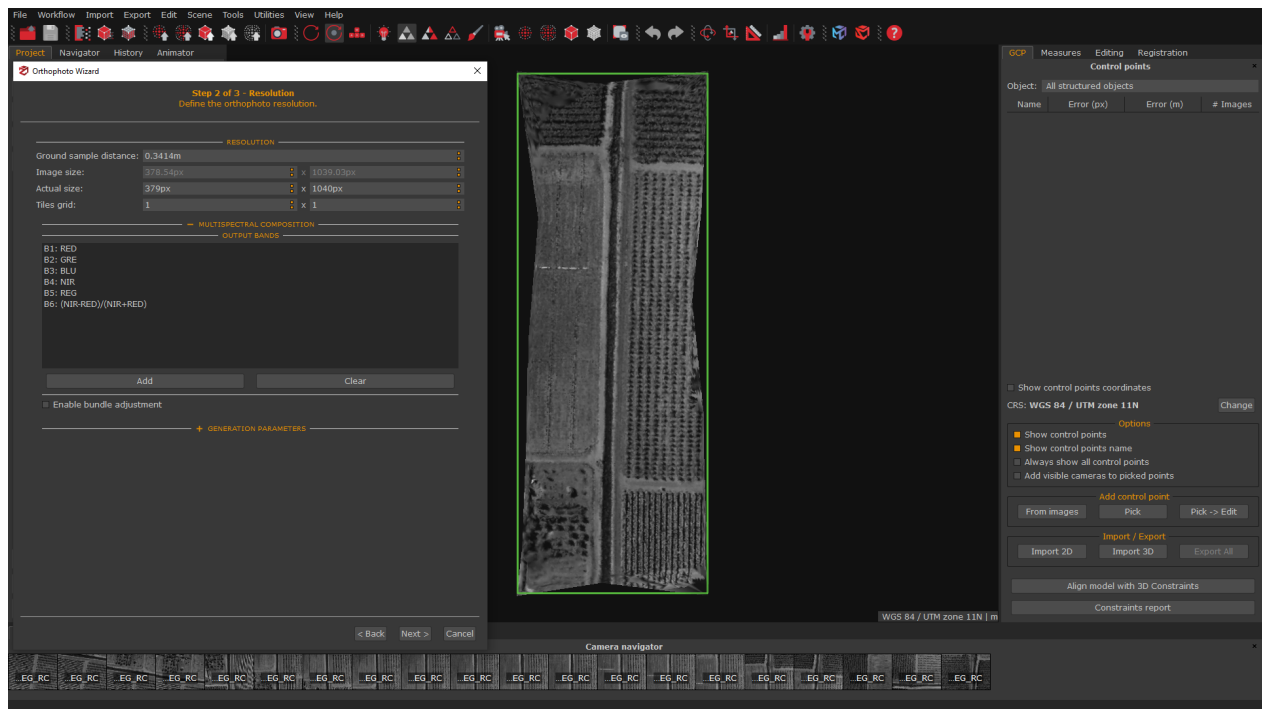
ORTHOPHOTO APPEARANCE (4)

this section enables/disables the drawing for customizing the control points and grid on the orthophoto if desired.

Following the reconstruction process, the orthophoto will be displayed in the **Orthophoto** section of the **Project** tab.

Multispectral orthophoto composition

If more bands (layers) are available in the workspace, the following section will also be shown in the **Step 2 - Resolution** page of the orthophoto generation wizard.



You can select the desired bands in output and eventually create your own composition by clicking the **"Add band"** button and using the following interface:



You may also click the **"Load transform"** button to access previously saved data (e.g. NDVI) or use the save button to save your user defined formula.

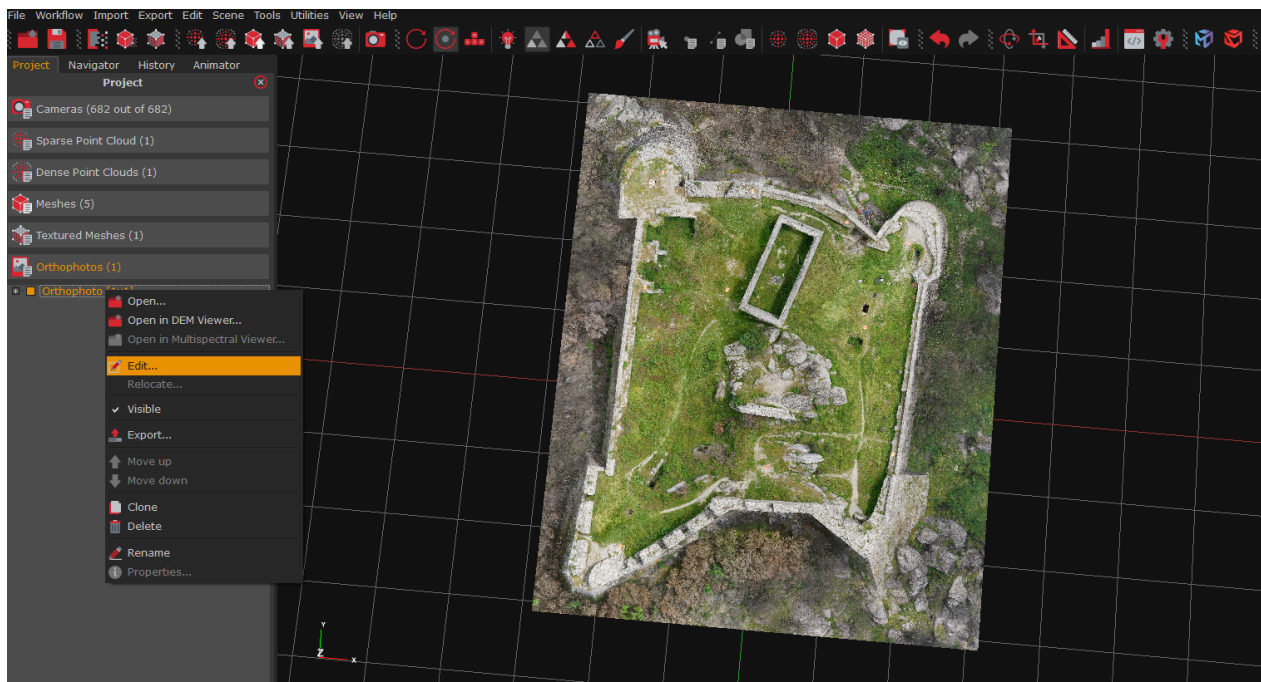
Orthophoto Editor

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

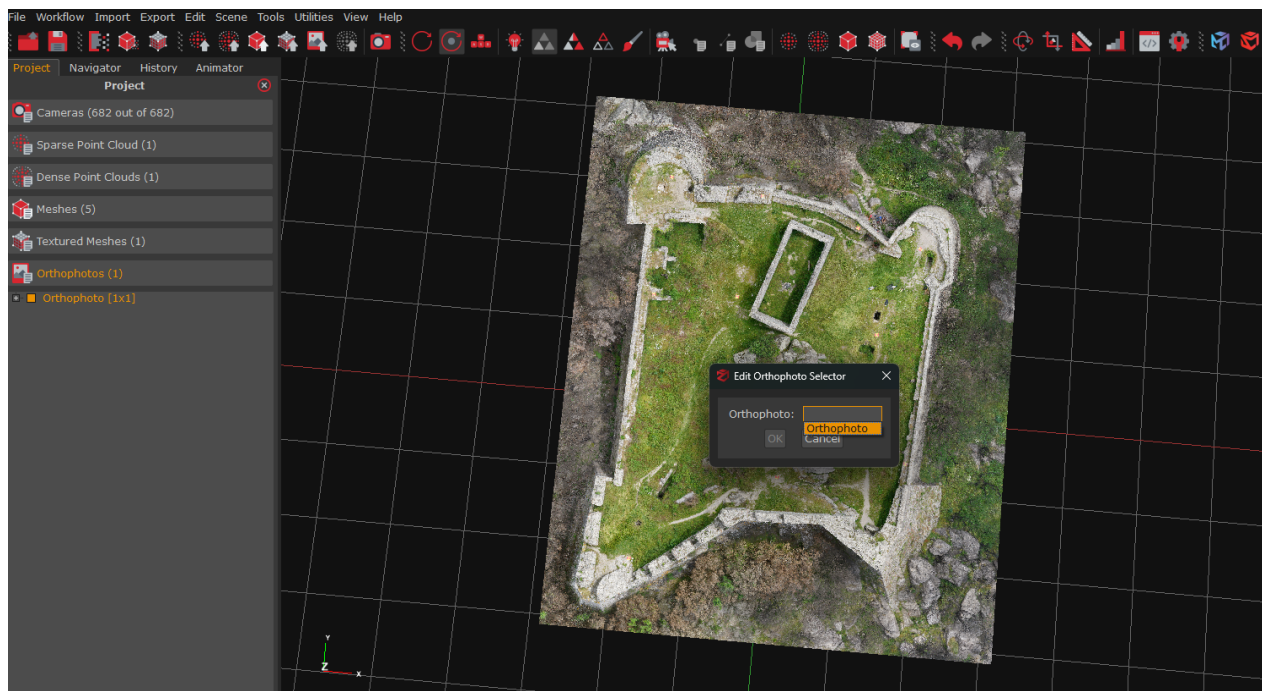
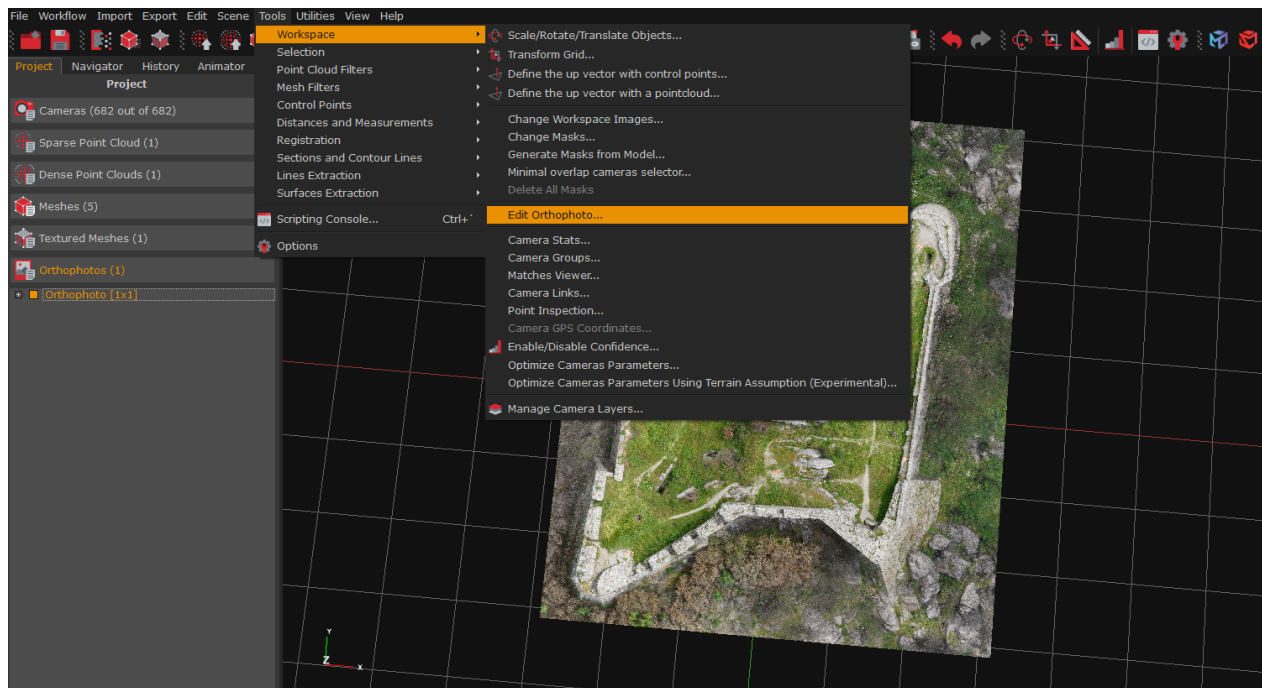
The Orthophoto Editor allows editing and improving specific portions of an orthophoto created in 3DF Zephyr using chosen cameras.

After you create an orthophoto, it's possible to launch the Orthophoto Editor by either methods:

1) Right-click on the **Orthophoto** that requires editing in the **Orthophoto** section of the **Project panel**, and select the **"Edit"** button.



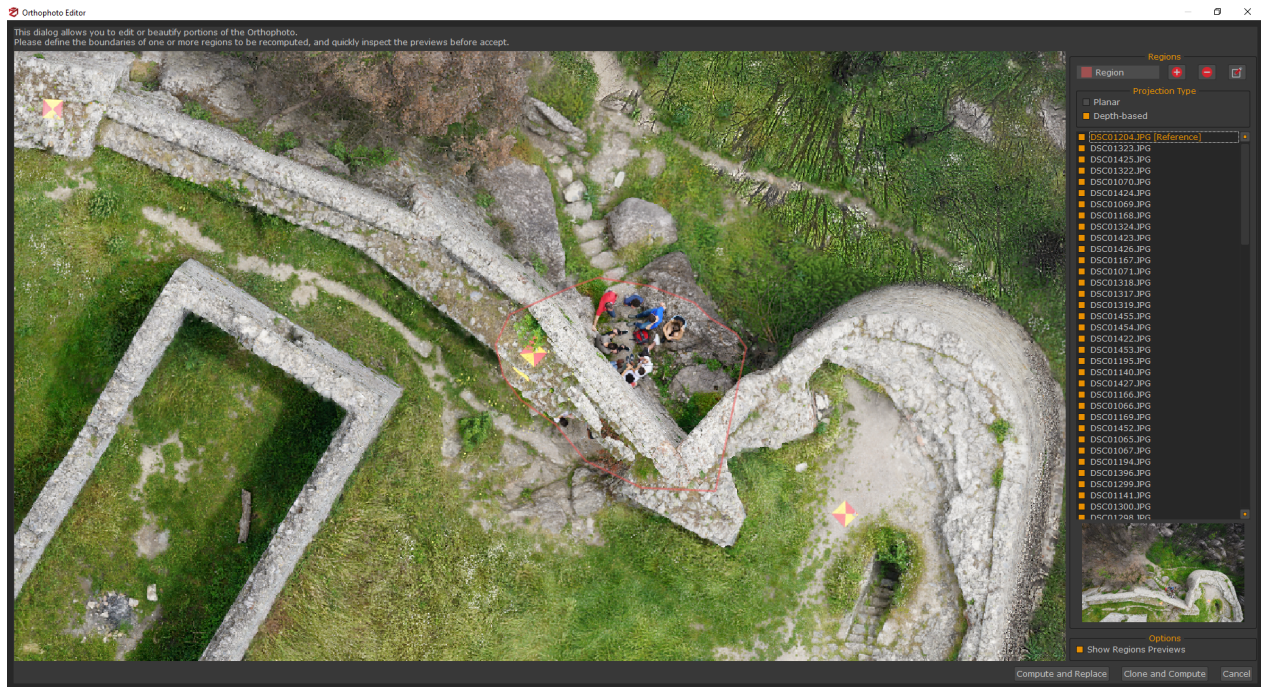
2) Select the **"tools"** menu > **"Workspace"** > **"Edit Orthophoto"**. Choose the orthophoto that needs to be edited in the **Orthophoto selector** dialog, click **"OK"**, and the **Orthophoto Editor** will appear.



The Orthophoto Editor window

The editor dialog provides a set of drawing tools that can be used to select specific regions of the orthophoto that need to be recomputed.

Let's take a look at the interface:



On the right side of the dialog, the following are shown top to bottom:

- **Regions** section: A scroll-down list of the created regions, with the 3 main edit commands:

Add a region button: 

Delete region button: 

Edit Region button: 

- **Projection Type** section: here, it's possible to associate a projection type with the drawn regions, which will be used to recalculate the color balance within the delimited area. The two available projection methods are:

Planar: this method creates an adapted planar projection of selected reference cameras from the right camera list into the current drawn regions. It is advisable to use it only if you want to improve the orthophoto's visual quality of a planar region or when the underlying mesh is not correct, and it's not primary to maintain the accuracy of the data.

Note: when using this projection methods, at least the polygon boundaries must lie in a planar area to avoid reprojection distortion.

Depth-based: this method makes use of the 3D information from mesh

geometry to enhance the drawn regions of the orthophoto by selecting the cameras on the right list. This option makes use of a similar strategy to build the initial orthophoto but uses only the sub-set of images selected in the right list instead, which will allow preserving the original proportions of the orthophoto.

Example:

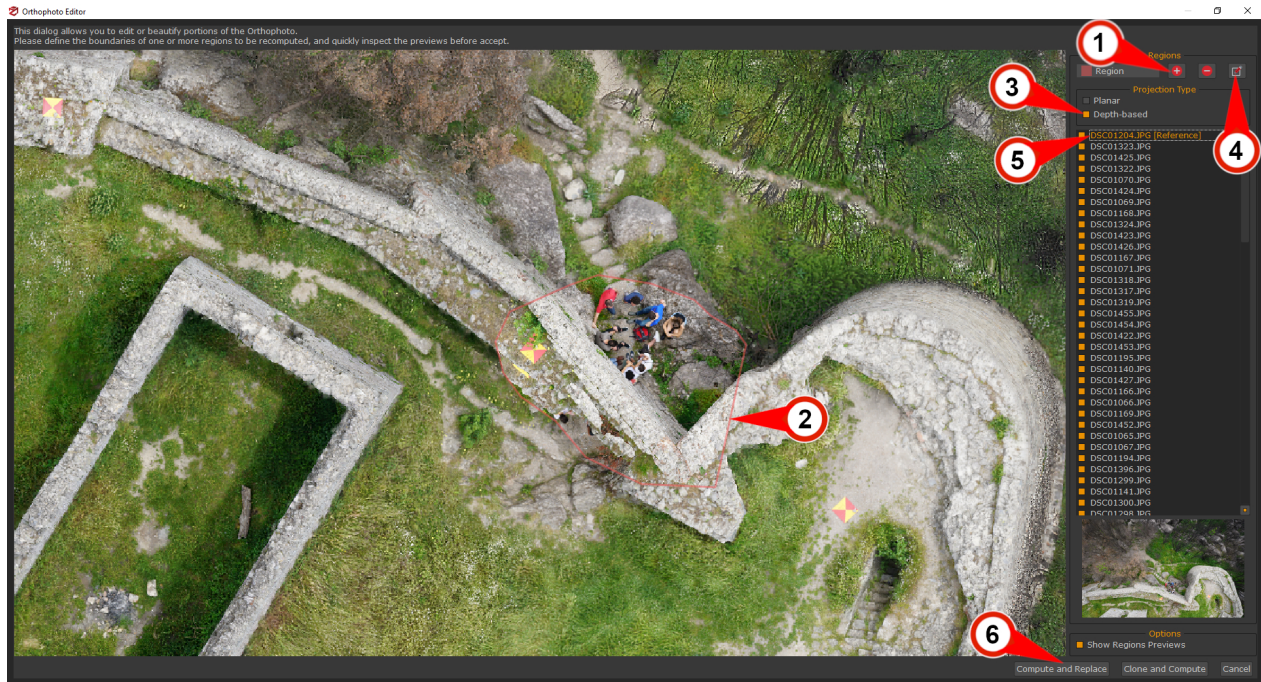
If you want to remove a person or a car from a region, you can select a camera without them as [Reference]. After that, you can deselect all the cameras where the subject is visible; therefore will be more possibilities of removing the unwanted subject without leaving an "image ghosting effect" in the orthophoto.

- **List of the Cameras** associated with the currently drawn regions. Among these cameras, it's possible to select one **[Reference]** Camera that plays a central role in the editing process and the others cameras needed for the computation by the check-boxes. Only the selected cameras will be used during the orthophoto generation, therefore the deselected images won't be used for color balancing.
- **Options:** this check-box will enable/disable the projection preview within the drawn region.

To finalize the editing operation click pressing the "**Compute and Replace**" or the "**Clone and Compute**" buttons. If the result is unsatisfactory, it's possible to undo the operation with CTRL+Z or the "**Undo**" button, in the main 3DF Zephyr interface.

Orthophoto editing workflow

This example will explain the Orthophoto Editor workflow to improve the color balance of selected parts and remove unwanted subjects within the orthophoto.

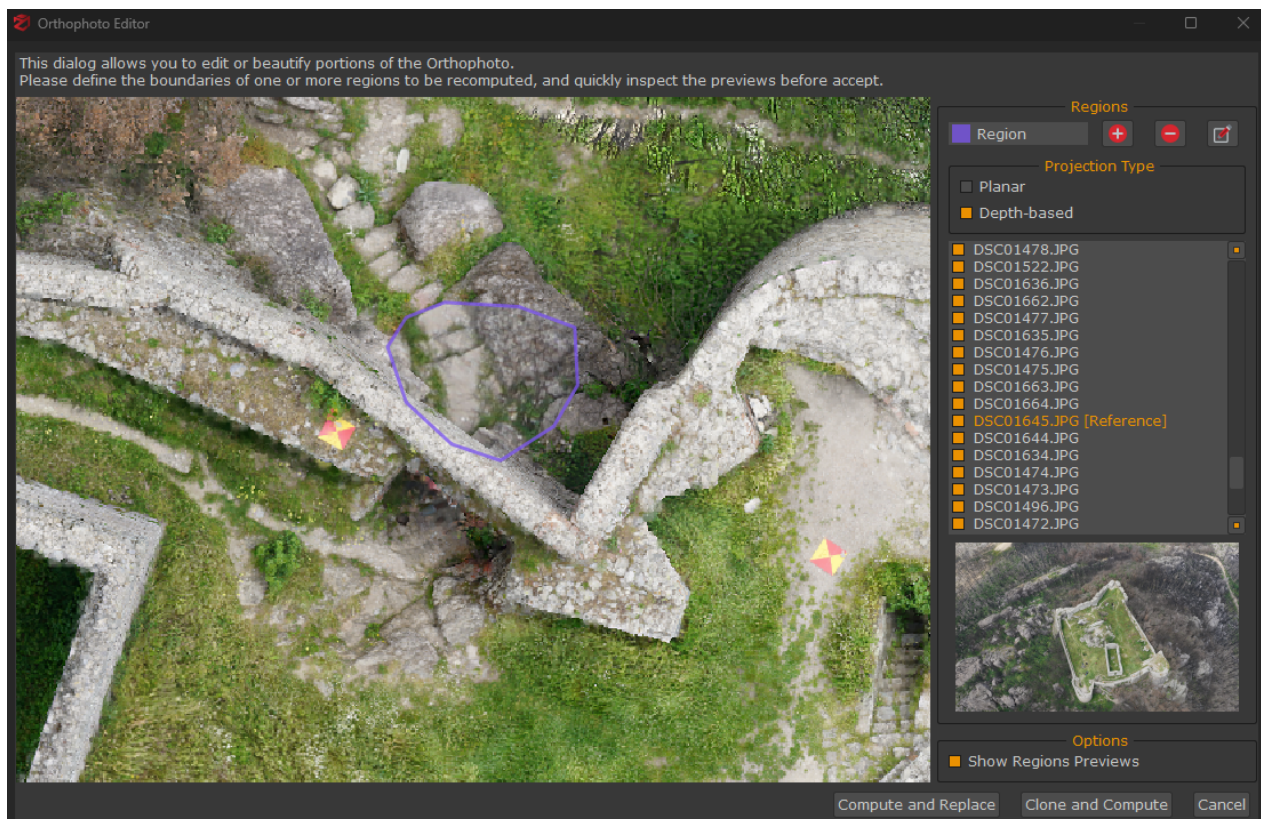
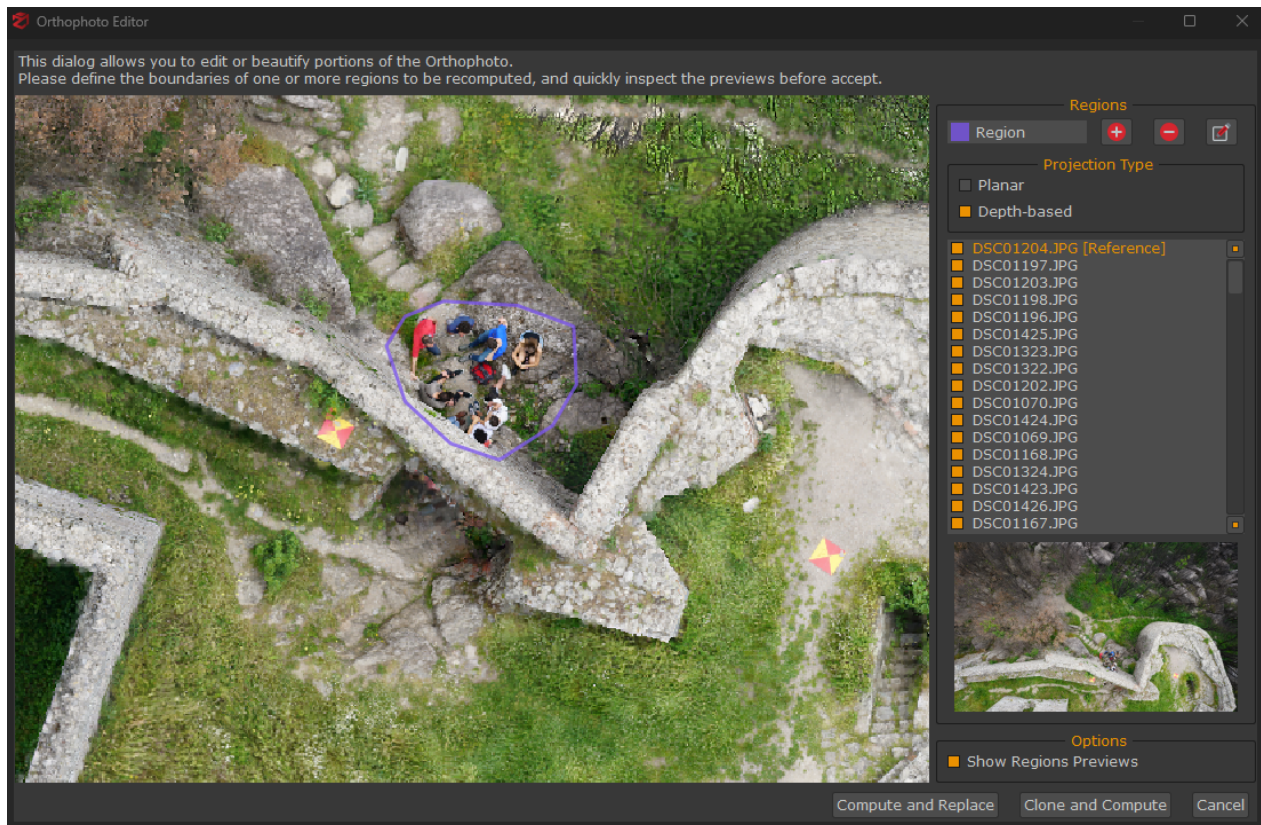


Click on the **"Add Regions" (1)** button, in the **Regions section**, and create the **region's boundaries (2)** on the orthophoto in the working space. To place more regions, click again on the **"Add Regions" (1)** button and draw more regions; if you need to delete a region, press the **"Delete Region"** button .

Chose the **Projection Type (3)** between **Planar** and **Depth based**, and press the **"Edit regions" (4)** button .

The editor will list all the visible cameras for the drawn regions in the **Camera List (5)** section, the first picture will be the **[Reference]** camera used in the computation. It's possible to choose another camera as a reference, that will be more suitable for improving the regions, by double-click on it.

In the example below, the **[Reference]** camera has been switched to one without people, notice that the preview in the regions is changed because the **Show Regions Preview** check-box is enable:



To complete the workflow, click on the **"Compute and Replace" (6)** button.

The "Import" menu

The "Import" menu allows you to import different data into the workspace, for example

point clouds or meshes. Importing a model into a workspace will not cause the workspace to be closed, so that you may combine different sources.

You may:

- Import a model (point cloud or mesh) from an external source. Any imported model at this point will be unstructured, but it can be made structured so that the visibility information can be used. Multi-ICP alignment for laser scanned point cloud is available for this purpose.
- Import a mesh with custom UVs in order to regenerate a texture with said UVs (the mesh can be composed by triangles and/or quads)
- Import a whole other Zephyr workspace in order to merge it with the currently opened one.
- Import drawing elements (DXF and XML, not available in 3DF Zephyr Lite and 3DF Zephyr Free)

Import a model (point cloud or mesh)

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Zephyr can import all the file types supported for visualization.

To start the tool just click on **Import > Import model** (both point clouds and meshes) in the menu bar. Now click on **Import mesh from file** button. Time taken to import depends on the size of the mesh file.

Once the file is loaded you can click on **Import in the workspace** button.

Point cloud file formats available for import:

.ply	.fls	.xml
.las	.fws	
.ptx	.zfs	
.pts	.rdb	
.xyz	.rdbx	
.txt	.dp	
.e57	.x3a	
.rcp	.laz	

Mesh file formats available for import:

.obj

.ply

.dae

.osgb

.ive

.fbx

.xml

Import a mesh with UV map

This tool allows to import an external mesh with known UV map into the current workspace and apply a texture on it.

Before using this tool you need to make a 3D reconstruction, usually completing at least the mesh generation phase. In this way you can add the color information to the mesh you want to import.

Tip: the mesh you are importing and the one generated with Zephyr must have the same reference system. In a nutshell you have to make the same procedure as in SRT transformation alignment tool related to point cloud import.

Merge projects

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

In 3DF Zephyr you can merge two or more .zep projects related to the same scene or subject. Simply click on **Import menu** and select **Import and Merge another workspace** option.

To optimize the procedure it is recommended **to generate just the sparse point cloud** into the projects involved before proceeding with the merge. Once this is completed it will be possible to start the following steps of 3D reconstruction.

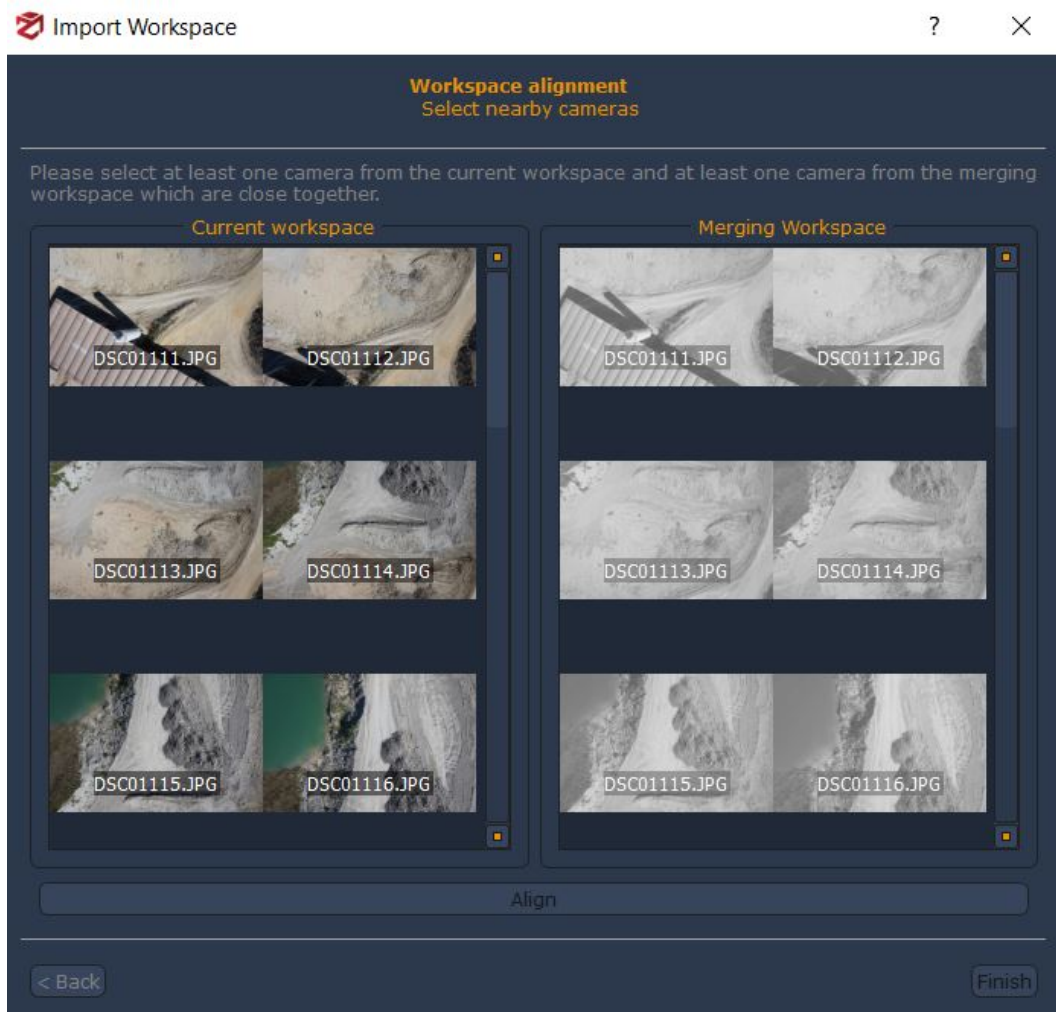
However, it is a perfectly valid workflow to merge two different projects with all kinds of other elements: the wizard will ask you which other elements (any dense cloud, mesh or textured mesh) will be imported into the current workspace.

The photographs of the projects have to share a common area so you can proceed to the merge by means of:

- **Control points:** after clicking on **Import > Import and merge another workspace** you will see the Import window. It is necessary to place at least three control points on each point cloud of the projects before running this procedure. Control points must have the same position and the same name to allow Zephyr to find matches between them and proceed to the merge. It is recommended to keep the **Compute Bundle**

Adjustment option active so as to further optimize the merge process.

- **Nearby cameras:** click on **Import > Import and merge another workspace** to open the Import window where you just select the project you want to merge and click the **Import** button. If no control points are placed in the projects Zephyr will automatically select **Use the nearby cameras** option.
- **Same Reference systems (direct merge):** is the third option which let users merge different projects having the same reference system (local or geographic).



In the image above you can see the pictures of current project work on the left side while the images to be merged are shown on the right side of the window. Note that the thumbnails of images on the right side are displayed in black and white as long as the user selects at least one photograph from the group on the left.

First of all you need to select at least one picture in the list on the left, then you have to select at least one picture in the list on the right. **The most proper pictures to be selected focus on a common area of the captured subject or scene.**

Import drawing elements

This tool allows to import CAD elements (available file formats: .xml, .dxf) in 3DF Zephyr.

Please note that the drawing elements you are importing and the point cloud/ mesh

generated in Zephyr must have the same reference system in order to be correctly overlaid on each other.

The "Export" menu

The **Export** menu allows export of different elements from the workspace as standalone files (for example, an obj file) or to other services (for example, direct upload to YouTube).

The "Export cameras and points" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This function allows to export:

- camera's internal and external parameters and projection matrices (different file formats available);
- sparse point cloud and camera visibility;
- cameras to Bundler (.rd .out) and NERF/Blender formats (.json);
- undistorted images with full or internal distortion bounding box;

The "export dense point cloud" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This function allows for exporting dense point clouds into different file formats.

The first option in the export dialog allows the selection of the desired dense point cloud since more than one dense point cloud can coexist in the same workspace.

The "Export format" option allows you to select the desired export format - it is possible to export directly into .ply, .pts, .ptx, .xyz, .txt, .las, .e57, .ncn, .laz, .rcp and to the 3D visualization web service Sketchfab. By selecting certain formats, some advanced options may or may not be enabled.

The "Export colors" option (if selected and for the supported formats) allows for exporting the point colors.

The "Export normals" option (if selected and for the supported formats) allows for exporting the normals.

The "Use binary encoding" option (if selected and for the supported formats) allows for exporting dense point clouds in binary mode (or in text mode if not selected).

The "Decimate" option (if selected) allows the automatic decimation of the dense point cloud point number up to the desired value (as defined by the Max point cloud option).

The "Local rendering reference system" option (if selected and for the supported formats) allows for exporting the dense point cloud by using the local rendering reference system.

The "Export mesh" function

This function allows for exporting the generated meshes to different file formats.

The first option in the export dialog allows selection of the desired mesh, since more meshes can coexist in the same workspace.

3DF Zephyr Lite allows for exporting 3D meshes to .ply, .stl, .obj/mtl and and to the 3D visualization web service Sketchfab. By selecting certain formats, some advanced options may or may not be enabled.

In addition to the above file formats, 3DF Zephyr allows you to export 3D meshes to .fbx, pdf3D, Universal3D, Collada (.dae), .3mf and .dxf file formats. Please note that the fbx format also allows you to export the camera positions.

The "Export normals" option (if selected and for the supported formats) allows for exporting the normals

The "Use binary encoding" option (if selected and for the supported formats) allows for exporting in binary mode (or in text mode if not selected)

The "Export cameras" option (only for 3DF Zephyr, if selected and for the supported formats) allows you to save the camera positions.

The "Remesh before exporting" option (if selected) allows the execution of the remeshing algorithm, which will generate a new mesh with a vertex count as higher as the number defined by the user.

The "Add comment" option (if selected and for the supported formats) allows the addition of a text comment as file metadata.

The "Export textured mesh" function

This function allows the export of the generated textured meshes in different file formats.

The first option in the export dialog allows the selection of the desired textured mesh, since more textured meshes can coexist in the same workspace.

3DF Zephyr Free can only export textured meshes in a limited number of formats as well as 3D visualization on Sketchfab.

3DF Zephyr Lite allows for exporting textured meshes to .ply, .obj/mtl and and to the 3D visualization web service Sketchfab. By selecting certain formats, some advanced options may or may not be enabled.

3DF Zephyr also allows for exporting (in addition to the formats exported by 3DF Zephyr lite) textured meshes to .fbx, pdf 3D, Universal3D, Collada, USD and tiled mesh for ESRI i3s (.slpk) file formats. Please note that the fbx format also allows export of the camera positions.

Export option in .slpk for ESRI i3s tiled mesh format.

The "Export normals" option (if selected and for the supported formats) allows the export of the normals.

The "Use binary encoding" option (if selected and for the supported formats) allows for exporting in binary mode (or in text mode if not selected).

The "Export cameras" option (not available in 3DF Zephyr Lite and 3DF Zephyr Free), if selected and for the supported formats, allows for saving the camera positions.

The "Add comment" option (if selected and for the supported formats) allows addition of a text comment as file metadata.

This dialog also allows you to choose, when available, the texture export format (PNG, JPG, EXR and TIFF32) as well as select the maximum size of the texture. If you wish to rescale the texture, please note that it's a simple rescaling operation, which does not add detail. You may rescale to a fixed power of two size or automatically compute the nearest power of two value.

The "Export LOD Mesh" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The mesh will be re-generated and split into a certain number of tiles in order to preserve level of detail over huge meshes. Export formats available: Kmz, Zip, Osgb, Ive, Obj, Gltf, Glb+dds Gzip.

The "Export control points" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This button opens the same dialog that the "Export data" button shows from the "Control point" panel.

The "Export workspace" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This function allows the export of the workspace to .ply/text files.

The "Export processing report" function

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This function will create a pdf report about the current workspace. The report will contain information about the workspace, from the sparse point cloud to the textured mesh, with a technical summary and statistics.

The "Export current view as PDF"

This function allows for generating a screenshot of the workspace current view, as a PDF file.

The "Take screenshot" function

Like the "Export current view as PDF" function, this function allows for creating a screenshot of the current view, as an image file. Some additional options are available, such as the possibility to have a transparent background.

The "Edit" menu

From the "Edit" menu it is possible to quickly access the classic "**Undo**" (CTRL+Z) and "**Redo**" (CTRL+Y) actions.

Not all actions in Zephyr support undo/redo.

The command history can be seen from the "**History**" panel.

The "Scene" menu

This menu allows the user to manage how the subject is rendered and how the bounding box is defined in the scene.

Most of these functions have a quick access button on the main toolbar.

Camera management via the "Camera" menu

Zephyr allows navigation of the scene in three different ways:

- **Orbit**: in order to navigate the scene in "orbit" mode the mouse cursor has to be on scene: keep the left mouse button pressed and move the mouse to orbit around the subject. To zoom in or out, keep pressed the left shift button and move the mouse forward/backwards. The pivot is centered as the center of the bounding box.
- **Orbit with pivot**: similar to orbit; however, the pivot will be moved where the mouse cursor is at the time of the left-click button press.
- **Free look**: "first person shooter" view where the movement is applied via the WASD buttons (W forward, S backwards, A left, D right) and Q/E (up,down).

The "Orthographic projection" camera mode can be toggled via the dedicated check-box.

Finally, there are buttons that allow the user to move quickly into a predefined position with respect to the subject (move left, move up, etc.) and a reset camera button.

Rendering management

The rendering settings can be changed by modifying the following settings:

Turn light on/off: toggles the lighting applied to the scene

Show only sparse point cloud: changes the current active workspace object to the sparse point cloud.

Show only dense point cloud: changes the current active workspace object to the dense point cloud.

Show only mesh: changes the current active workspace object to the mesh.

Show only textured mesh: changes the current active workspace object to the textured mesh.

Enable/Disable wireframe: toggles the wireframe visualization

Enable/Disable colors : if the lighting is enabled, this can be used to disable the mesh color for an easier mesh inspection. Obviously, if the lighting is turned off this option won't be enabled as well.

Enable/Disable culling: toggles triangle culling

Enable/Disable volume: shows the computed mesh volume

Edit bounding box

You can enable the [bounding box widget](#) from this submenu.

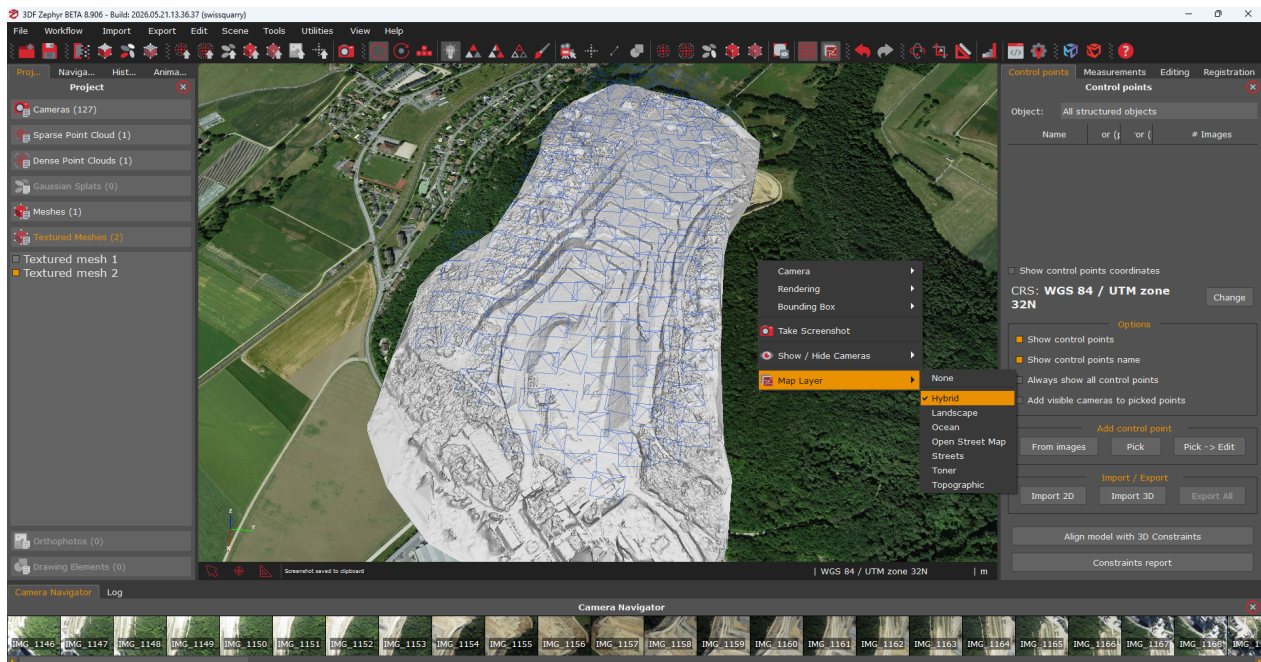
Maps within the scene

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This menu allows the user to fetch and toggle online satellite maps if the dataset is georeferenced. This allows to place your dataset into the proper geographic context.

Note how by right clicking the viewport and selecting the "Map Layer" menu you will be able to swap between various different available layers.

This feature requires an active internet connection.



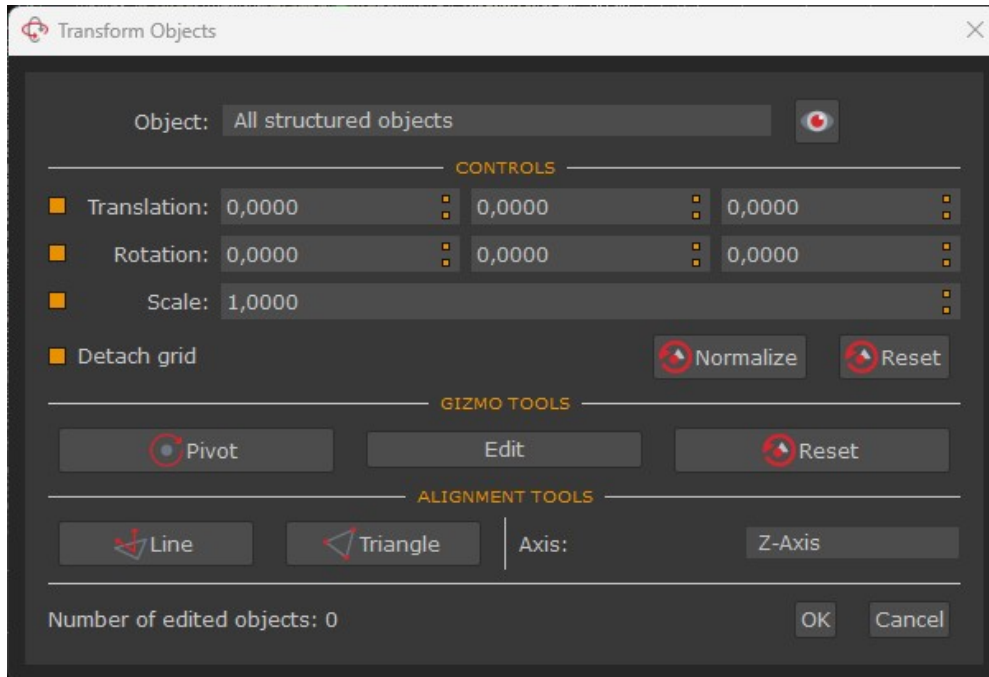
The "Tools" Menu

Tools that directly impact the workspace are grouped under the **"Tools"** menu.

Tools - Workspace

The Workspace menu allows for running tools dedicated to 3D objects management and pictures used in the 3D reconstruction:

- **Scale/Rotate/Translate Objects:** this tool opens a window that allows the user to scale/rotate/translate the 3D models (clouds and meshes) either by inserting your desired values or by using the 3D gizmo performing a manual transformation.



Besides, from this window, you can also edit the pivot of your gizmo, and find other alignment tools such as:

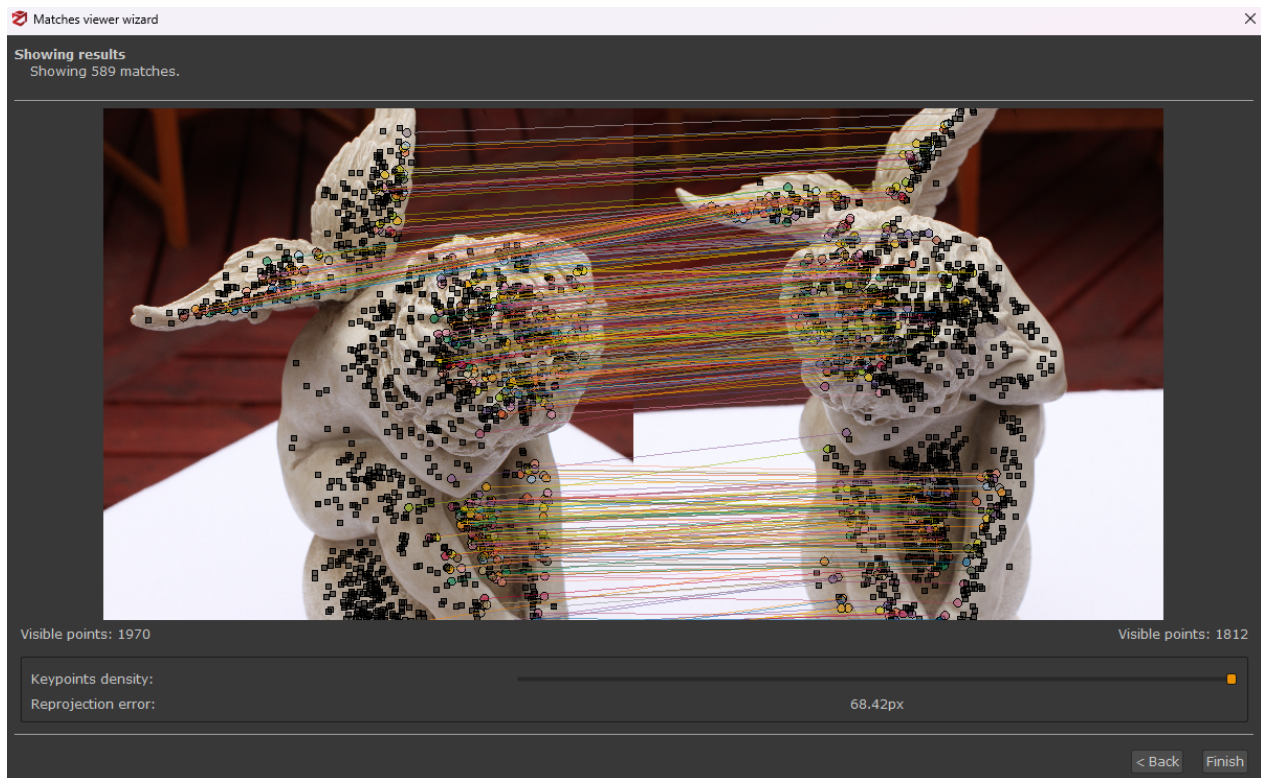
- o **Define the up axis by drawing a line:** allows drawing of a single segment directly on the 3D model to be aligned with the desired axis (the drawing must be done on an element of the 3D model that is actually on the up vector in the real world, such as a wall in a building).
- o **Define the up axis by drawing a triangle base:** allows drawing of a triangle (a plane) from which the Z axis will be computed (the plane must be done on an element of the 3D model that is actually on the horizontal axis in the real world, such as the ground). After picking the second point in the plane, two arrows will be rendered on the screen, one that will show the selected axis (blue arrow) and the normal direction of the plane (light blue arrow). In order to correctly align the axis, the two arrows must match.

Please note: the **Reset** tool in the "**Controls**" section allows for resetting the gizmo to the initial state, whereas the **Reset** tool in the "**Gizmo tools**" section resets the gizmo independently from the 3D object.

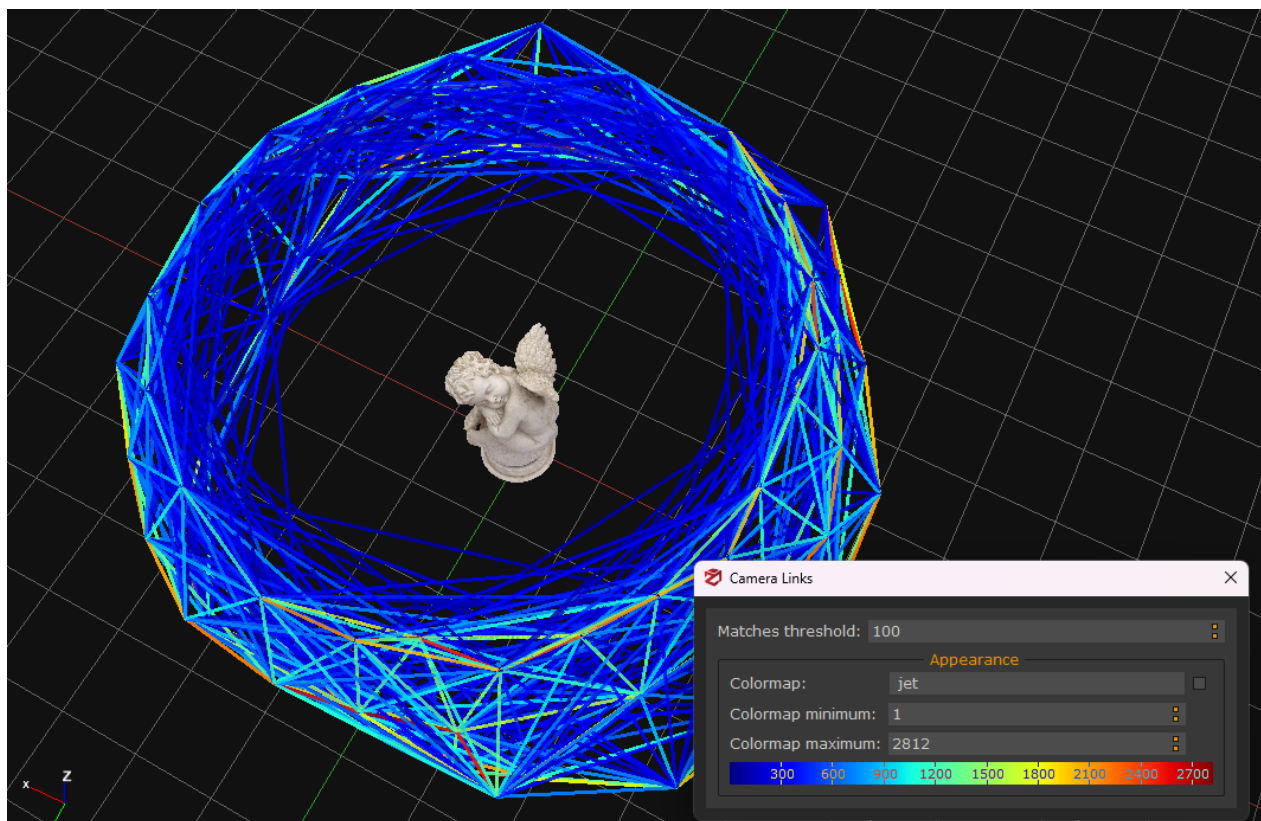
- **Transform Rendering Reference System:** allows to scale/translate the 3D

viewport.

- **Define the up vector with control points:** this tool opens a window that allows to select at least 3 GCPs previously placed to define a plane on your point clouds or meshes: its resulting normal will be the new up vector.
- **Define the up vector with a point cloud:** allows to define the vector from points (either of sparse point cloud and dense point clouds) and to set the desired inlier threshold.
- **Change Workspace Images:** this tool is very useful when working with thermal or NIR (Near Infrared) images: after the 3D reconstruction has been completed using classic RGB images from a normal camera, you can swap the corresponding NIR/thermal image and everything will behave exactly as the sparse point cloud was made with those images. Although this is still a valid workflow, you should now use the multilayer workflow for this case.
- **Change Masks:** allows changing of the masks used for the current dataset.
- **Generate Masks from Model:** allows to use the 3D model as a reference to calculate the reprojection and generate the related masks. It's useful when dealing with post-processing in other 3D modeling software.
- **Minimal overlap camera selector:** allows to define the minimal set of cameras that view a point cloud/mesh. Useful to reduce the camera overlap and not consider redundant cameras.
- **Delete All Masks:** this option becomes enabled when there are masks uploaded into the workspace, allowing the user to delete them from the project if needed.
- **Edit Orthophoto:** this option becomes enabled when there are orthophotos which have been previously generated or imported into the workspace. This tool opens the "[Orthophoto Editor](#)" window which allows to make some visual changes to the orthophotos.
- **Camera Stats:** shows information about the mean reprojection error and the number of points viewed by each camera in the sparse point cloud.
- **Matches Viewer:** opens the match viewer interface. Simply select an image on the left panel by left-clicking it and similarly an image on the right panel. After clicking "next", keypoints and matches will be shown with a line between the two images. Simply click "back" and repeat the process to see matches from different images.

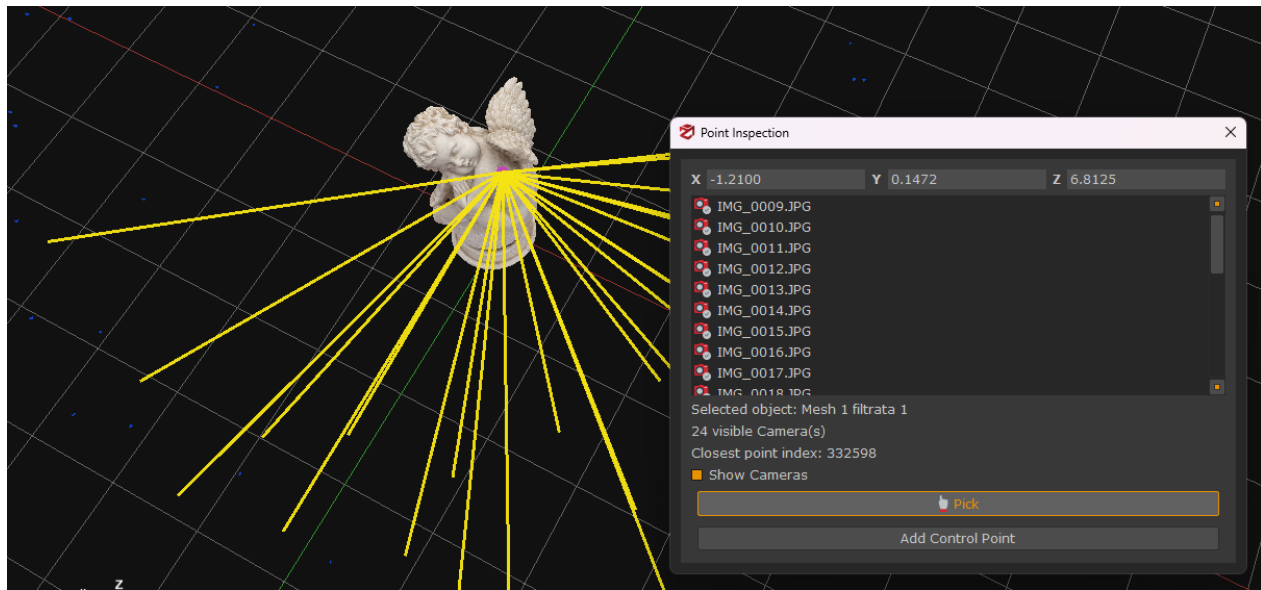


- **Camera Links:** they show the strength of the matches between the cameras during the orientation phase. A series of lines which link the cameras will be shown in the workspace according to a matching threshold defined by the user, while their degree of intensity is indicated through a color map.



- **Point Inspection:** this tool enables the user to pick a desired point upon your 3D

model. The cameras that see that specific point will be shown in the viewport and listed in the dedicated window, along with its XYZ position in the 3D space.



- **Camera GPS Coordinates:** shows a preview of the GPS coordinates via OpenStreetMap.
- **Enable/Disable Confidence:** allows the user to see/hide information about the dense point cloud confidence.
- **Optimize camera parameters:** this tool allows running a further *bundle adjustment*, in order to improve the accuracy of the Structure from Motion algorithm. It is advisable to run this tool before running the Multi View Stereo phase (dense point cloud extraction).

Tip: a typical case in which the bundle adjustment step is required is when the first camera orientation step has completed with a mean reprojection error value above 1: after placing at least three control points from the images it is possible to run the "optimize camera parameters" step, giving much more weight to the defined constraints.

- **Optimize camera parameters using terrain assumption (experimental)**

This tool allows the user to run the bundle adjustment, however by assuming a terrain. This is very useful when the structure from motion suffers from error drifting and causes the reconstruction to look "bent". By using this tool, Zephyr will guide the reconstruction using a planar assumption.

- **Manage camera layers:** manage multi-layers for multi-layers datasets.

Tools - Selection

The "Selection" menu allows the user to apply certain functions to the workspace elements - most of these commands have a direct quick button on the main toolbar. These tools have the same effect as those in the [editing panel](#).

Select All: selects all the currently active items in the workspace - triangles for meshes,

points for clouds. The selected part will be highlighted by a red color.

Select None: Undo the previous selection of all the active items in the workspace.

Invert Selection: invert the previously done selection. The selected part will be highlighted by a red color.

Delete Selected Items: deletes those elements currently selected (highlighted in red) from the currently active object.

Manual Selection: allows to select points (for sparse clouds and dense clouds) or triangles (for mesh and textured mesh) through different selection modes (rectangle, polygon, ellipse, lasso, box). By choosing the desired mode and the desired elements in the 3D space, it will be possible to combine them using the appropriate action (add, remove and by using the pause button to freely move in the workspace). All the selected elements will be highlighted in red.

Select by Color: selects (on dense point clouds) all the points of a given color (within a given threshold).

Select by Plane: selects a part of the currently active subject - the selection is done by placing a plane that will "cut" the subject - all points above that plane will be selected. The selected part will be highlighted with a red color.

Select by Points: allows selection of a part of the currently active object in the workspace - the selection is made by including all the points contained within a dragged rectangle in the workspace (keeping the left-click button pressed) - when the click is released, the selection will be done. The selected part will be highlighted with a red color.

Method Statistics X84: The algorithm selects those points whose density doesn't meet the X84 statistic criteria.

It calculates which are the nearest points (neighbours) or not useful ones (outliers) to remove those too far from the correct solution. For each individual point in the cloud, the algorithm finds the nearest "neighbor" point (defined by the neighbors parameter) and calculates its distance. The set of calculated distances is processed through the statistical rule X84. The filter considers points that fall within a certain deviation as valid and classifies those that fall within the "tails" of the distribution as outliers to be removed.

The parameters:

- *Neighbors*: Defines which neighbor points to consider for distance calculation, influencing sensitivity to local density.
- *Scale*: it's the scale, or "tolerance" of the X84 filter.
 - > High Scale: The filter is more tolerant. Fewer points are removed.
 - > Low Scale: The filter is more aggressive. More points are considered outliers and eliminated.

Select by Triangle: allows selection of a part of the currently active object in the workspace - the selection is made by including all the points contained within a polygon defined by clicking and connecting the polygon points in the workspace - when the

polygon is closed, the selected part will be highlighted by a red color.

Select Cameras: allows selections of the workspace cameras through different selection modes (rectangle, polygon, ellipse, lasso). Once selected, the cameras will be highlighted in orange both in the viewport and in the camera navigator.

New Object Via Copy: creates a new object in the workspace, by making a copy of the current selection.

New Object Via Cut: creates a new object in the workspace, by cutting the selected object. The inverse of the selection will become the origin object.

Tools - Point Cloud Filters

From this menu it's possible to apply the selected mesh filter to a dense point cloud in the workspace.

Decimation: select the desired point cloud with the dropdown menu and the number of desired points. The point cloud will be regenerated decimating the point count to the maximum specified value.

More specifically, it is possible to decimate the desired point cloud using these different methods:

- Maximum points count;
- Maximum points count with octree (the octree is a data structure which guarantees a more homogeneous distribution of the decimated points);
- Average point distance;
- Octree size.

Densification: select the desired point cloud with the dropdown menu and the number of desired points. The point cloud will be regenerated densifying the point count to the maximum specified value. Only structured point clouds can be densified.

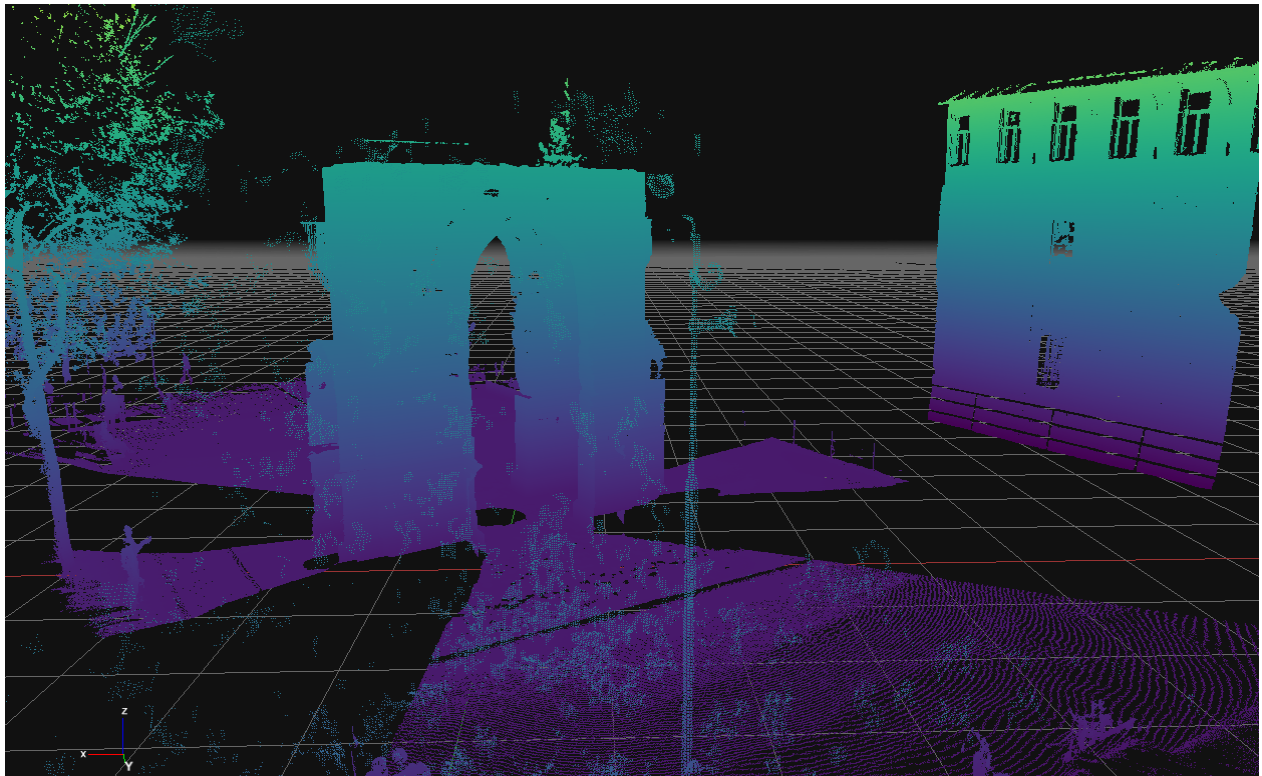
Project on Regular Grid: with this filter it's possible to use a regular grid as a projection for the dense point cloud, so that points are at a regular distance. You may define the grid spacing as well as the grid research value for the grid generation. This tool is especially useful for aerial datasets in topography.

Ground Extraction Filter: allows the automatic extraction of the terrain from a dense point cloud to create a 3D Digital Terrain Model (DTM) and eliminate everything above, such as trees and houses. Users can select the dense point cloud and set the following parameters:

- **Scene:** suggests filtering the type of scenario that has been reconstructed in 3D.
- **Resolution:** refers to the grid size of cloth that is used to cover the terrain. The bigger the resolution, the coarser the DTM.
- **Height threshold:** refers to a threshold to classify the point clouds into the ground and non-ground parts based on the distances between points and the simulated terrain.

Point cloud Classification: This tool automatically identifies different scene objects, allowing the user to choose from three categories: buildings, roads, and trees. It works ONLY with dense point clouds generated from aerial datasets and integrates the ground extraction filter, which is enabled by default. Once the process is complete, a new dense cloud for each selected object category will be added to the workspace.

Update Colors: This filter can be used either to recompute colors from images (useful when you are changing the workspace images) or by elevation (useful to colorize a laser scan cloud for example). If you choose the latter, a list of available color maps will be shown for selection.



Tools - Mesh Filters

From this menu it's possible to apply the selected mesh filter to a mesh in the workspace.

Decimation: allows selecting the referred mesh from the drop-down menu and setting the number of corresponding vertices. The mesh will be regenerated by decimating the number of vertices with the specified maximum value. You can ask the software to:

- ***Preserve the boundaries:*** with this option, the vertices borders are never decimated. Therefore, it will allow having an edge equal to the starting mesh; the disadvantage is that the border remains much denser at the inner part's expense, resulting in fewer points and less detail.
- ***Filter only selected triangles:*** with this option, you can decimate just the mesh areas previously selected with the selection tools.

Densification: select the reference mesh with the drop-down menu and the desired number of vertices. The mesh will be regenerated by densifying the number of vertices with the specified maximum value.

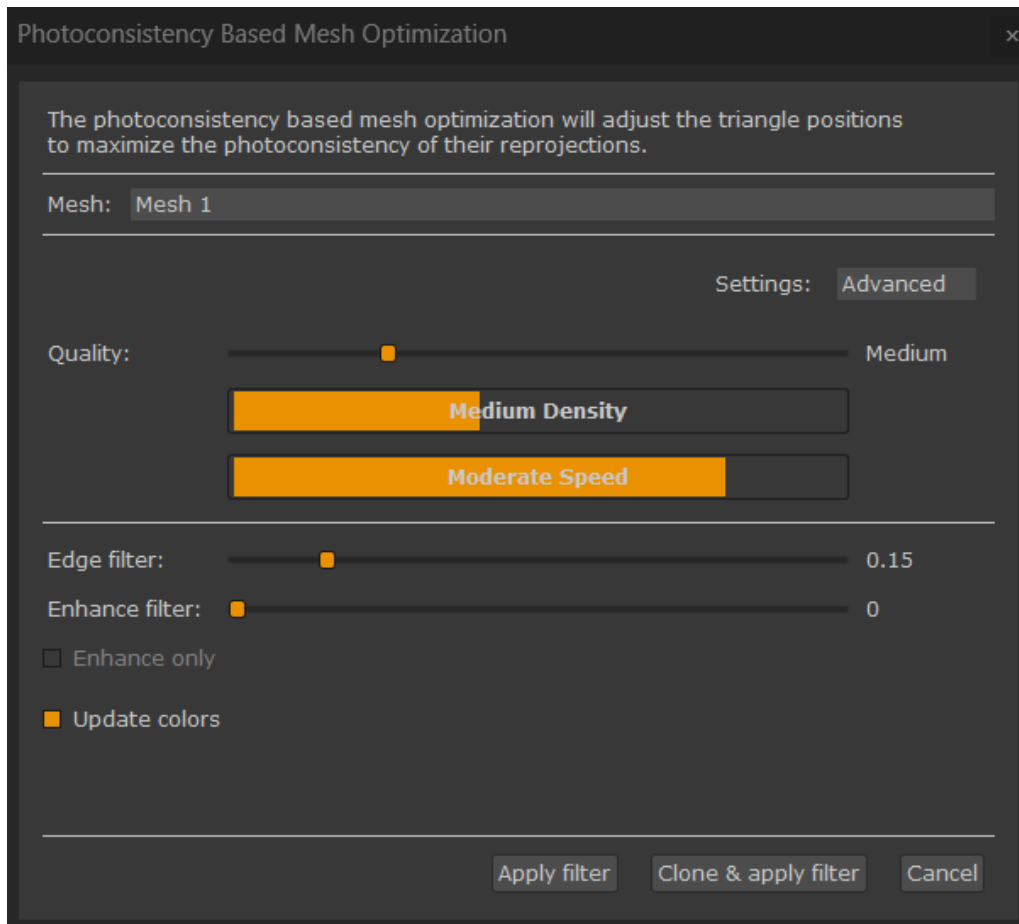
You can either apply the filter to the mesh you have selected or clone it and filter the mesh copy.

Retopology: This filter allows you to optimize the mesh topology. Triangles will be simplified and Zephyr will try to generate larger triangles where possible. The greater the optimization factor, the larger the size of the generated triangles. Please, note the filter may cause a loss of mesh detail, especially where there are geometries with well-defined edges.

Laplacian smoother: reduces the mesh noise and does not keep sharp edges. The more iterations are inserted, the more smooth the mesh will be. This filter is suitable for non-edged subjects (e.g., human body datasets).

Bilateral smoother: the filter allows to smooth selected mesh with the appropriate drop-down menu, and it reduces noise by improving and emphasizing edges where it is possible. This filter is suitable for architecture and construction scenarios.

Photoconsistency Based Optimization: this is a kind of filter that, based on photos, optimizes the surface of the model to make it as much consistent as possible with the starting images, through a minimization process, where at each iteration, the surface is modified in such a way as to reduce the error of reprojection of one image on the other. This allows obtaining a much more detailed rendering of the surface, thus increasing its accuracy.



Here below, a detailed analysis of how to change these settings; in brackets (), you will find the default values:

- **Quality:** determines the balance between processing time and result fidelity during the photoconsistency filtering. Higher-quality steps improve details and generate higher-density meshes but take longer, while lower steps are faster and generally more noise-resilient for low-quality datasets. You can choose between "Standard", "Medium", "High", "Ultra", and "Extreme" values by adjusting the dedicated slider.
- **Edge filter (0.15):** this parameter is used to emphasize edges; the more the mesh is angular (buildings, objects, etc.), the more you can increase this value. Usually, it can be kept at a value of 0.15.
- **Enhance filter (0):** it is a post-processing method that can generate “fake details” by increasing the number of mesh triangles. Depending on the result you want to obtain and the photo’s quality, you need to carefully adjust the slider to avoid creating additional noise instead of additional details.
- **Update colors:** calculate vertex colors according to cameras. It recalculates the colors each time after making the photoconsistency. The flag can disable for the test, and the colors can be recalculated later.

Ground Extraction Filter: allows the automatic extraction of the terrain from a mesh to

create a 3D Digital Terrain Model (DTM) and eliminate everything above, such as trees and houses. Users can select the mesh and set the following parameters:

- **Scene:** suggests filtering the type of scenario that has been reconstructed in 3D.
- **Resolution:** refers to the grid size of cloth that is used to cover the terrain. The bigger the resolution, the coarser the DTM.
- **Height threshold:** refers to a threshold to classify the point clouds into the ground and non-ground parts based on the distances between points and the simulated terrain.

The “**preview**” button will highlight the terrain elements as green and non-terrain elements as red. Optionally, you can use a selection to force non-terrain regions.

.Classification

The AI Classification tool automatically identifies and segments semantic categories within a 3D scene. Users can choose among three predefined classes: buildings, roads, and high vegetation (Trees). Please note that this tool is specifically designed to operate on dense point clouds and meshes generated from aerial datasets.

Update colors: this filter allows re-computing mesh colors:

- **From images:** (e.g., to change the workspace pictures if you are dealing with multispectral imagery).
- **By elevation:** it updates the colors according to the points' elevation. A list of color maps will allow you to pick among several color palettes.
- **By normals:** using normal maps from the dataset images.
- **Uniform:** choosing one specific color from a color palette.
- **By curvature:** different sets of colors can be applied according to the local geometry, which means the color varies depending on whether the area is flat, angular, or curved.

Fill Holes Selective or WaterTight: it allows to automatically fill and close holes in the meshes. There are two modes available:

- **WaterTight mode:** allows automatically filling all the holes at once.
- **Selective mode:** allows filling the holes manually in the selection window. You can select a specific hole by:
 - **Number:** choosing it directly in the 3D workspace with the **pick hole** button, or the corresponding number (the hole will be highlighted with an outline in the workspace).
 - **Size:** defining the size threshold using the dedicated slider.

The color of the triangles that will close the hole will most likely be wrong when the missing visibility of the point from the camera will behave in a degenerated way (and it is impossible to identify the color of something that is not seen by any picture).

The **Selective** mode allows you to close single holes faster, but it may not work for complex cases, which we recommend using the **WaterTight** mode.

Cut with bounding box: by changing the bounding box's size created by the mesh, it can be adjusted to cut unnecessary parts and exclude them outside the bounding box.

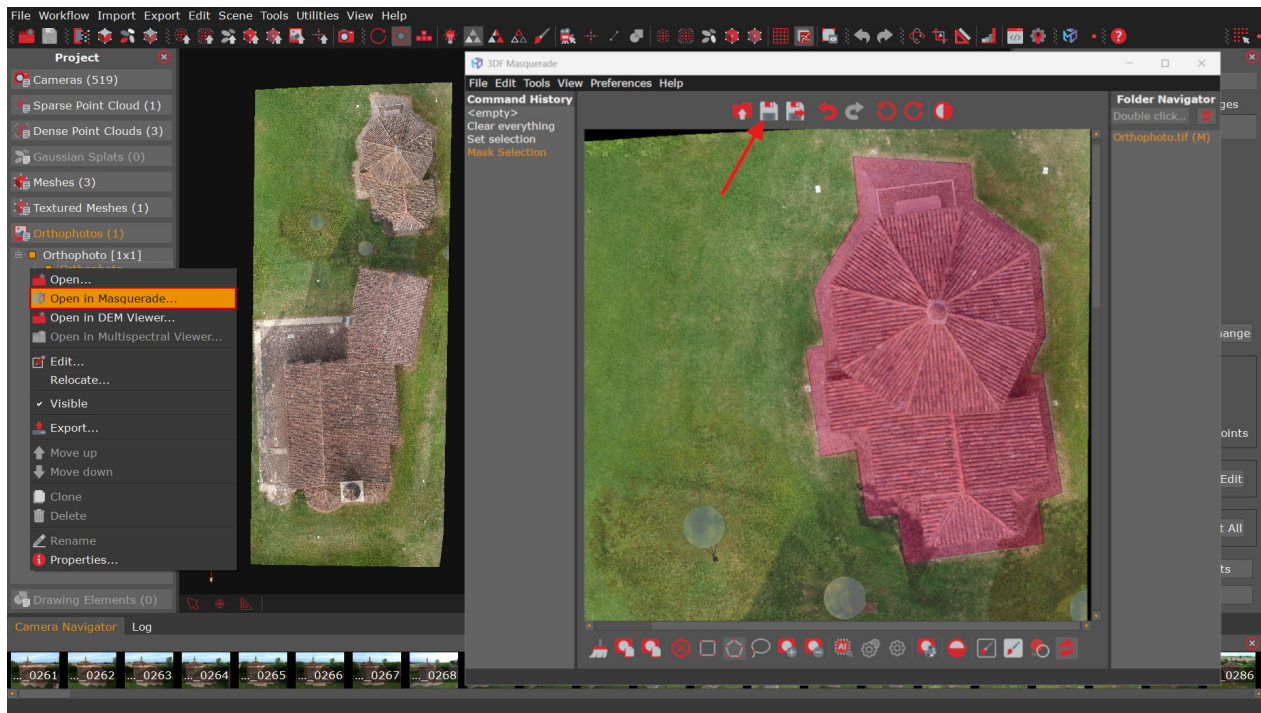
Cut with plane: this function allows you to cut the mesh sharply with a plane, regenerating the triangles on the edge where cut.

Cut with Orthophoto and Masks: The orthophoto generated from a mesh can be loaded directly into the Masquerade tool, where you can apply masks and use them to cut out portions of the mesh based on the orthophoto.

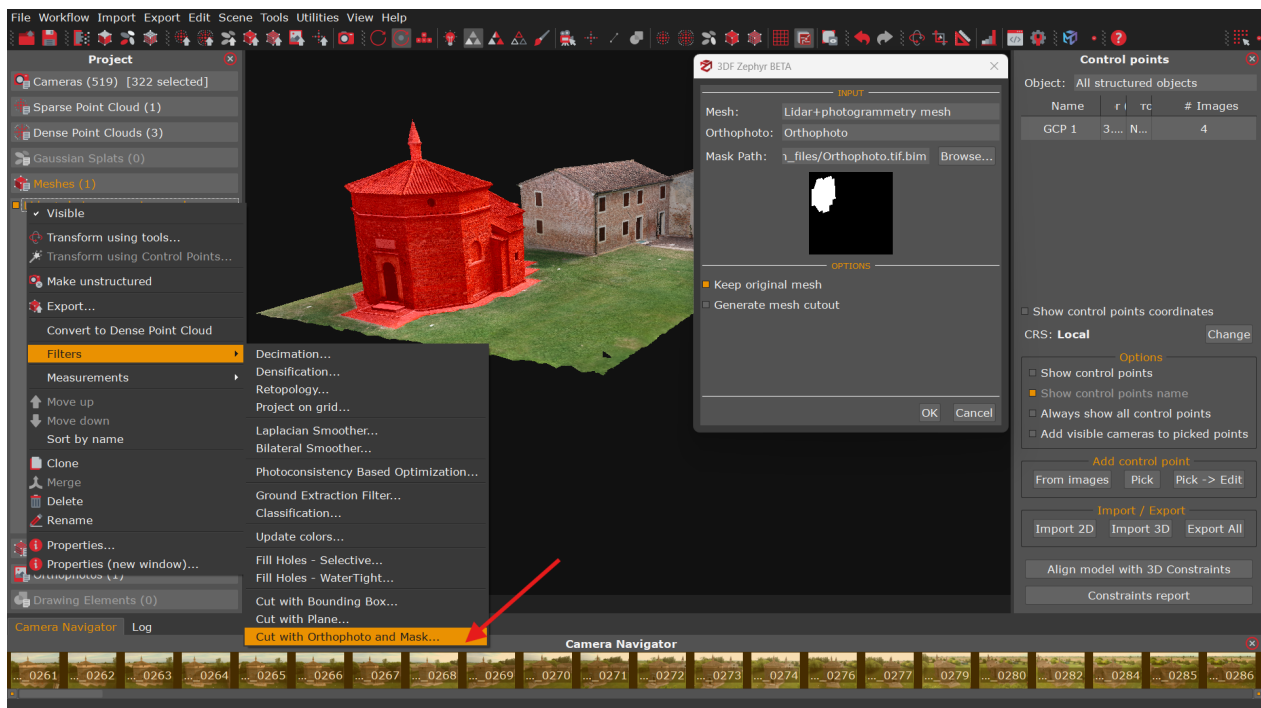
To start the workflow, right-click on the orthophoto and select the '**Open in Masquerade**' option. In the **Masquerade** tool, you can mask the desired portion of the



mesh to be cut, then save the result



Right-click on the mesh and from: **Filters > Cut with Orthophoto and Masks** open the tool dialog.



Enable the "Keep Original Mesh" and "Generate Mesh Cutout" options if needed, then click "OK". All mesh cutouts will be available in the **Mesh** section of the **Project** panel.

Classification

The **AI Classification** tool automatically identifies and segments semantic categories

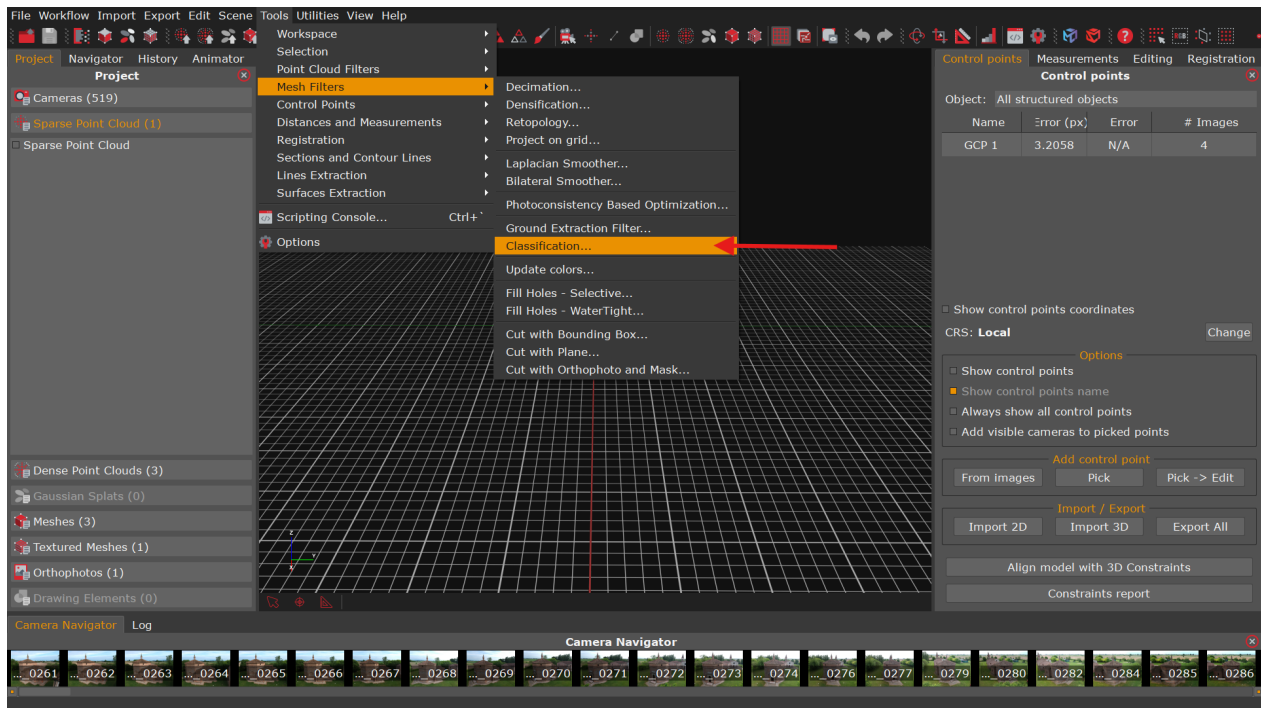
within a 3D scene. Users can choose among three predefined classes: *buildings*, *roads*, and *trees*. Please note that this tool is specifically designed to operate on dense point clouds and meshes generated from aerial datasets.

The **Classification** process internally includes the **Ground Extraction filter**, which is enabled by default to improve terrain separation during object segmentation.

Upon completion, 3DF Zephyr will automatically generate and append new 3D model layers for each enabled category in the **Project** tab. This allows users to efficiently visualize, manage, and export classified data within the workspace.

Note: 3DF Zephyr will download the required machine learning models during the initial use. Therefore, an internet connection is necessary.

The **Classification** tool can be launched from the **Tools > Mesh filters > Classification** menu.



Once opened, the **Object Classification** window displays the following configuration sections:

Object Classification

Select the input object and the categories to classify. Classifications models are automatically updated from the internet.

INPUT

Target Object: photogrammetry point cloud

CATEGORIES

☒	Buildings	Buildings	
☒	Roads	Roads	
☒	Trees	Trees	

Model Manager

OPTIONS

☐ Use Ground Extraction Filter

Complex scene

Resolution: 0.119464

Height threshold: 0.014933

ADVANCED

Min. Cameras per Category: 3

Min. Points per Category: 100

OUTPUT

☒ Create a new object for each category

☒ Color output

Accept Preview

- **Input section:** Selects the **Target object** from the list of available point clouds or meshes to be processed.
- **Category section:** This section allows users to enable or disable individual object classes for extraction. The first column lets you assign a custom classification model to each class. The second column allows you to assign a custom display color by clicking on the respective color option.
- **Model Manager:** Allows you to manage the AI classification models used in the tool.
- **Options section:** This section contains the **Ground Extraction parameters**, which

are active by default but can be disabled if desired.

- **Advanced section:** This section provides control over filtering thresholds for classification, increasing either value reduces noise and discards smaller, less reliable segments:
 - **Min. cameras per category:** Sets the minimum number of camera observations required for a point to be considered valid for classification.
 - **Min. points per category:** Defines the minimum number of points needed for a class to be retained in the output.
- **Output section:** This section provides options for managing classification outputs:
 - **Create new object for each category:** When enabled, Zephyr will generate separate objects for each selected class.
 - **Generate color output:** Optionally generates a colorized version of the classified result for visual inspection.

Clicking the “**Preview**” button will visualize the classification results within the 3D workspace, allowing the user to double-check the parameter settings before final processing.

Tools - Control points and Distances

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This menu allows access to certain control points tools.

Scale Model: it opens the same window shown in the "GCP" tab by clicking on "Align model with 3D Constraints".

Show constraints report: it opens the same window shown in the "GCP" tab by clicking on "Constraints report".

Show Alignment Info: shows information about the latest "Align model with 3D Constraints" operation, with the final mean error and the error of every constraint.

Change Reference System: allows change of the reference system of the project. You must have already defined the reference system with control points before you can change the reference system.

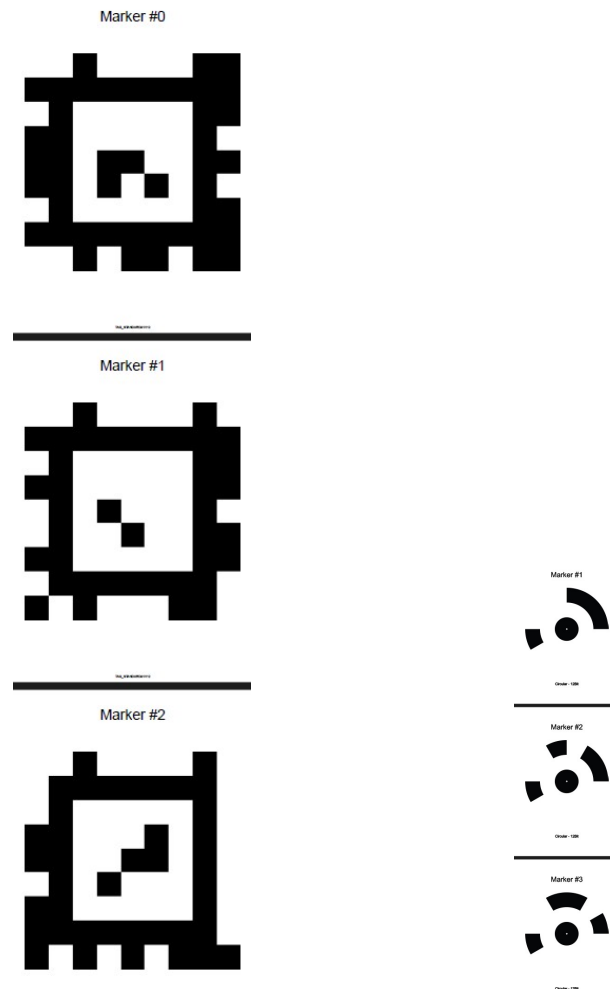
Import & Export 2D / 3D Coordinates: these functions are the same shown in the

"GCP" tab, under the "Import / Export" section.

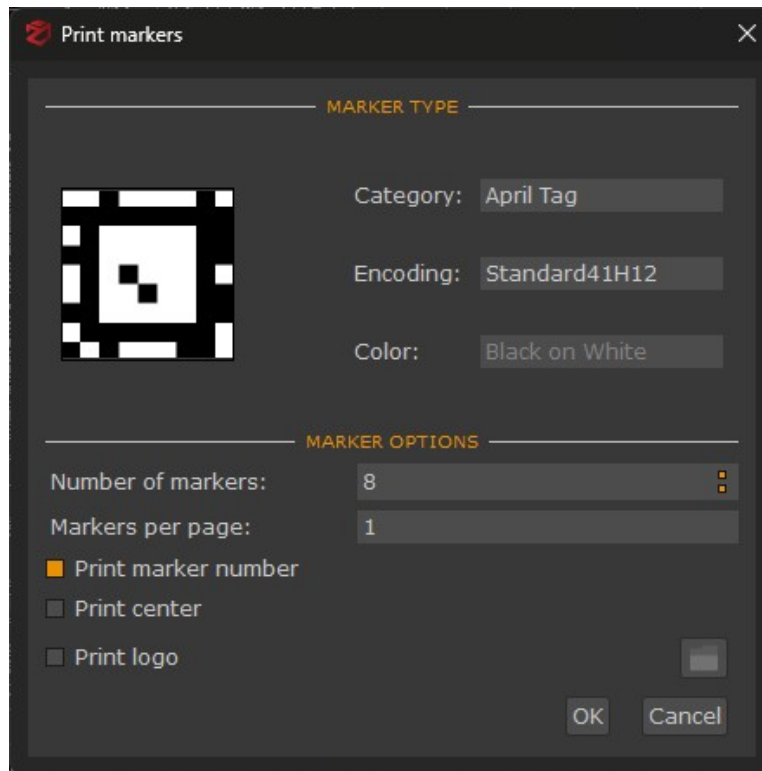
[Print Markers and markers use](#)

This chapter explains how to use coded targets in 3DF Zephyr in order to further improve the camera orientation phase.

3DF Zephyr's coded targets are of different types and shapes (see image below).



Coded targets can be printed by clicking **Tools > Control points > Print Markers**. Additional options are available, such as "print logo", "print (target) center", and "print marker number".



3DF Zephyr supports 16 bit coded targets, and the printing size strictly depends on the scene/subject features.

Recommended settings are as follows:

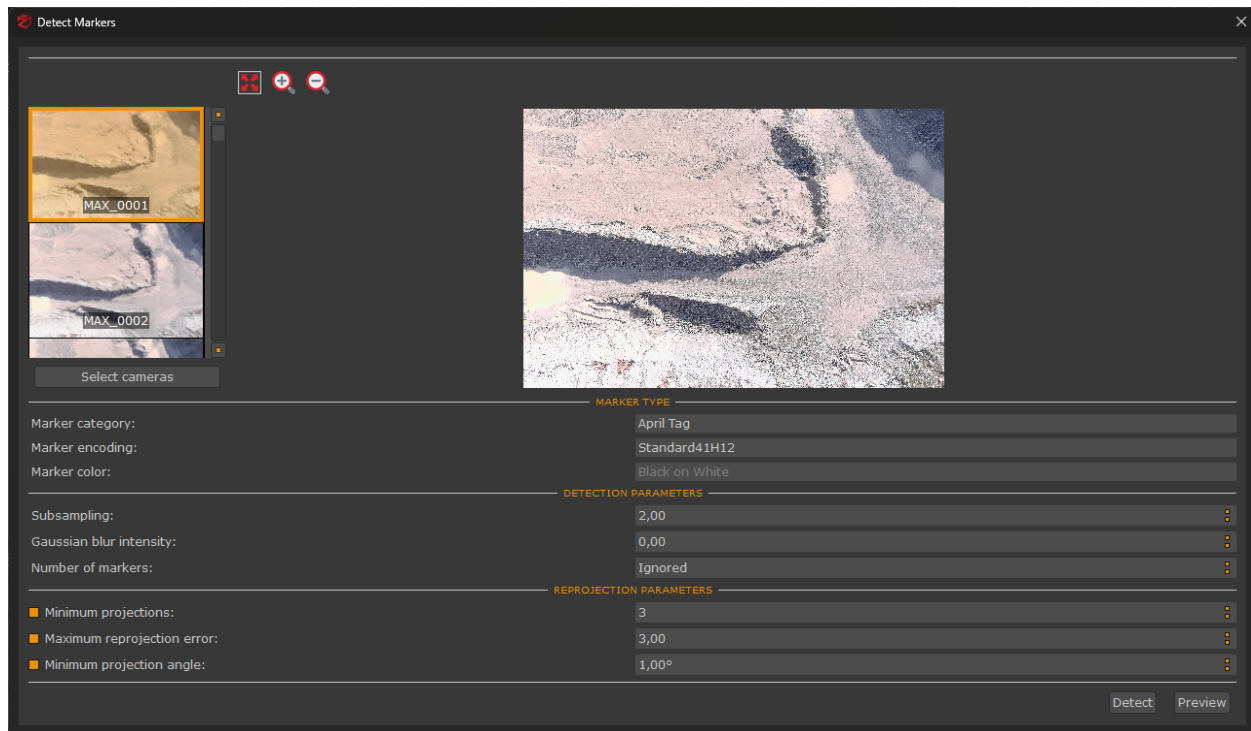
General and Human Body	4 targets per sheet (A4 size)
Urban	2 targets per sheet (A4 size)
Aerial	1 target per sheet (A4 or A3 size)

You can define the number of targets per sheet by editing the printing menu settings on Windows (in that menu, the term “page” refers to a target).

It is recommended NOT to use coded targets randomly; instead, they should be used in their numerical sequence (1, 2, 3, 4, etc., and not 4, 13, 22, etc.).

With 3DF Zephyr, you can also automatically detect standard targets, including square, circular, or custom ones.

Once the image capture is complete and the camera orientation phase is finished, you can start the automatic detection of coded targets by clicking on **Tools > Control Points > Detect Markers**.



In the new window, you need to specify:

- The marker category, encoding and color: select which markers have been used on-site.
- Subsampling [1.0 - 10.0]: the detection is performed on a subset of pixels of the original image, can be seen as shrinking the original image by the provided subsampling factor prior to the detection. As an example, a subsampling of 2.0 will rescale a 100x100 pixel image to a 50x50 pixel image. Higher subsampling will speed up the detection considerably, but might give worse results.
- Gaussian blur intensity [-0.5 - 0.5]: blurs the original image prior to the detection, may aid the detection in case of noisy images. The higher the blur value, the more the original image gets blurred. Negative values act as a sharpening filter instead, increasing contrast along edges.
- Number of markers: markers with ID's higher then the "number of markers" are ignored. This is useful to reduce the number of false positives when the maximum ID of the marker is already known. As an example, setting the "number of markers" to 4, will allow for the detections of markers 0 to 4, avoiding to detect any marker with ID higher than 4.
- Minimum projections [2 - 10]: minimum amount of times a marker needs to appear in each image before being considered a valid marker. This value should be lowered if markers are not being detected, should be increased in case of many false positives.
- Maximum reprojection error [0.0 px - 10.0 px]: markers whose estimated 3D position is inconsistent between different images are ignored. This value should be lowered when not many markers are detected, should be increased when marker position precision is a priority.
- Minimum projection angle [deg] Markers from images that are too "aligned" with each

other (not enough angular diversity) are removed to avoid errors during triangulation, keeping only those with sufficiently different viewpoints.

After clicking the **"Detect"** button, 3DF Zephyr will start the automatic target detection and will set the control points based on the detected targets.

Tools - Distances and Measurements

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

This menu allows access to the most used Distance and Measurement tools already present in the [Measures panel](#).

Area: allows to compute the area of a given mesh.

Volume: allows to compute the mesh volume. If the mesh is not completely closed, all holes will be automatically filled and later shown with a red color.

Volume with Projection: allows calculation of the volume of a mesh or a point cloud by considering the points distance and the position of a plane chosen by the user. Points under the plane are not considered, while those above are projected on the plane's surface.

Hollow Volume: allows calculation of the volume of a cloud/mesh when the photographic survey has been carried out from the inside of the acquired object itself, as in the case of a room or a tank.

Angles: when at least three control points have been selected, you can compute the angle between control points. The interface of the window that will appear will allow you to set control points as A,B and C and then compute the angles between the vectors BA and BC. A checkbox will allow you to change the output to radians or degrees.

Quick Measurements: this function is also present on the toolbar with the icon



and it allows to quickly pick and measure directly in the 3D space. This tool allows also for measuring the horizontal, elevation and inclination of a segment.

Tools - Registration

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The **Registration** menu allows the user to handle point clouds registration. From this menu you can access to the:

Point cloud registration (ICP)

The **Iterative Closest Point (ICP)** function is an algorithm that minimizes the geometric difference between two point clouds, and generates a point cloud difference report as output.

This tool can be used to align a laser scanned point cloud with a photogrammetric point cloud, accounting for translation, rotation, and scale. Once aligned, the laser scan can be further processed, for example, structured and colored using the photogrammetric point cloud.

Note: If the point clouds are still too far apart, the **Gizmo**  tool, allows to manually bring them closer together before proceeding with another ICP iteration.

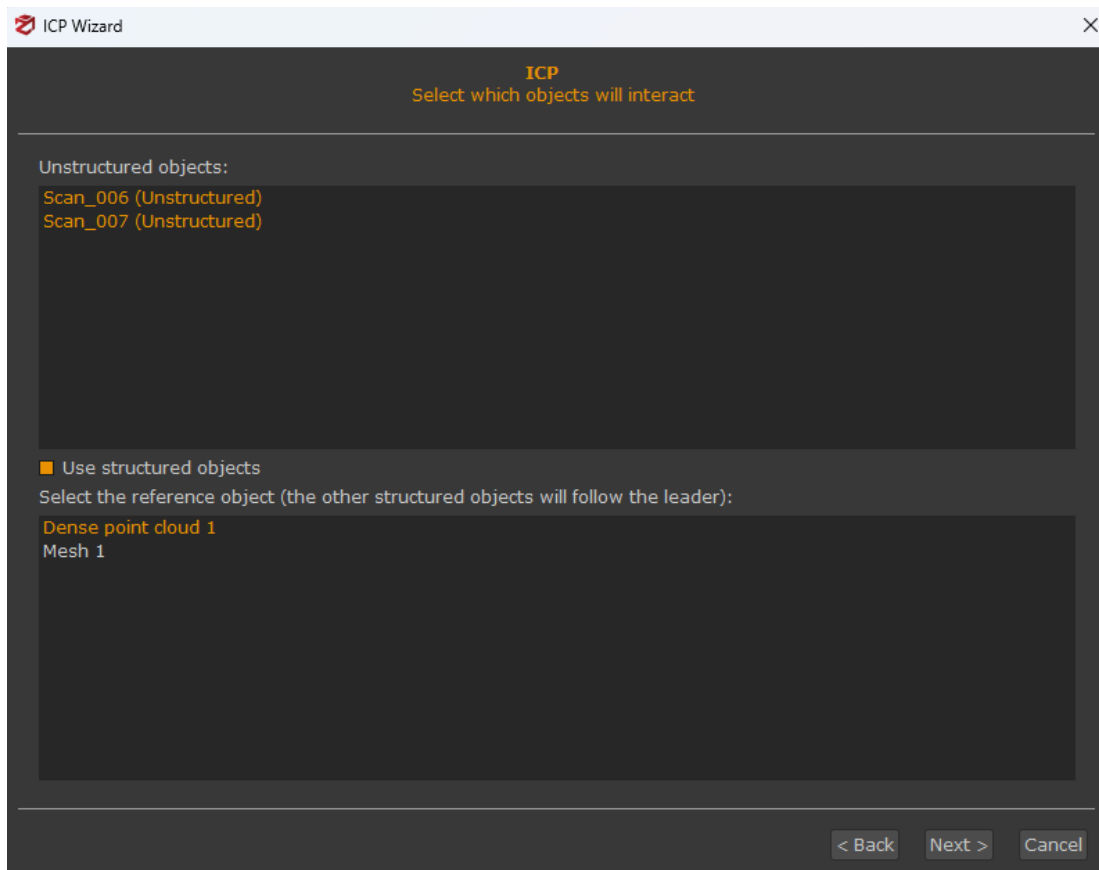
Multi view point cloud bundle adjustment (Multi ICP)

Use this tool is advised when you dealing with many point clouds that are already in the correct scale system, for example multiple scans from a laser scanner device. This function does not apply any scale factor.

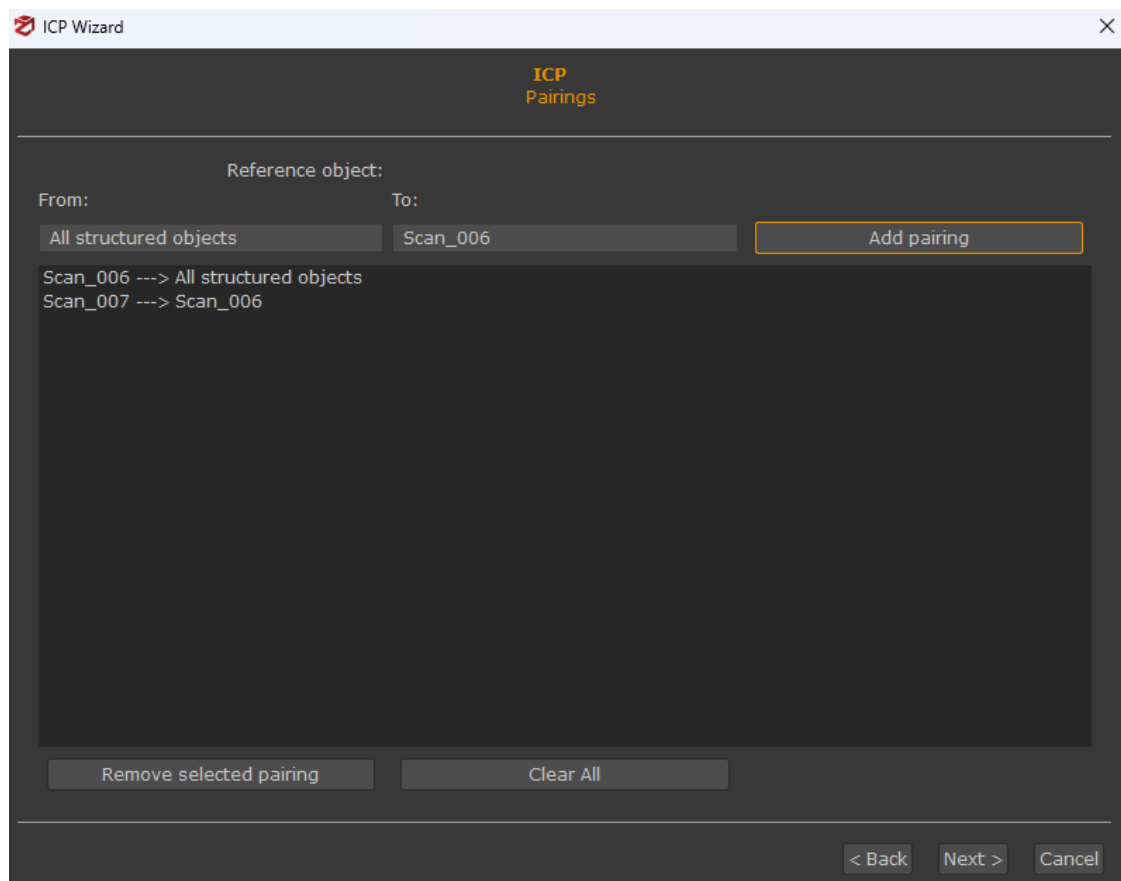
Please remember that:

- The objects must be close to each other
- You can use this tool to register multiple unstructured objects and structured ones
- The adjustment and the minimization will be performed in a global way
- If you need to register point sets with different scales, it is advisable to use the two view ICP dialog and enable scaling.

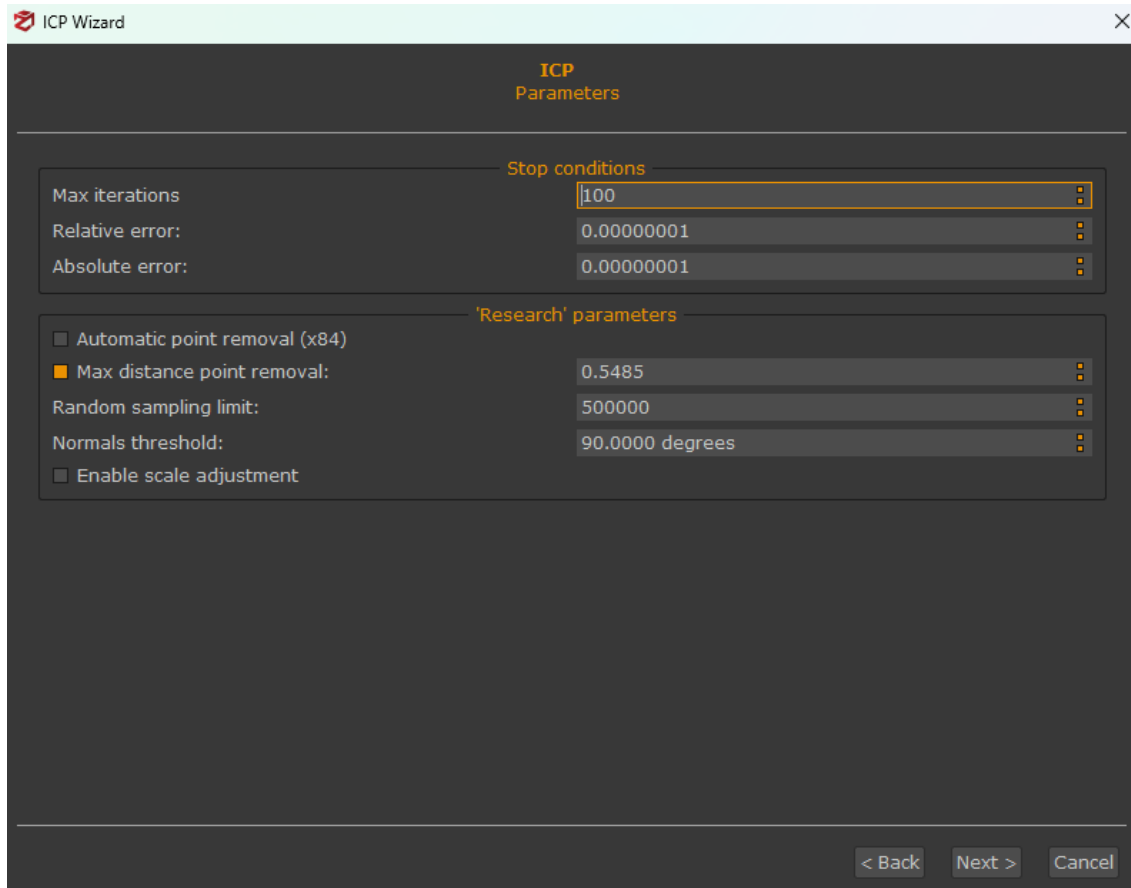
The first wizard page will ask which objects will interact:



The next page will allow the selection of the reference object. Then, you will be able to define the object pairings:



In most cases, pairings should not be changed as they should be automatically selected so no other interaction from the user is requested. Finally, you can define the stop conditions before you are shown a recap page where you can start the actual computation.



A summary of the set parameters will be displayed, and then procedure can be started by pressing the **Start** button."

Max distance point removal: when two or more point clouds are registered using the ICP algorithm, the corresponding points are calculated at each iteration by the algorithm itself.

Since it often occurs that point clouds depict different areas of a certain object/scene, a procedure to remove too far corresponding points needs to be applied. Indeed, the registration process would lead to a wrong result without that removal step.

The removal threshold can be calculated:

- **automatically** (X84 statistical analysis between point distances);
- **manually** (user is requested to set a metric value);

Point cloud comparison

This function allows computation of a comparison between two selected point clouds. A

chart is then plotted that graphically explains the residuals as a histogram. You can notice the errors recap on the bottom of the window (mean error and variance). Users should run this tool after the two clouds have been aligned to each other. Cloud comparison parameter settings are as follows:

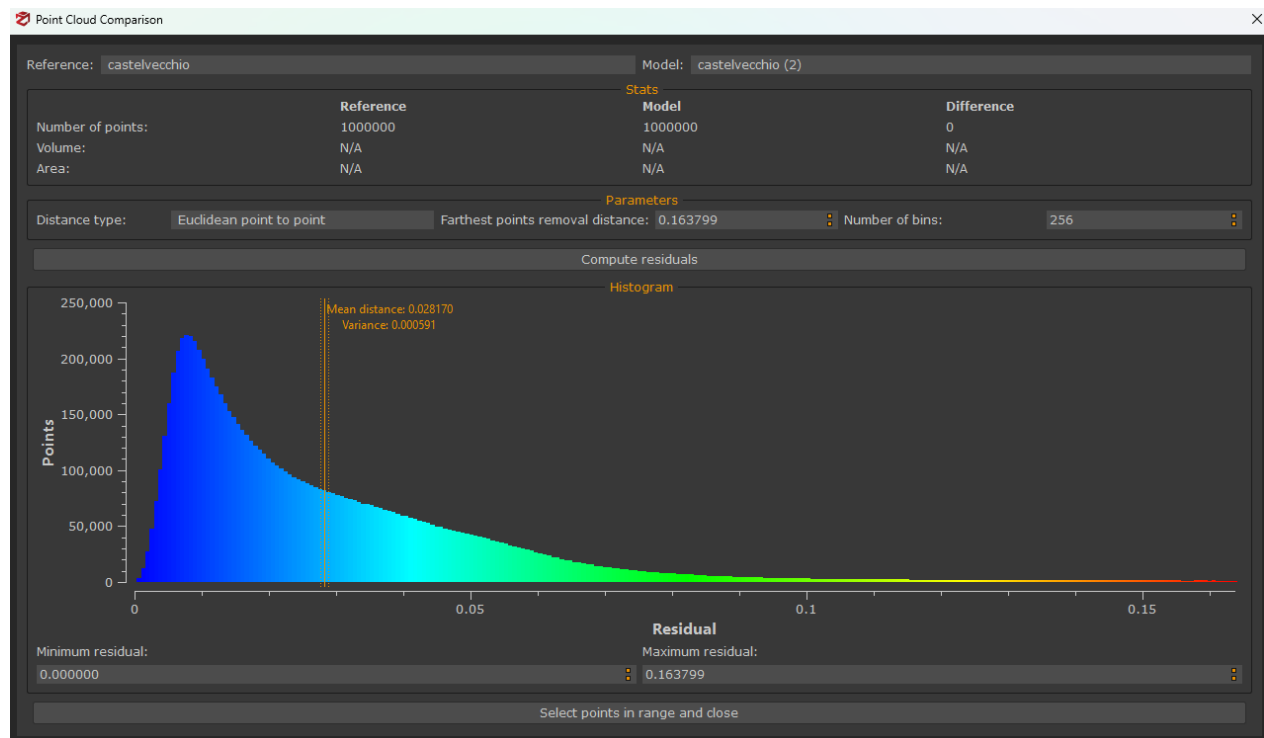
- **Distance type:** indicates the distance to be calculated and users can choose either "point to point" or "plane to point" distance;
- **Farthest points removal distance:** represents the highest value during the histogram computation;
- **Number of Bins:** defines the histogram amount of columns;

As for the residuals computation process:

- The first step computes the closest point of the model for every point of the target;
- If a distance between a couple of points is greater than the maximum distance value, that distance won't be considered into the computation;

It is also possible to select parts of the histogram to highlight only a certain number of points of the "model" point cloud directly in the 3D room.

In the 'Point to point' comparison the histogram is built by considering the closest point A for each point B. All the spatial distances are from A to B are used to build the histogram and color the point cloud accordingly. The 'Plane' metric is a bit different. In this case a plane is fitted considering B and its neighbors. The distance is then calculated from A to the fitted plane. The latter is useful with buildings and walls.



Match objects center

This tool is useful when a photogrammetric dense point cloud has already been created and a laser scan is then imported into the project. In some cases, the scan may have been acquired in a different coordinate reference system than the photogrammetric dense point cloud, causing it to appear displaced or entirely invisible in Zephyr's 3D workspace.

The **Match Objects Center** tool resolves this by repositioning the imported scan so that its center aligns with that of an existing structured object, typically the photogrammetric dense point cloud, making both datasets visible and spatially close to one another.

Control points registration

Ground Control Points (GCPs) can be used to pre-align a photogrammetric point cloud with a laser scan point cloud.

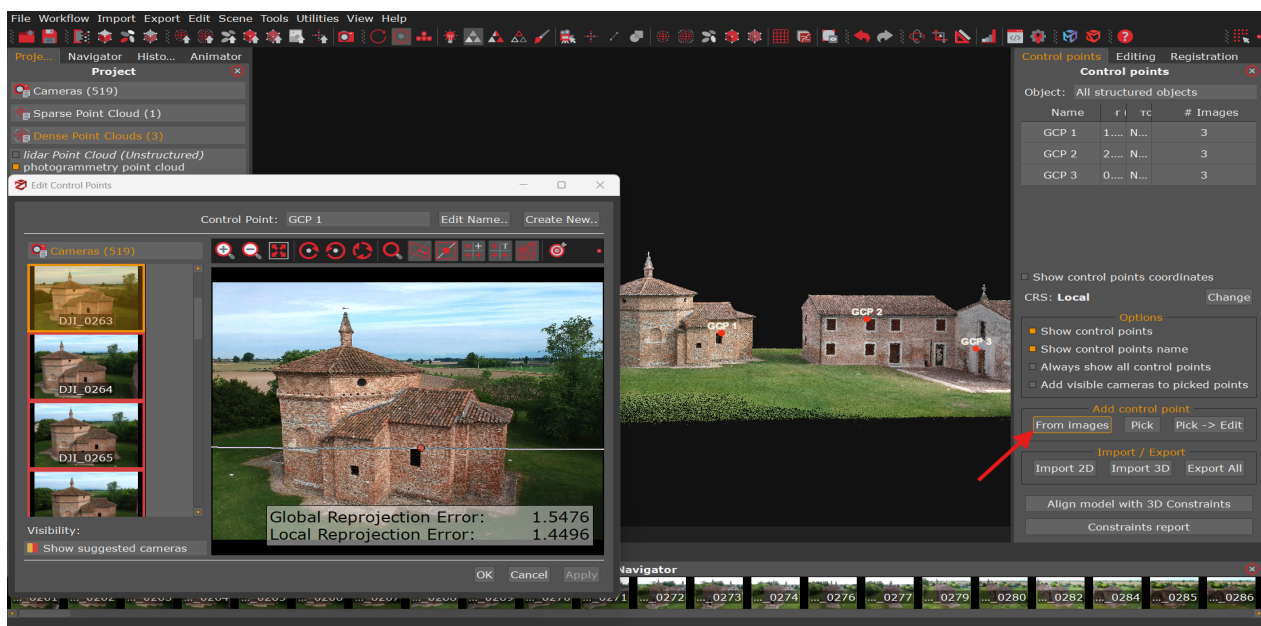
After importing the laser scan, the workflow requires placing at least three control points on the first point cloud, then identifying and applying the same control points on the second.

Depending on the workflow, you may choose to move either the photogrammetric or the laser scan point cloud, the procedure is the same in both cases.

When choosing control point locations, keep the following guidelines in mind:

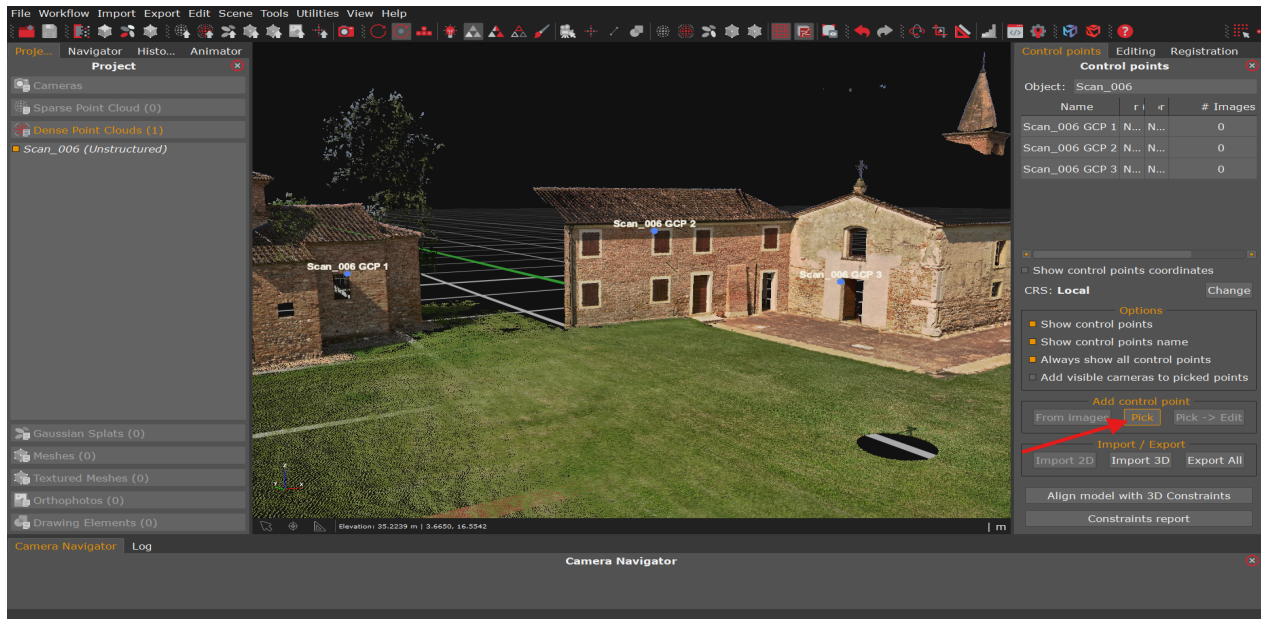
- Use well-defined features such as edges or corners, which can be easily and consistently identified across both point clouds.
- Distribute points across all three axes (X, Y, Z) to ensure a robust and accurate alignment.

*Note: control points are grouped by **Object** (photogrammetric point cloud/laser scan) in the "Control points" panel.*



For the photogrammetric dense point cloud, adding GCPs with the **"From Images"** tool is

recommended for greater accuracy.



When working with an unstructured laser scan, GCPs can be picked directly in the 3D view using the "**Pick**" command.

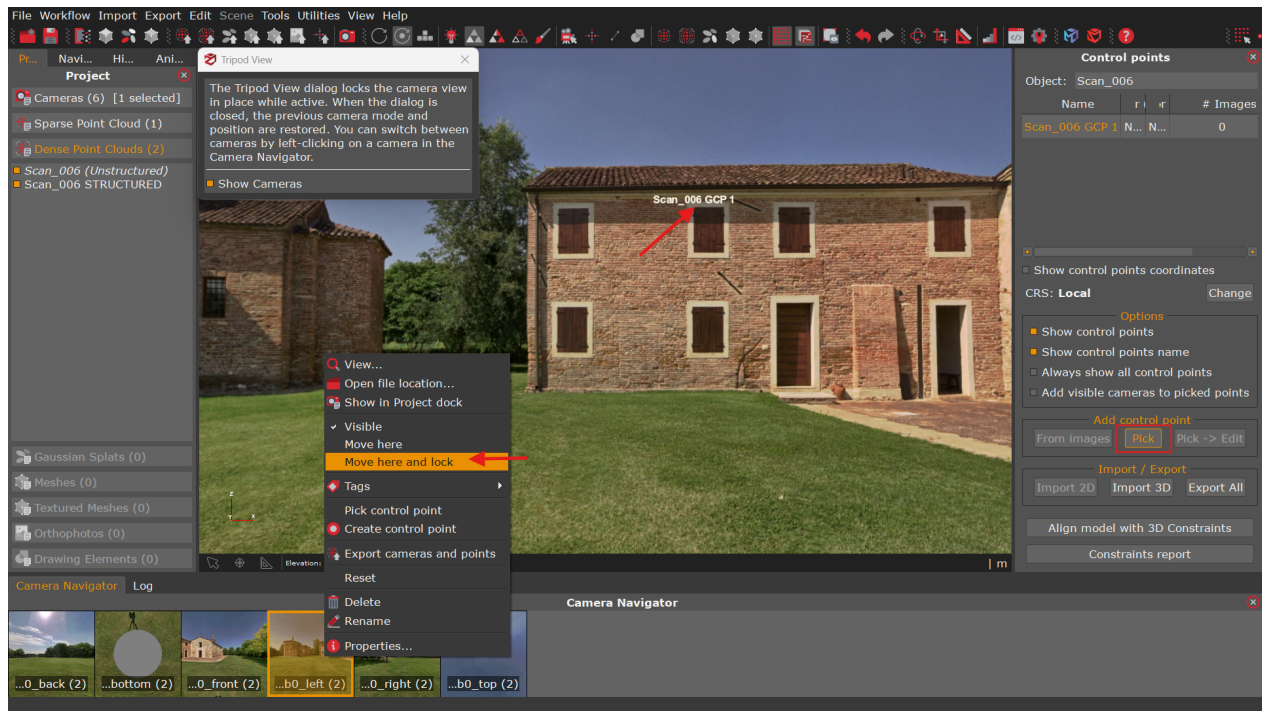
Use the Tripod View to define Control Points

If bubble view data is available in the imported scans, it is possible to structure the scans (see the **Structuring Laser Scan** section.) first and then use the bubble view to place **Ground Control Points (GCPs)** more accurately.

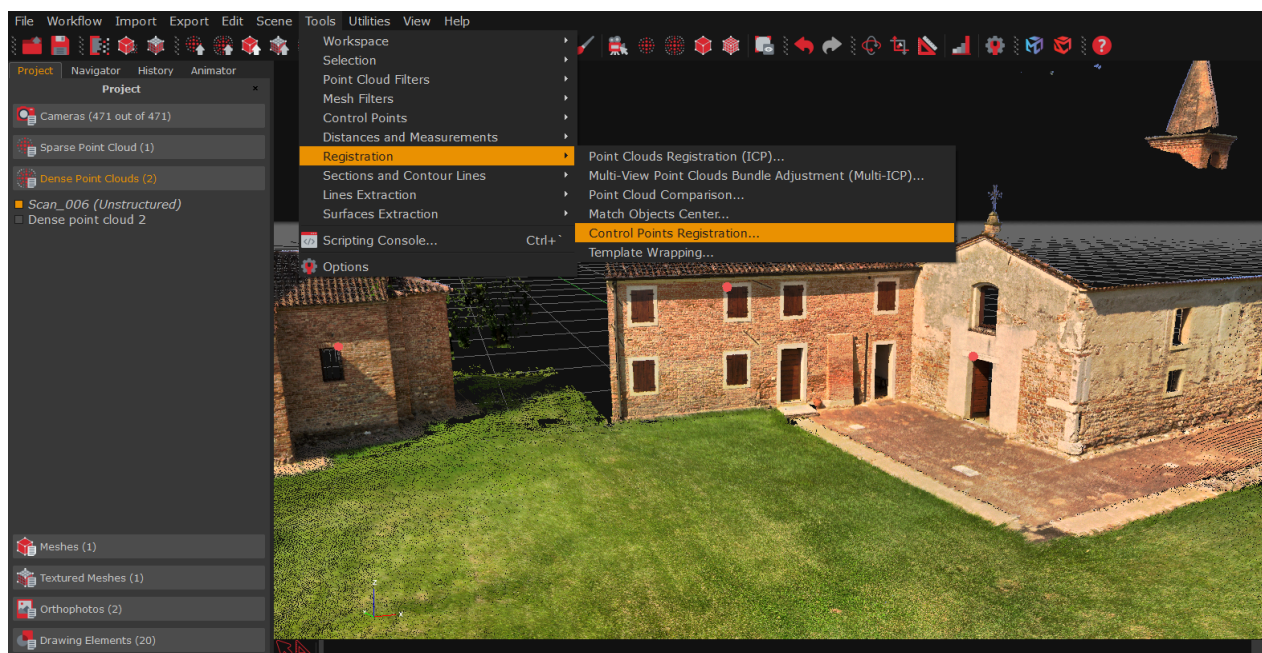
In the **Camera Navigator**, select the desired image, then press **Right-click** to display the "**Move Here and Lock**" option.

The **Tripod View** dialog locks the camera view in place while it is active. When the dialog is closed, the previous camera mode and position are restored. To switch between cameras, left-click on the desired camera in the **Camera Navigator**.

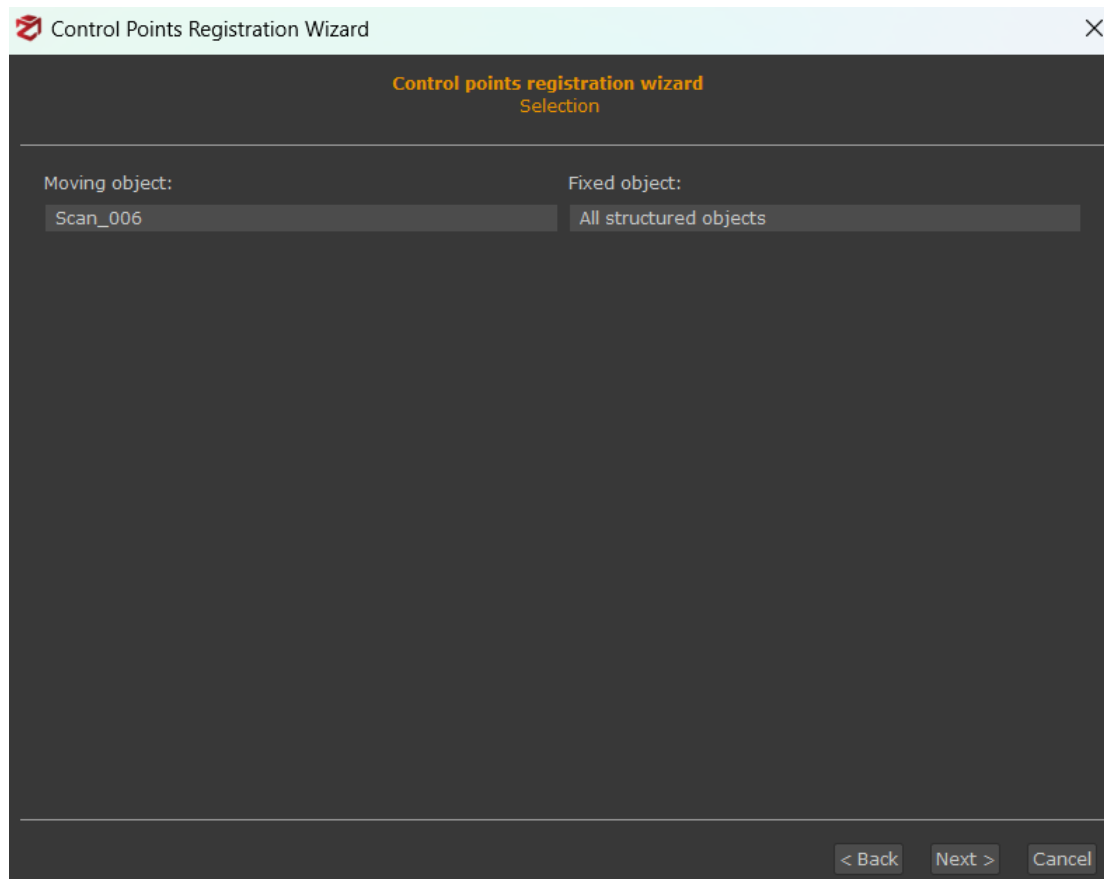
In the **Control Point panel**, **GCPs** can be picked directly on the Tripod View by enabling the "**Pick**" button.



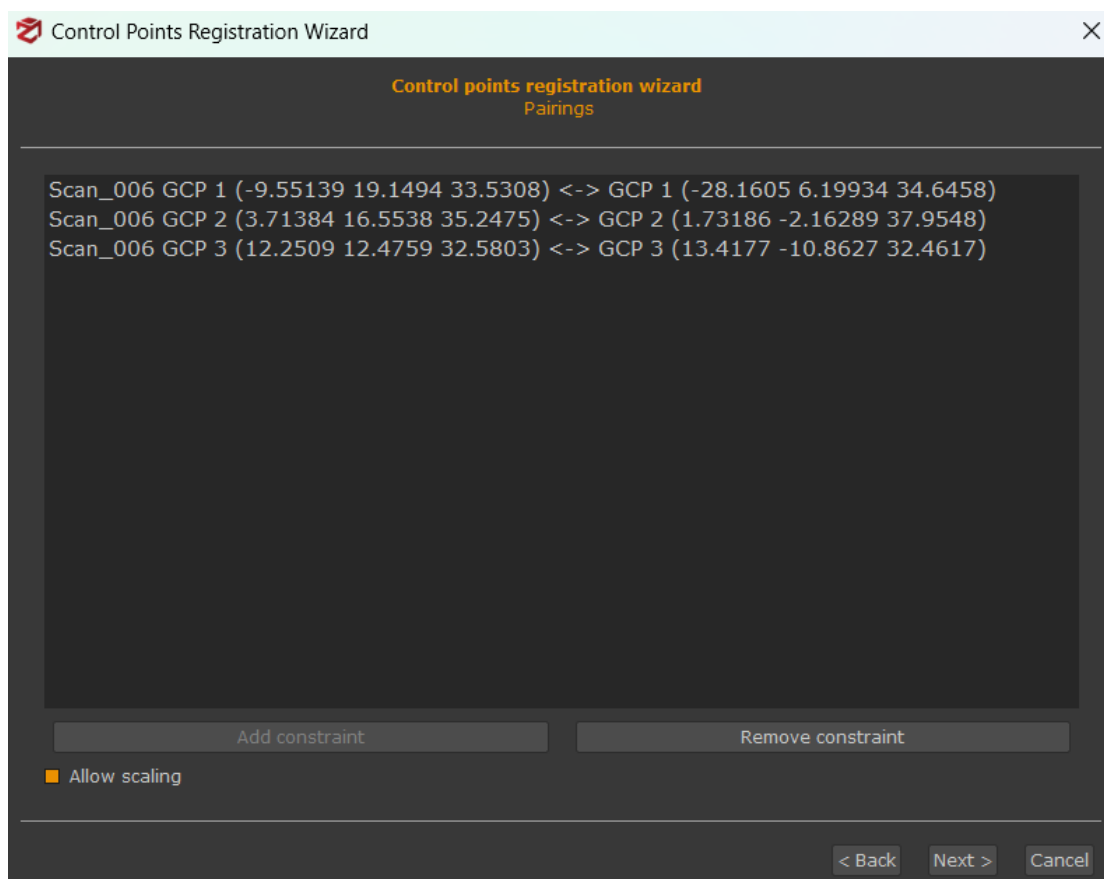
When all the control points have been placed, simply select **Tools > Registration > Control points registration** from the menu.



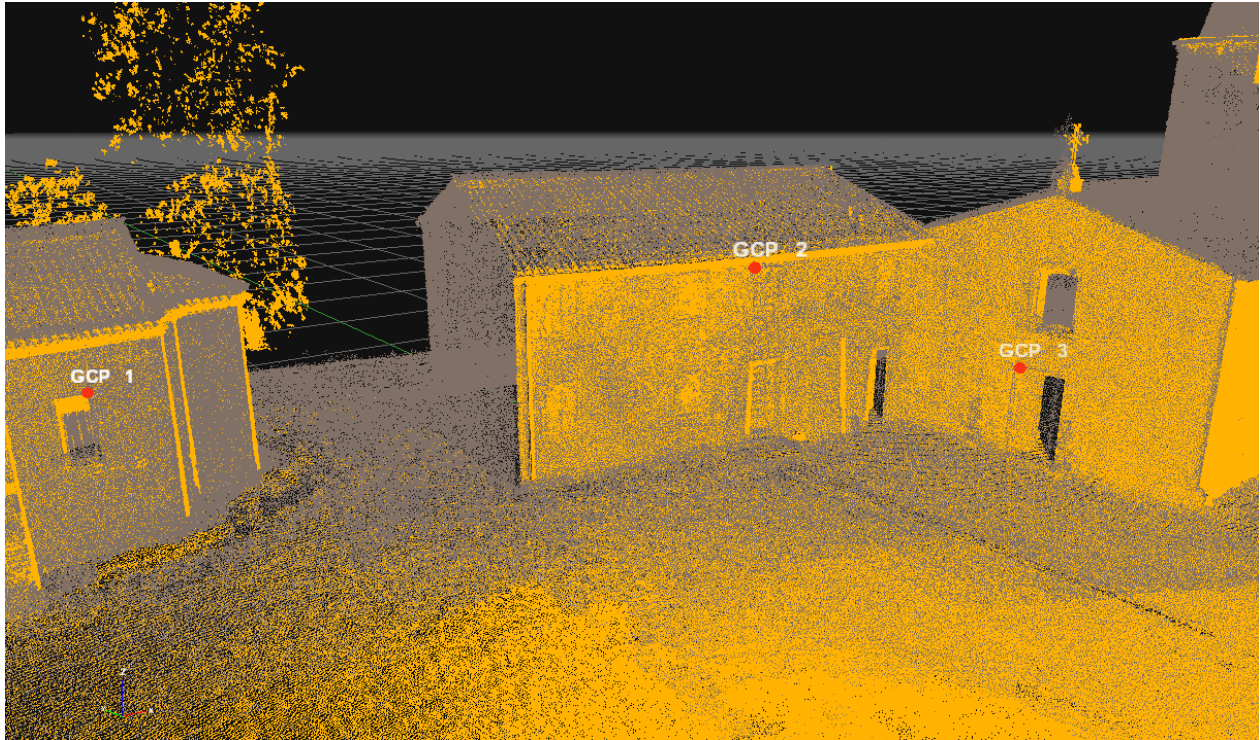
Select which object will move and which one will stay in its position.



Use the “**Add Constraint**” button to select the pairings, according to your naming convention that you used earlier. At least three constraints are required.



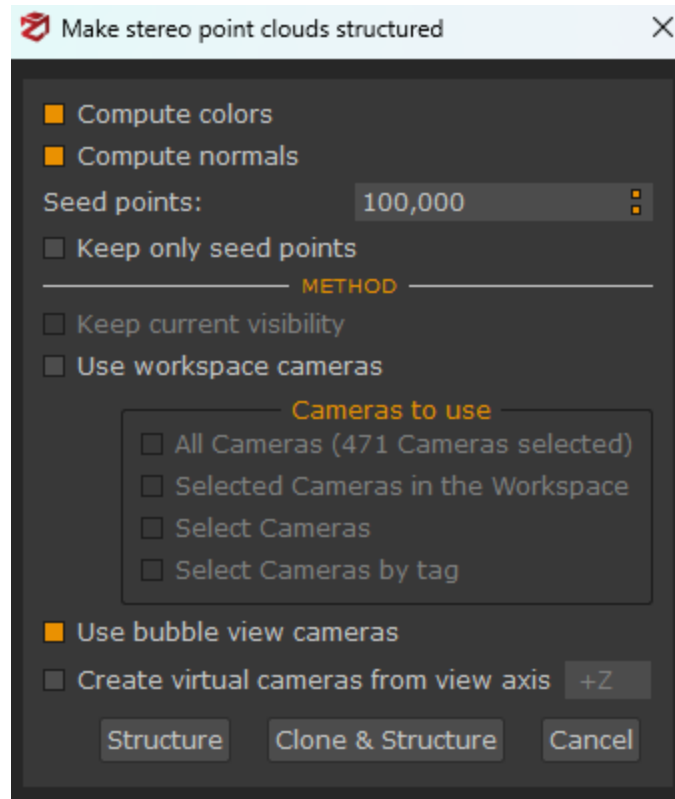
When ready, click “**Next**” and the summary will appear. Click “**Apply**” to continue.



At this point, the point clouds have been aligned correctly. An additional ICP step is advised at this point to minimize errors.

Structuring laser scans:

Once the registration is completed, simply select the desired dense point cloud from the “**Project**” Tab, right click it and then click “**Make structured**”. Select the options accordingly to your needs, as shown below:



After the structuring, now you are ready for the mesh generation. Please remember to select the correct amount of **seed points** from this dialog according to the level of detail you want to obtain in your final mesh.

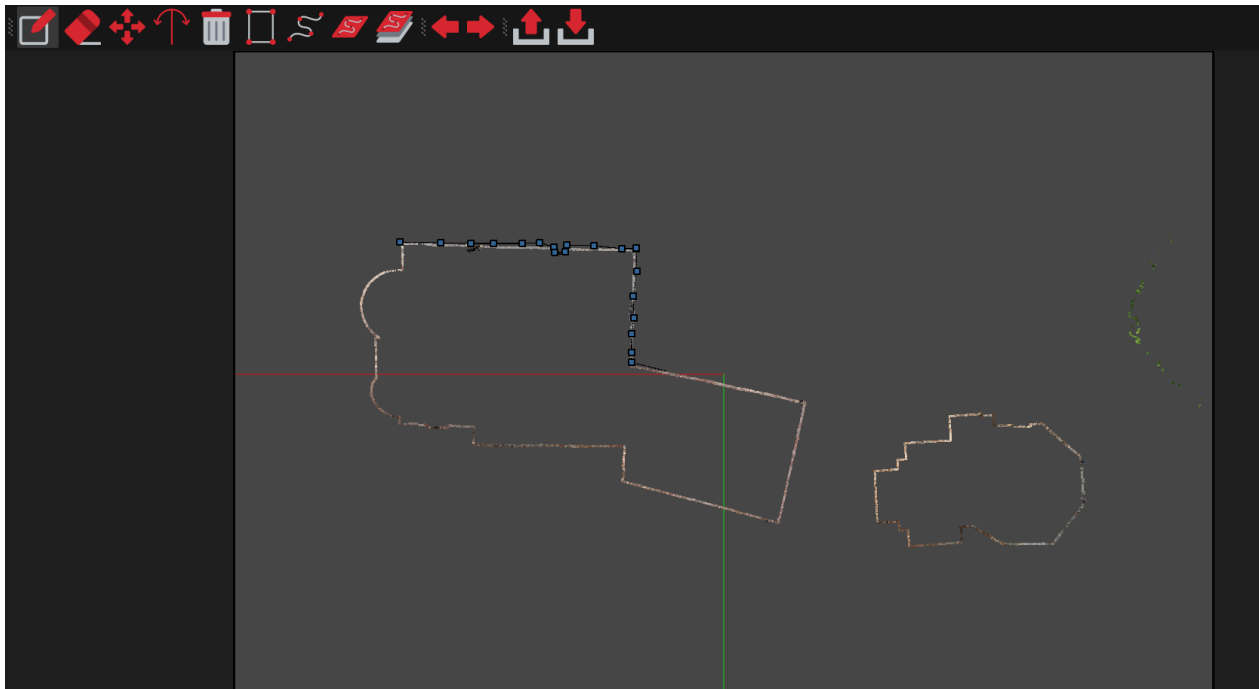
Tools - Sections and Contour Lines

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

By clicking on **Tools > Sections and Contour Lines** you can select the drawing element you want to create choosing from:

- **Sections:** this tool generates only one plane that you can move, rotate and resize; the position of the plane can also be modified using the control points, if they have been previously placed on the 3D model;

With this tool, a window will pop up after the plane has been placed (see image below).



In this window you can draw sections and contour lines previously identified by the planes both automatically or manually. In the upper bar of the window there are editing and drawing icons as follows (from left to right):

Create: manual method that allows you to draw a polyline;

Remove: removes the vertex of a polyline;

Move: moves the vertex of a polyline;

Split: adds vertex to a polyline;

Clear: deletes all polylines;

Close Polyline: closes a polyline;

Smooth Polylines: allows you to smooth all the polylines drawn;

Autocompute Current: generates a polyline only on the section shown in the window;

Autocompute All: generates a polyline for each section previously created using the planes;

Export: allows export of drawings as .dxf and .shp format;

Import to Workspace: allows to import drawing elements in Zephyr workspace;

Previous and Next icon allow scrolling among the sections created.

- **Track Sections:** this tool generates several planes (user can fix the amount of those) on each position of the control points so it is worthwhile when it is necessary to draw sections on an irregular path (for example, a river bed);
- **Contour Lines:** allows generation of one or more contour lines on the 3D model and

user can choose the reference axis for contour lines direction;

- **Elevation profile from Drawing Element:** allows generating elevation profiles if at least one drawing element (polyline) has been created. Please check the [DEM Viewer section](#) to understand how the elevation profile tool works.

Tools - Lines Extraction

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Via the "Lines Extraction" menu, it is possible to add drawing element to the project via a manual/assisted method or via a completely automated function.

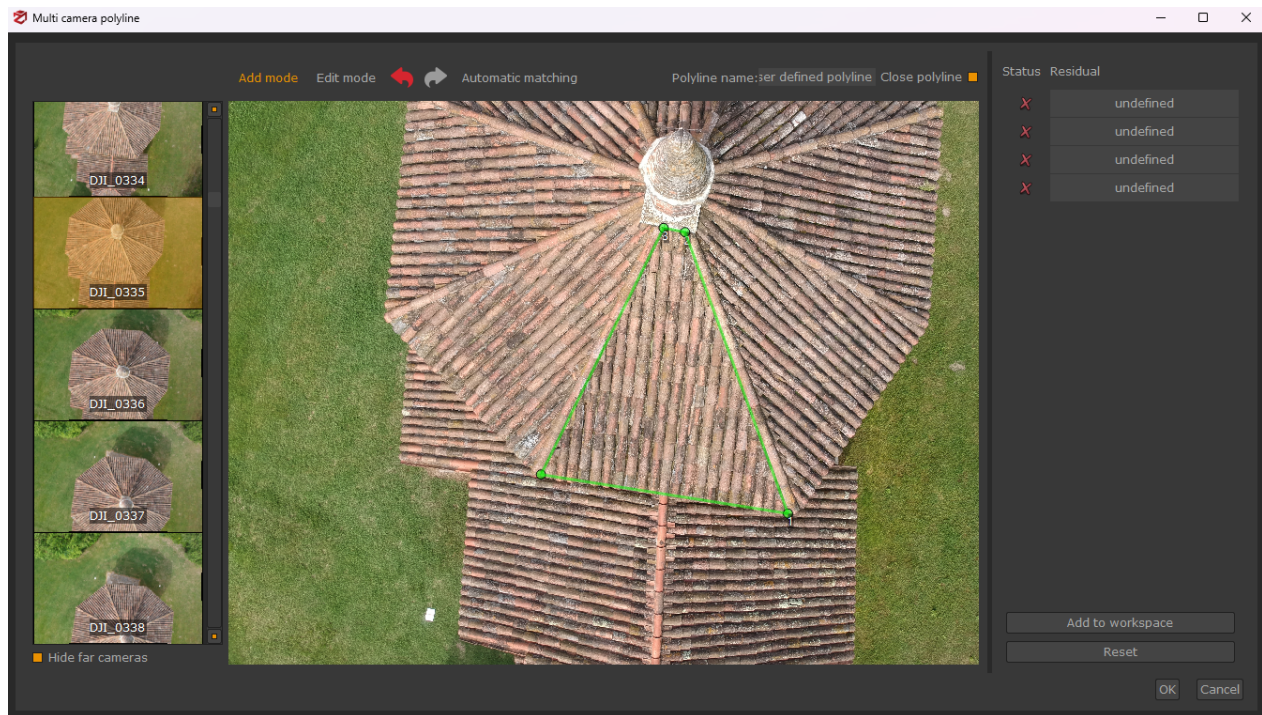
Manual Lines Extraction

Zephyr offers the manual lines extraction feature in two different workflows: one that requires to define a certain set of points on at least two pictures (given a sparse point cloud) and one that requires to define a certain set of points in just one picture (given a dense point cloud or a mesh).

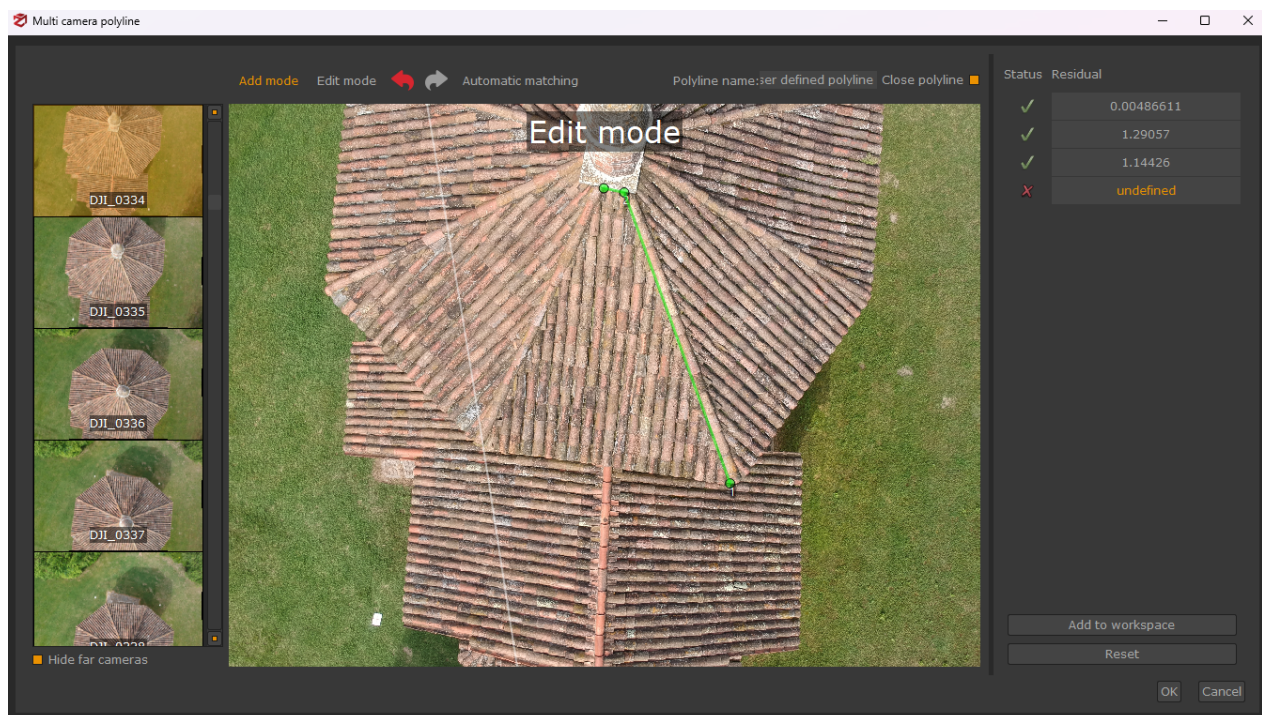
- **Manual extraction given two images and one sparse point cloud (multi camera polyline)**

In order to extract lines manually, a certain set of points must be defined on at least two pictures. This is done manually on the first selected picture, while an assisted automated point detection is offered when selecting other images.

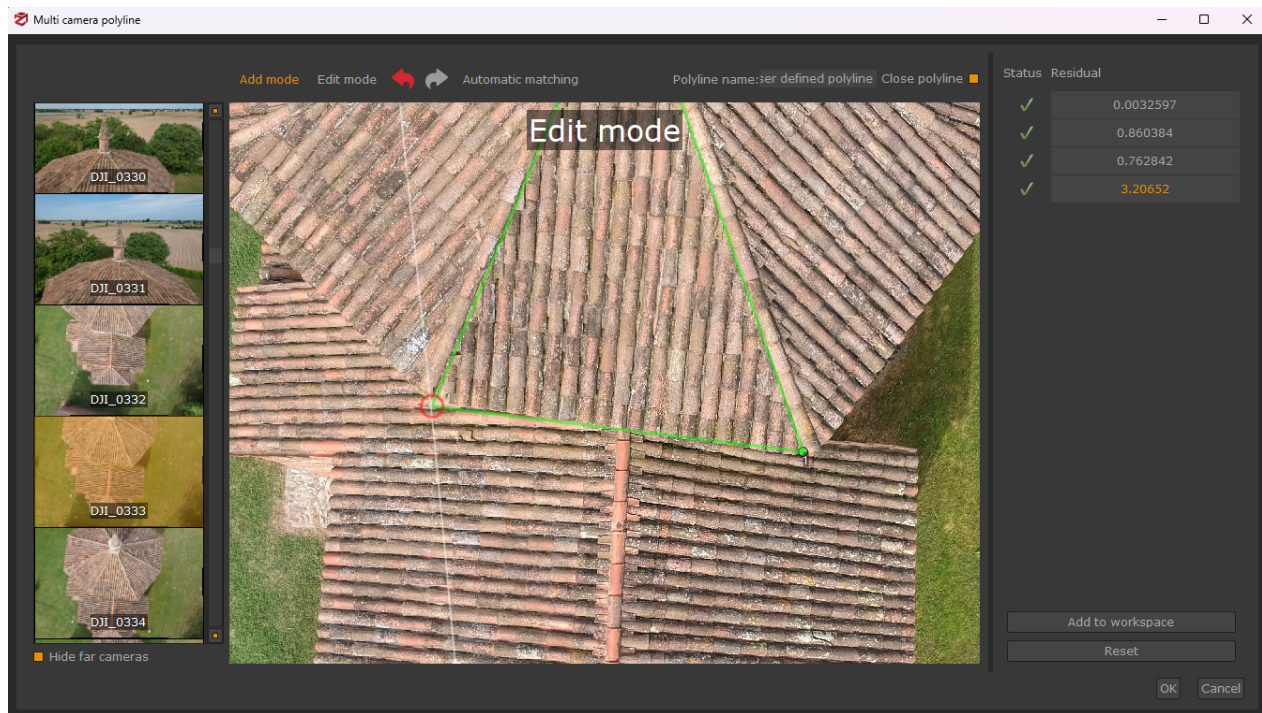
The point definition interface is similar to the one used to define control points, with the scroll-wheel used to zoom in and out and to pan the image via mousewheel click. On the right panel, the polyline name can be edited as well as the defined points. The top toolbar allows to switch from the "add mode" (which adds a new point) to the "edit mode" (which allows to edit a previously picked point).



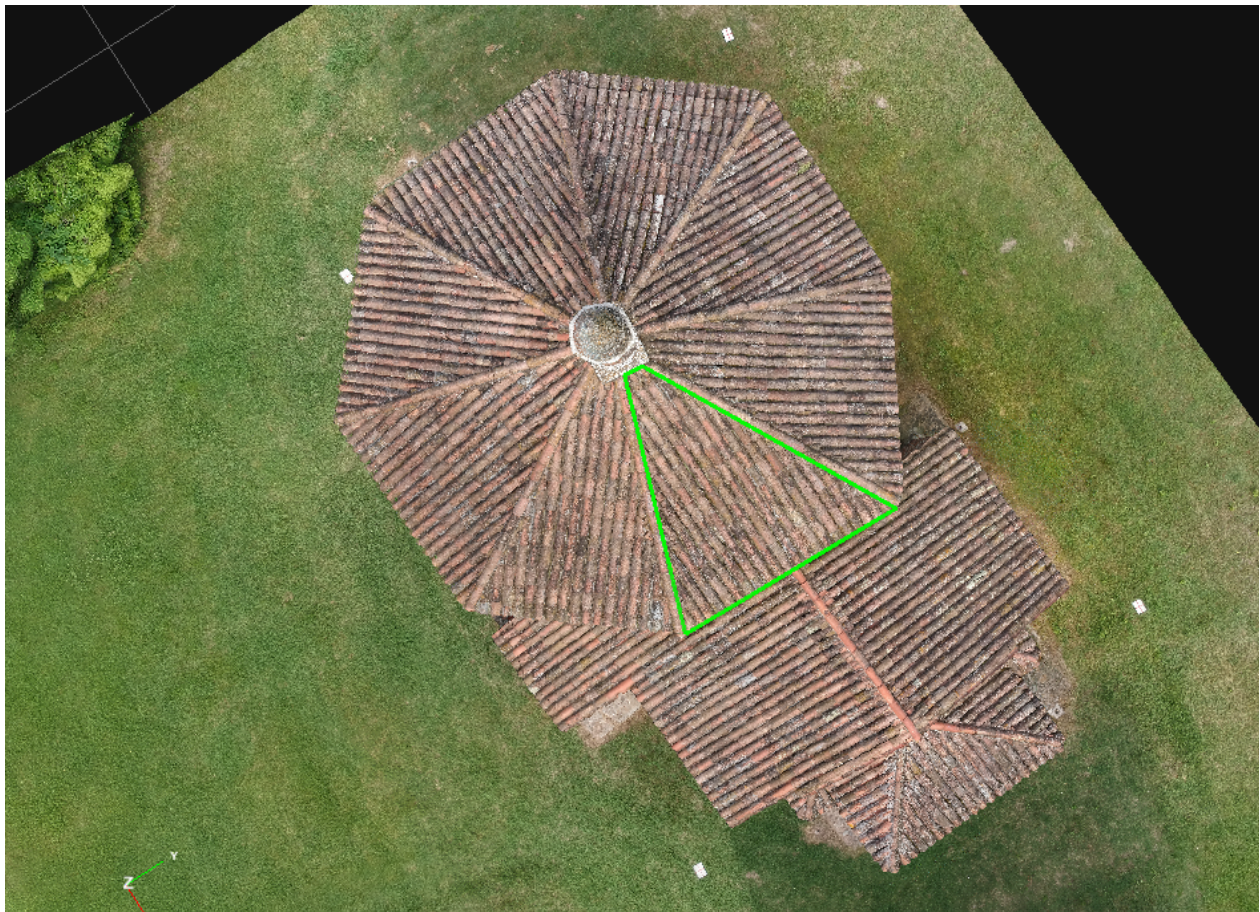
After selecting at least two points on the first image, the same points (in the same sequence) must be selected on another image.



Points can be selected manually again, and you will see that a red circle will be enabled along with the line where Zephyr expect to view the points of the polyline.



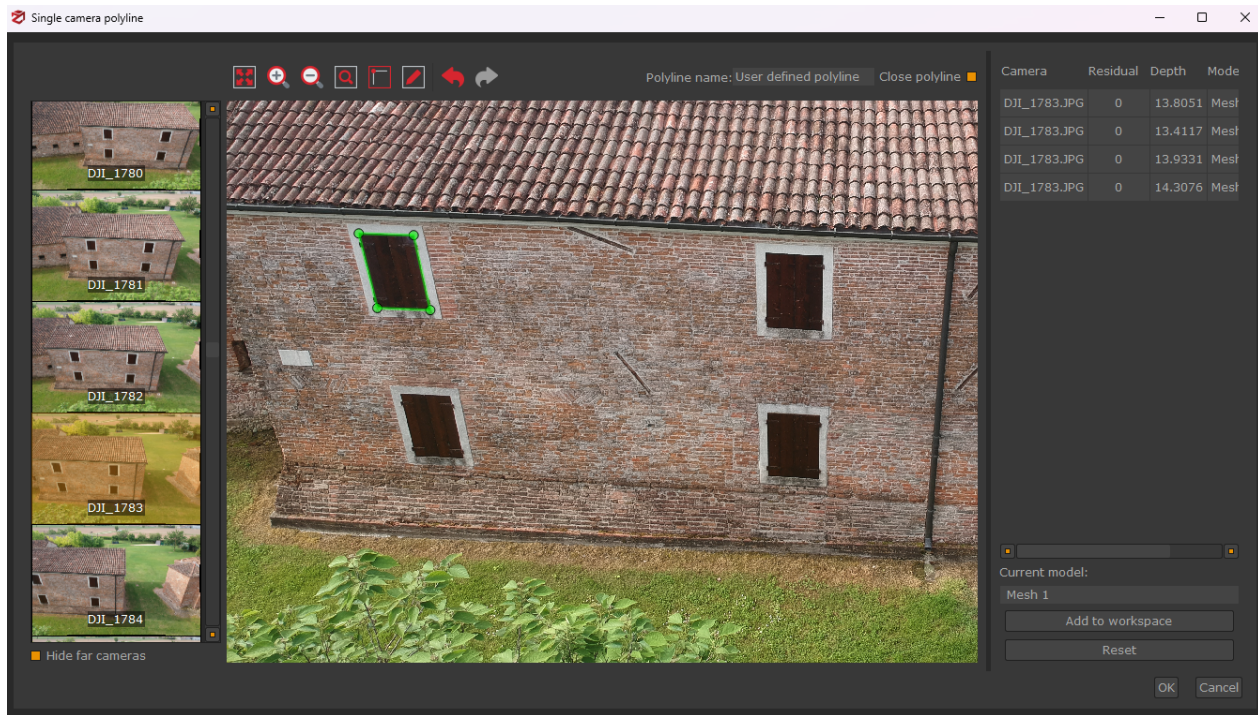
You can also perform automatic attempt by clicking "Automatic matching". When all the points are defined correctly, you may press OK to finish and automatically import the new polyline in the workspace, which will be added to the drawing elements section.



- **Manual extraction given a picture and a dense point cloud/mesh (single camera polyline)**

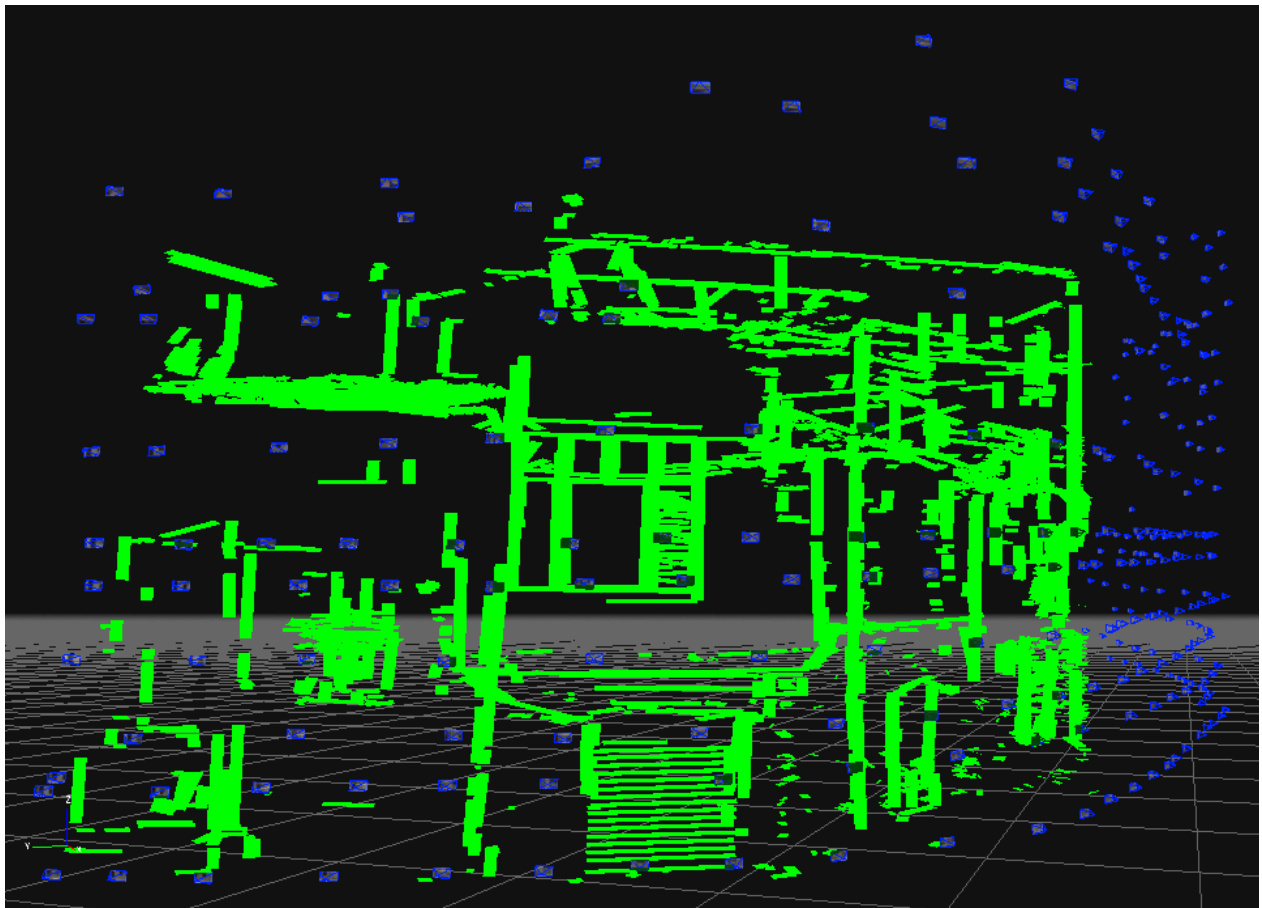
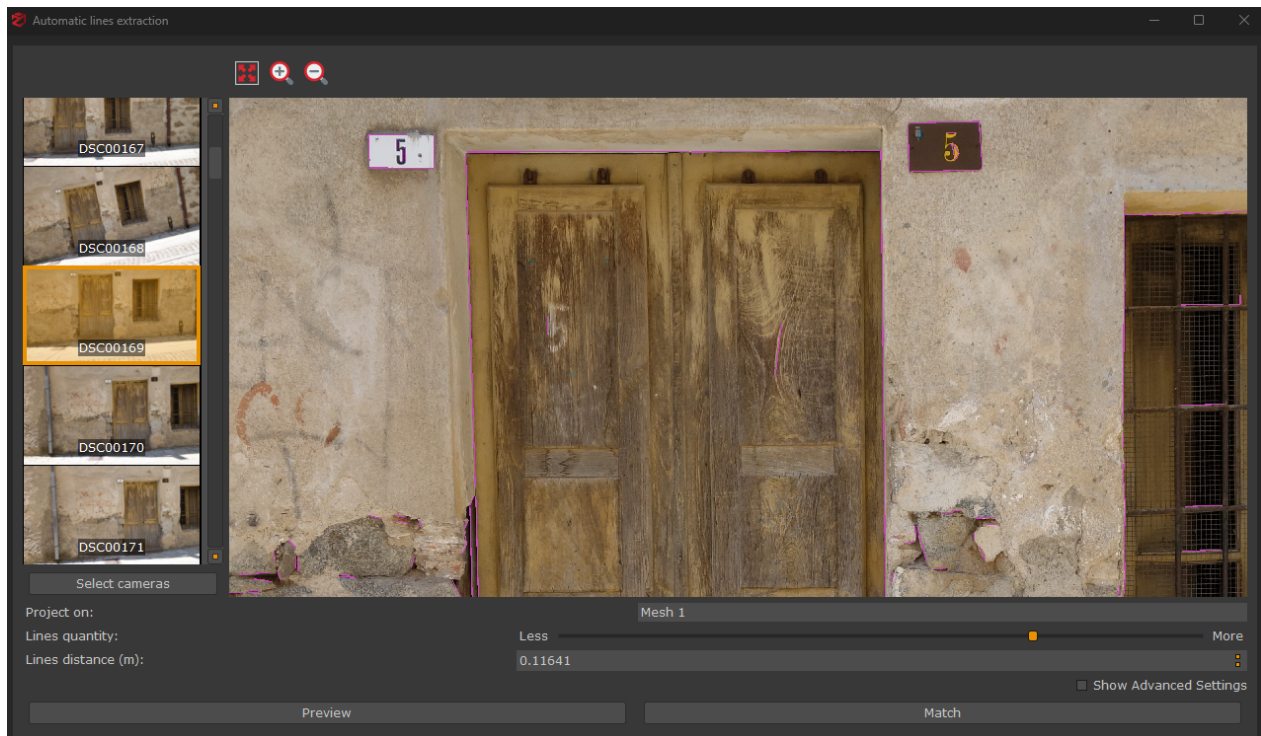
If at least a structured dense point cloud is available in the workspace, it is possible to extract polylines with a very similar workspace, however using only image. Thanks to the dense point cloud, the points projection will automatically extract the desired polyline.

The interface is very similar to the one mentioned above: simply select the desired polyline points in one image and the reference point cloud to generate the target polyline.



Automatic Lines Extraction

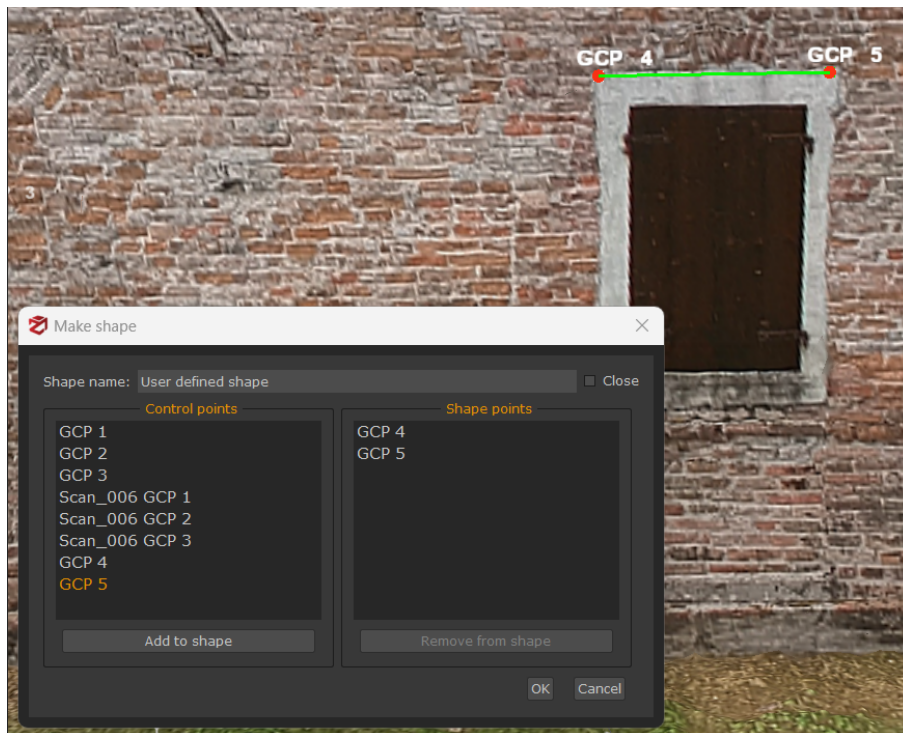
You may let Zephyr do all the work and automatically extract lines. This process requires to set a line distance (which makes sense when you have scaled the model to a known measure) and allows also for a preview per-image. Please note that although all the automatically extracted lines are grouped together in the "Drawing Elements" section, when exported in DXF, every polyline will have its own definition.



Make Polyline from Control Points

You can generate polylines by placing at least 2 control points in the 3D space. In the dedicated window, you will be asked to choose which control points to use for the

polyline creation.

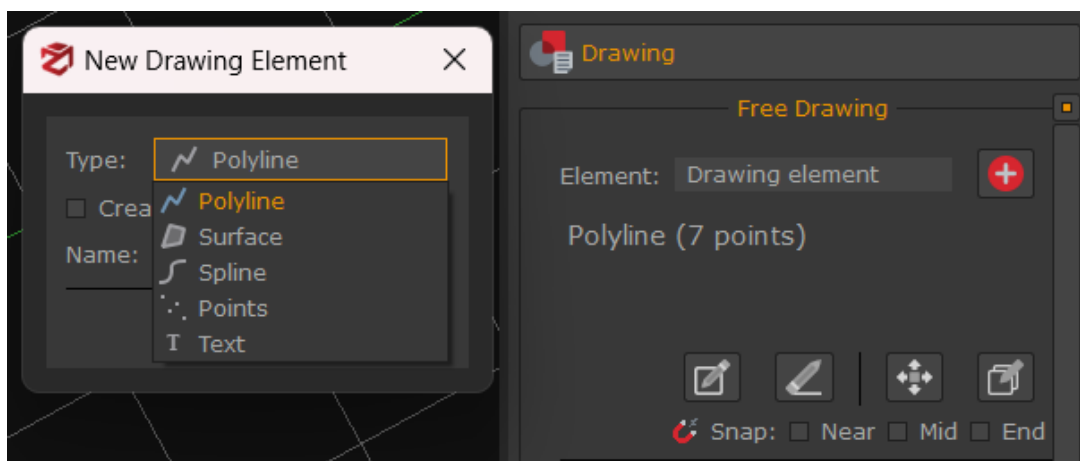


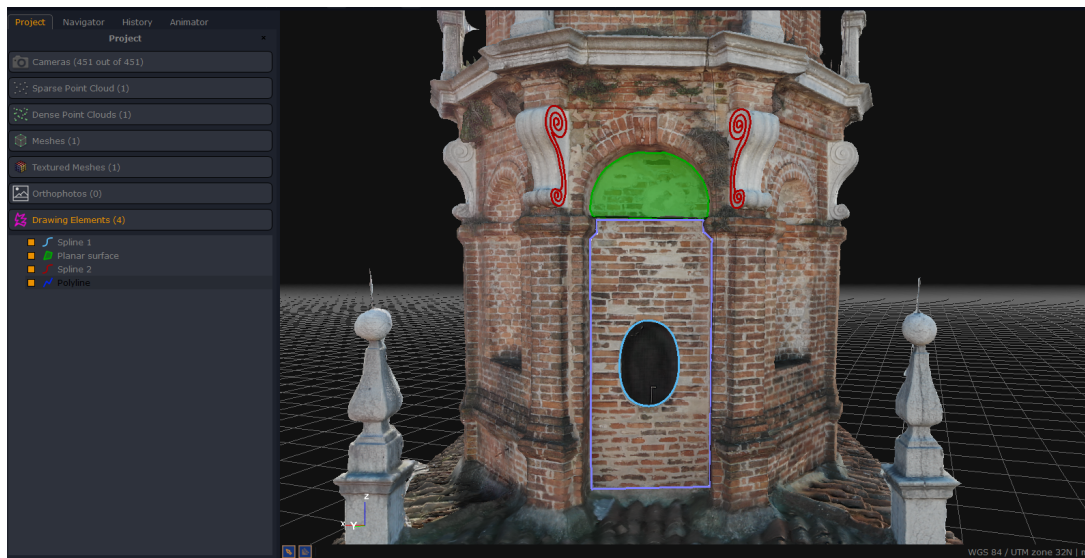
Drawing Elements & Layers

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The **Free Drawing** tool in the "**Drawing**" section of the **Editing** tab allows you to draw polylines, splines, surfaces, points, and text directly on the 3D model.

Please note that drawing elements can be exported into DXF, SHP, DNG and XML files.

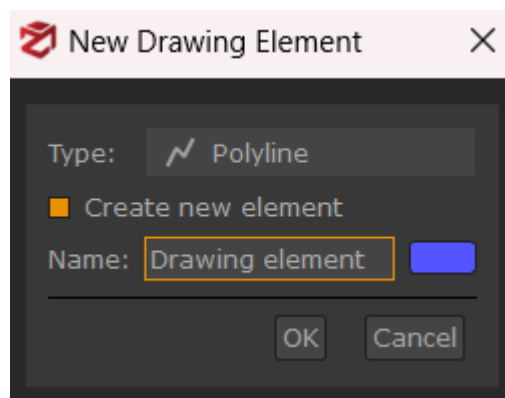




You can choose the drawing element type (polyline, surface, spline, point, text) from the **popup dialog**, by pressing the  button.

To create a new separate drawing element, the **Create new element** checkbox must be selected.

It's possible to rename the drawing element and change its color before pressing **OK**.



Once you draw a polyline or a spline, you can close the drawing element by clicking on another vertex. A popup window will be asking you if you want to close the drawing element:



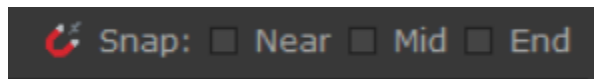
By clicking the **Edit** button , it's possible to add, relocate, and remove the selected point of a certain polyline, spline or surface. You can also subdivide the polyline by



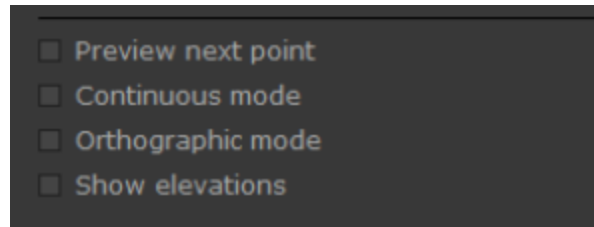
clicking on the **Subdivide** button

Once the **Edit** button is pressed, it's possible to move the drawing element vertices by pressing the **Move** button , or delete them with the **Remove** button .

You can also use the **Snap** function to link the polyline you're currently drawing to another already created: you can do that by using the main vertices ("snaps") of the drawing elements, such as the near/mid/end vertex.

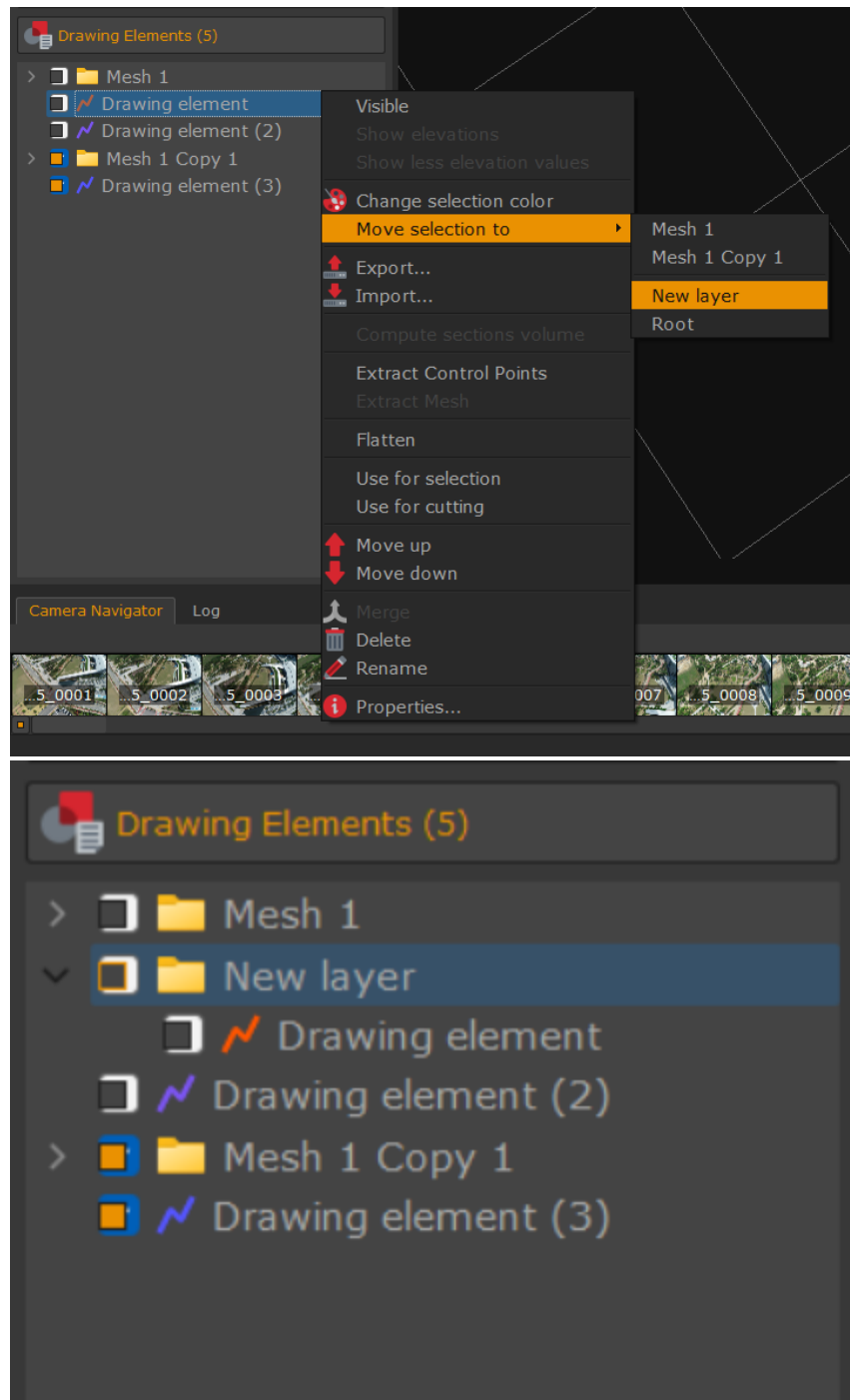


The following modes can support you while placing the polyline/spline/surface points in the 3D workspace:



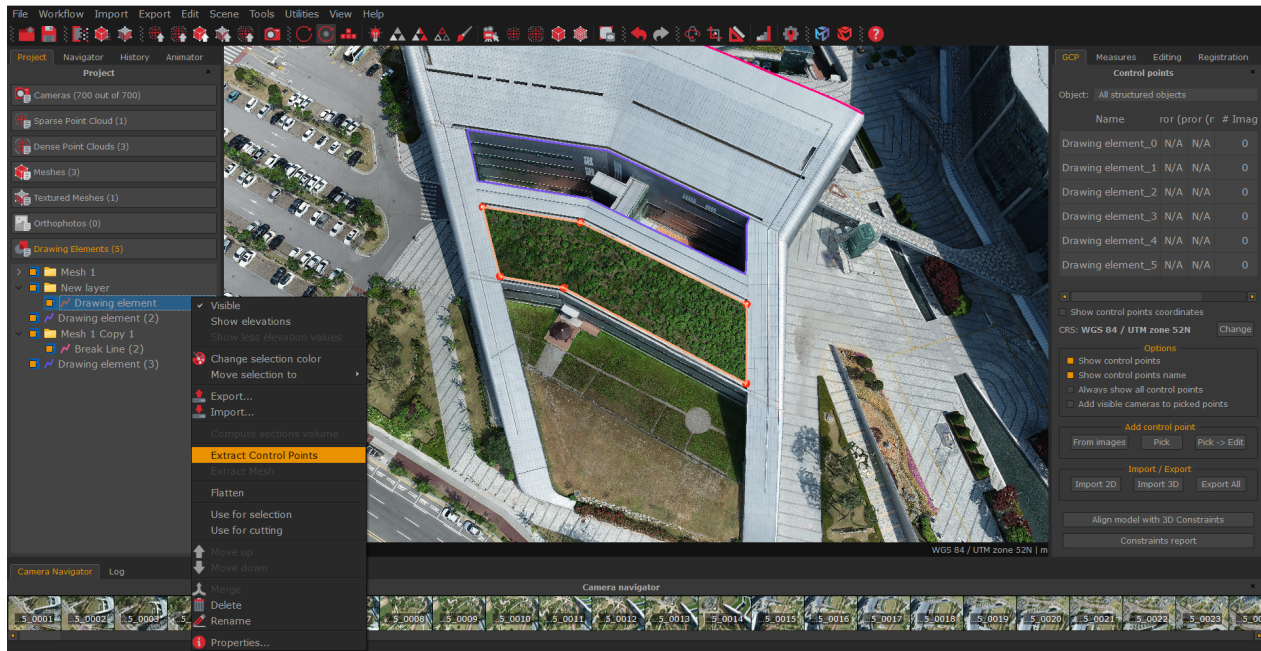
- **Preview next point** allows to have a preview of a point that has not been placed yet. This mode is handy for splines creation because you can check the curvature trend while placing the points.
- **Continuous mode** allows for automatically placing multiple points while moving the cursor.
- **Orthographic mode** allows for switching to the orthographic view during the drawing elements creation.
- **Show elevations** allows for displaying the elevations of the drawing elements' points.

The drawing elements can be grouped into layers regardless of their generation method. In order to do so, you simply have to select the desired drawing element (you may also use multiple selection to move more drawings to the same layer), right click and select the appropriate "move selection to" entry.

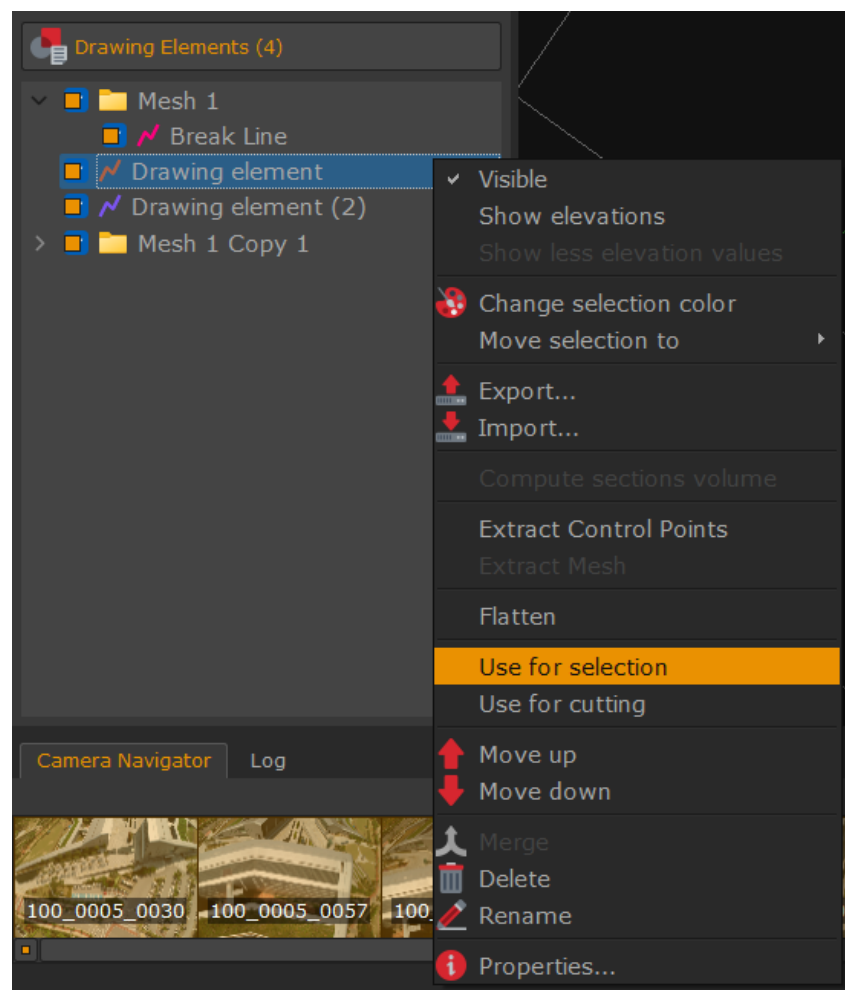


Note: the following tools are available after the drawing elements creation:

Extract control points - allows creating control points from already placed drawing elements vertices.

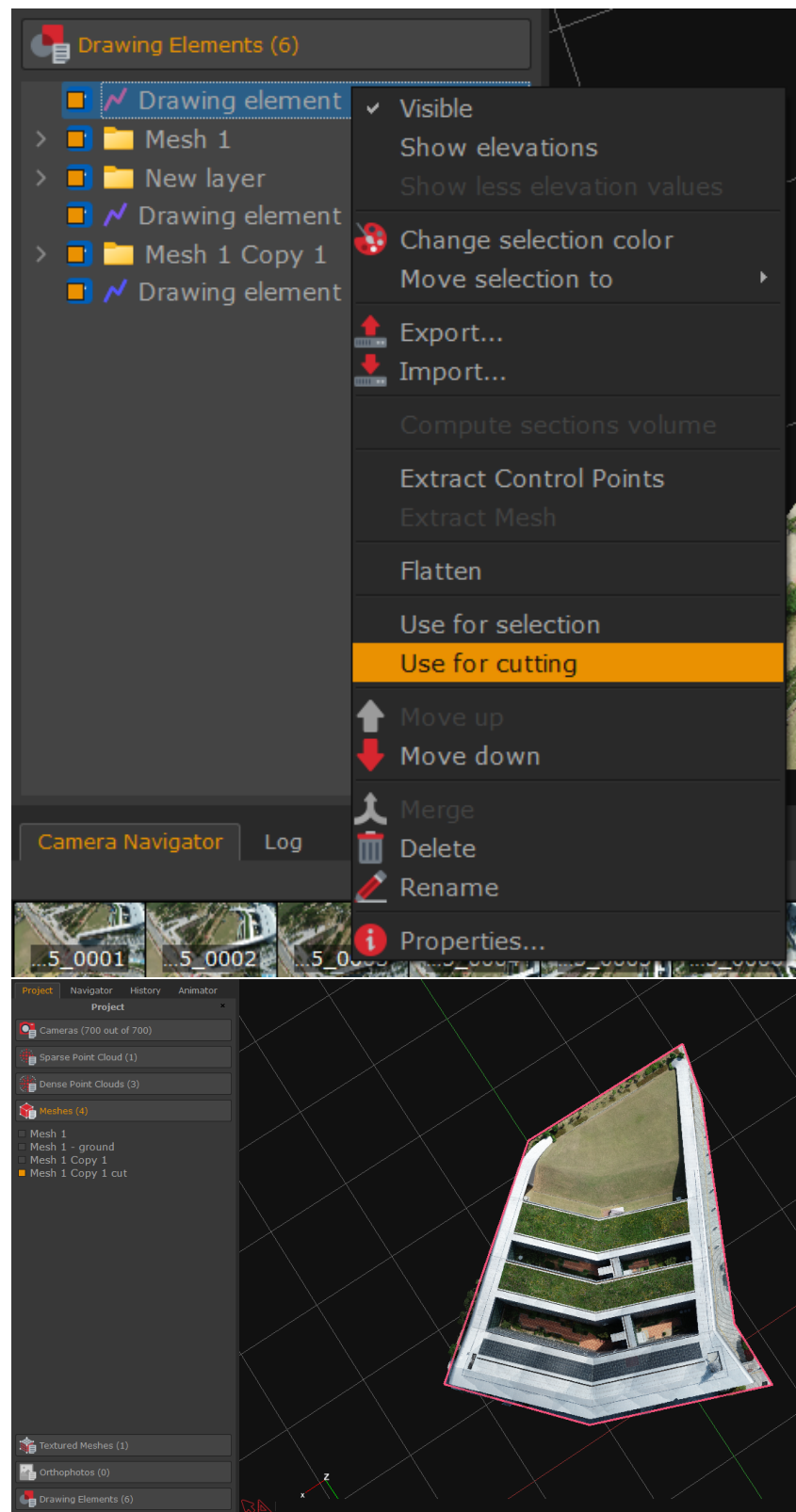


Selection - simply right click on a closed polyline/spline and pick the "use for selection" option to select points or polygons enclosed by the relative polyline/spline.

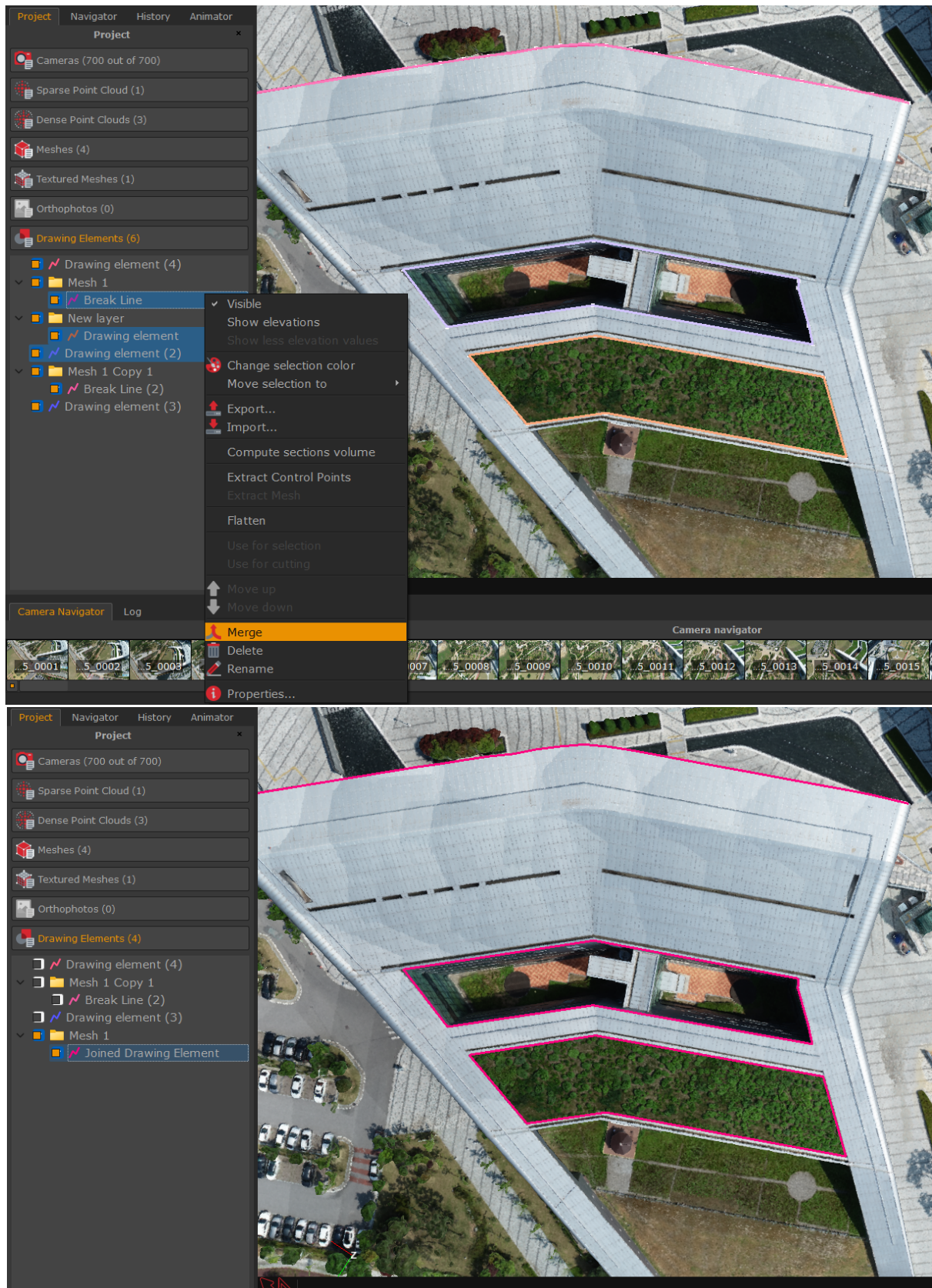




Cutting - right click on a closed polyline/spline and pick the "**use for cutting**" option to cut the area enclosed by the relative polyline/spline.

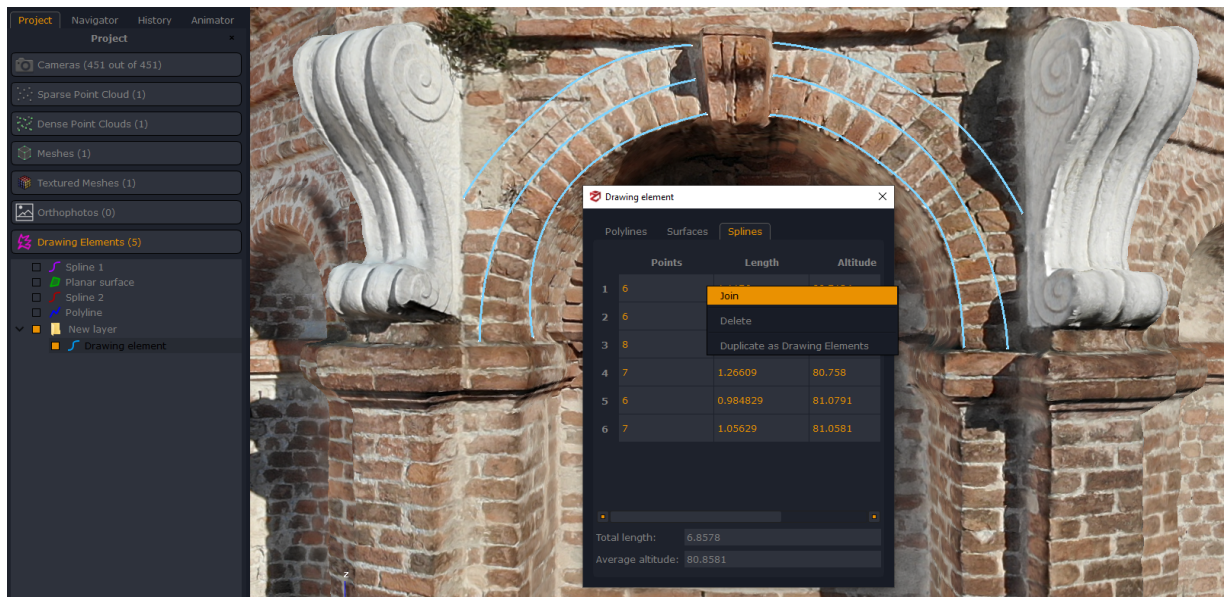


Merge - Allows to combine separate drawing elements of the same type.



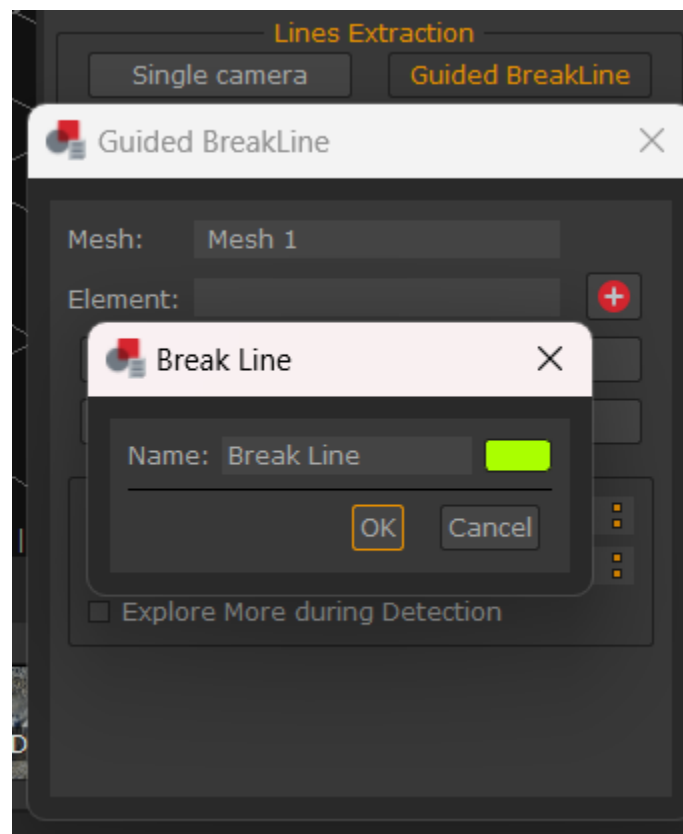
Properties show information about the selected drawing element. Right click on a polyline/spline to choose among **Delete**, **Duplicate as Drawing Elements** or **Join** option.

Please note that you need to select the drawing elements listed in the properties and right click the **Join** option in order to join them together. Once you are done, the properties will list only one polyline/spline.



Guided BreakLines

To create **breaklines**, simply click **Tools > Lines Extraction > Guided BreakLines Extraction**, or select the "**Guided BreakLine**" option under the **Drawing** section from the **Editing** tab.



Click the  button in the popup dialog to rename the breakline and/or change its color. Click **OK** to add the new drawing element to the current workspace.

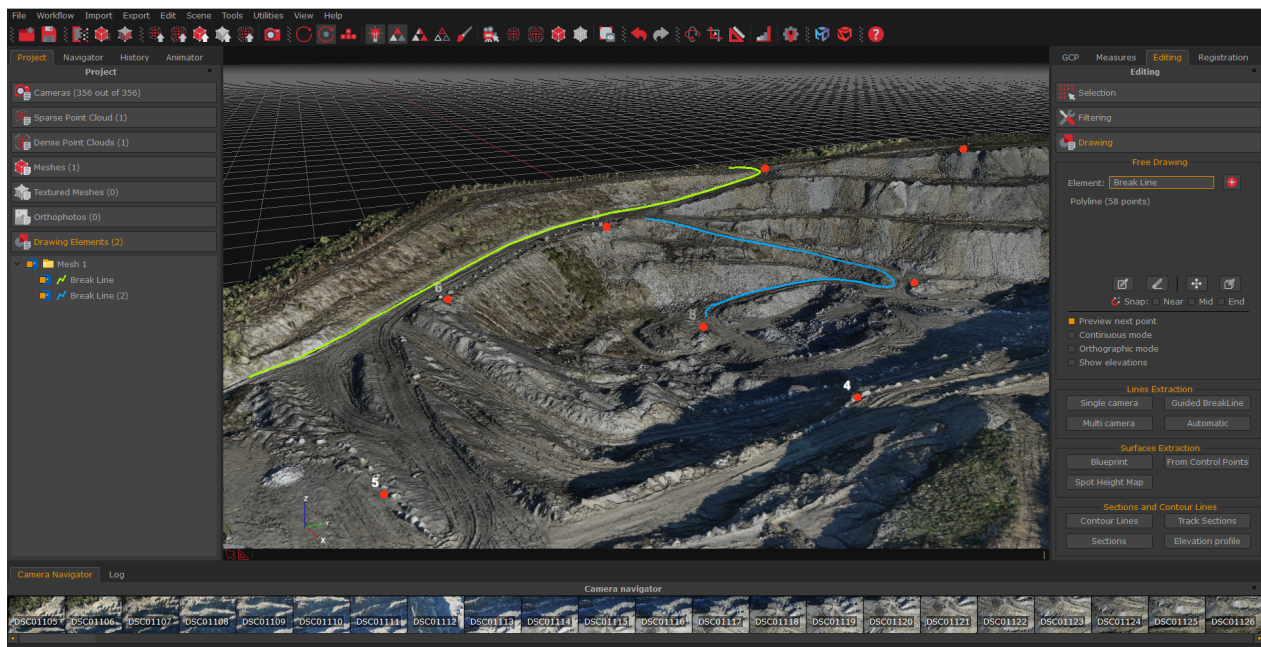
Breakline creation Settings are as follows:

- **Max Segments number**: defines the maximum number of the breakline segments to detect.
- **Max Angle degree**: sets the maximum angle between two segments.
- **Explore more during detection**: this flag enable a more explorative detection, which helps recognize more extended profiles on the mesh structure. This option increases the amount of calculation conditions of the algorithm in order to find longer and more articulated profiles. You can enable this option if the standard guidance is not good enough. Be aware that drifts are more likely to occur.

Once you draw the first vertex, you will notice the breakline will point to the vertex closest to the mouse cursor while hovering the mesh (guided drawing mode). A preview of the breakline (blue line) will be displayed in the meantime. You have to left-click again to add the breakline.

Drawing can be paused and resumed by clicking the "**Pause**" and "**Continue**" buttons, respectively.

You can switch between guided and manual drawing mode anytime by clicking the **Free drawing / Guided drawing** button.



Note: the segments size of the breakline will be similar to the first drawn segment. In this respect, the algorithm behavior is highly influenced by the length of the first segment and it will try to replicate the same length for the successive segments. Therefore, if the searched profile is extended, it's usually recommended to draw a relatively big first segment in order to save time. However, please be aware as the segment size determines the accuracy of the final line.

Tools - Surfaces Extraction

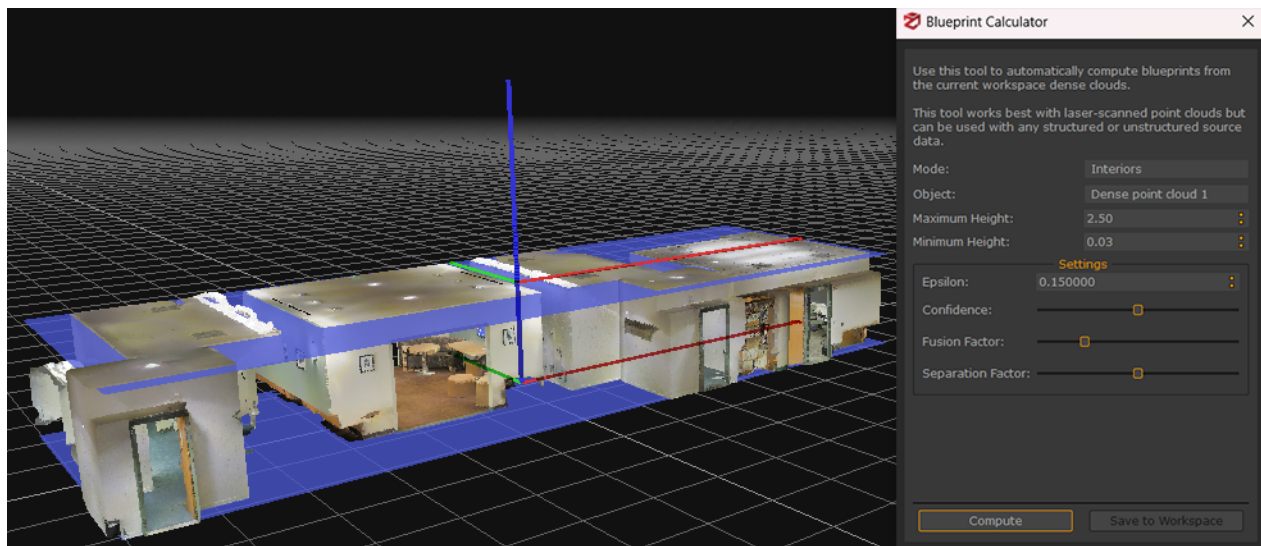
These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

You can generate surfaces manually using control points or by using our blueprint generation method.

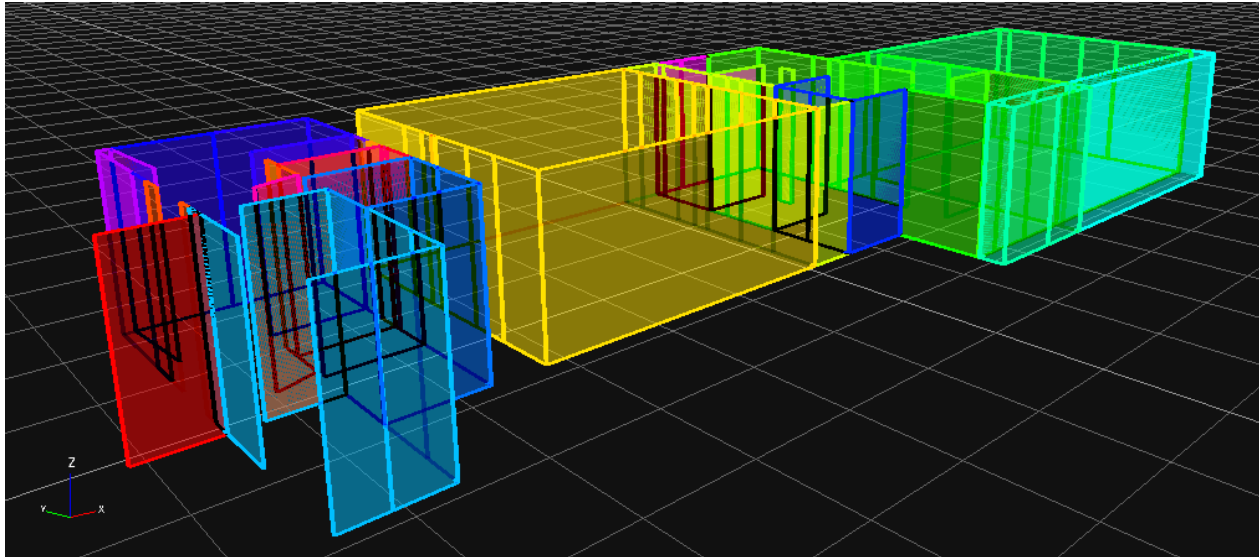
Blueprint generation

This function can work on either structured or unstructured dense point clouds. All you need to do is confirm the automatically detected floor and ceiling planes and select the extraction method (interiors or exteriors).

You can also set the Epsilon (point to plane distance - points further from this value will not be considered belonging to the plane) and fusion factor (controls how segments are generated, a higher value will yield a longer segment and less gaps) if you need further control on the generation method.

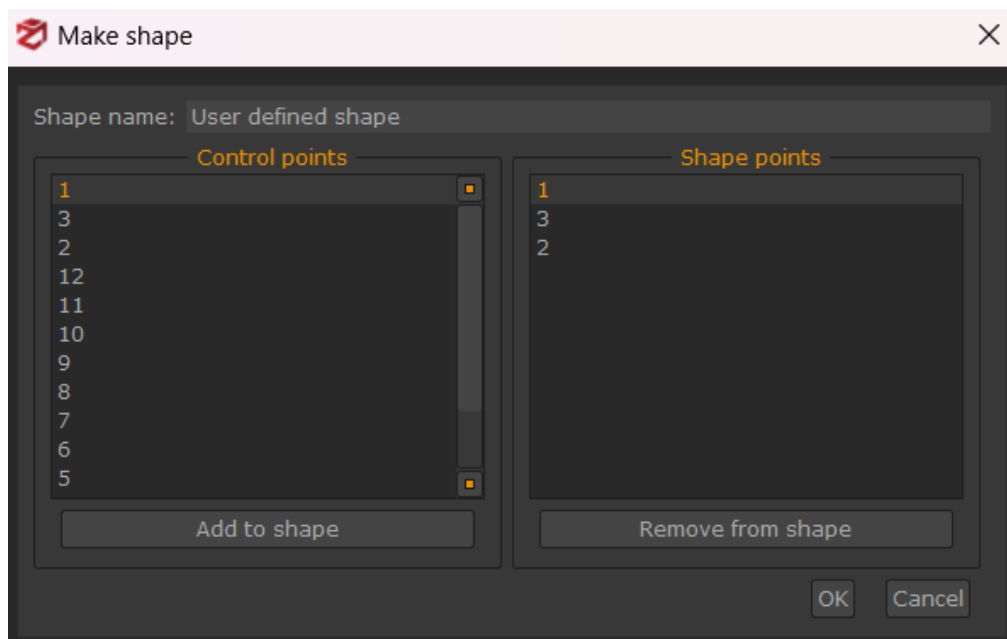


Click "**Compute**" to start the process. When done, blueprints (polylines) and surfaces (surfaces) can be added in the workspace by clicking "**Save to Workspace**". All elements can be found under the **Drawing Elements** Section.



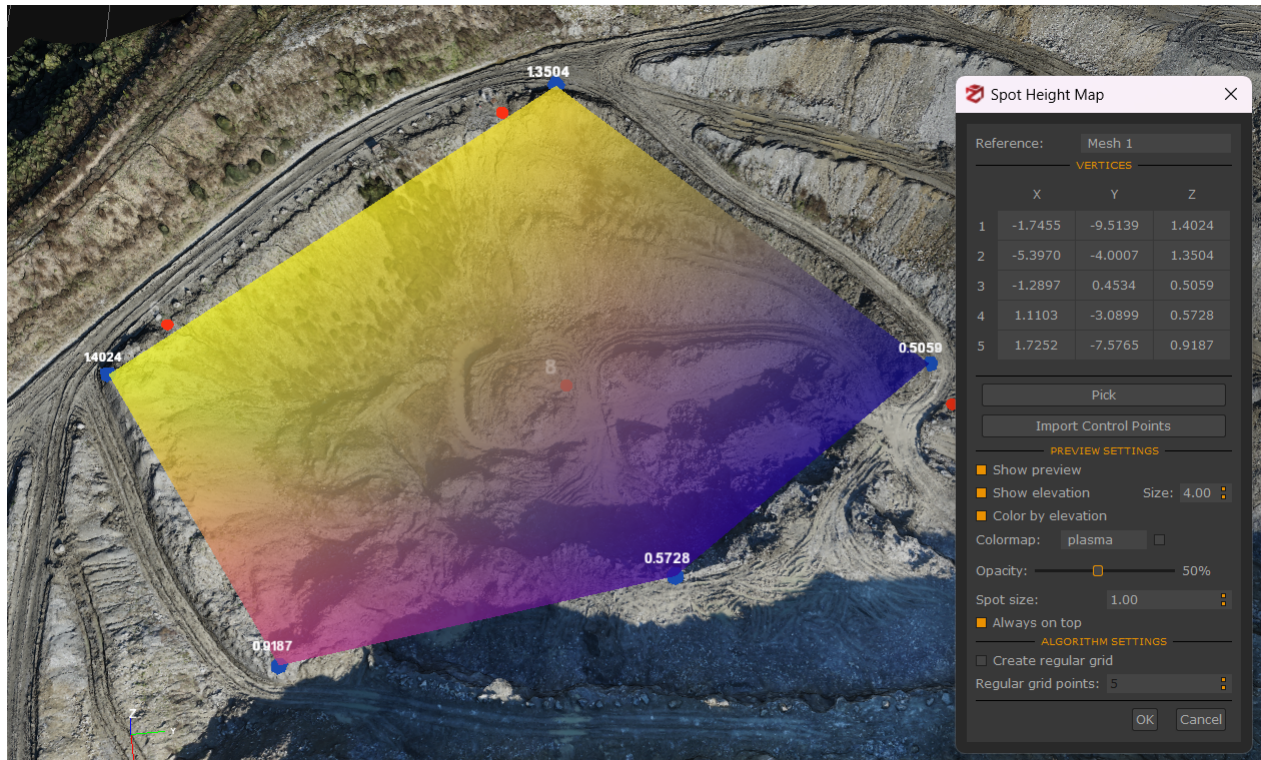
Make surface from control points

Surfaces can be generated by selecting control points. Simply select and add the desired control points to the shape and click "**OK**" when ready.



Spot Height Map

This tool allows to create spot height maps on dense point clouds or meshes either using the GCPs you have already placed or picking new control points.

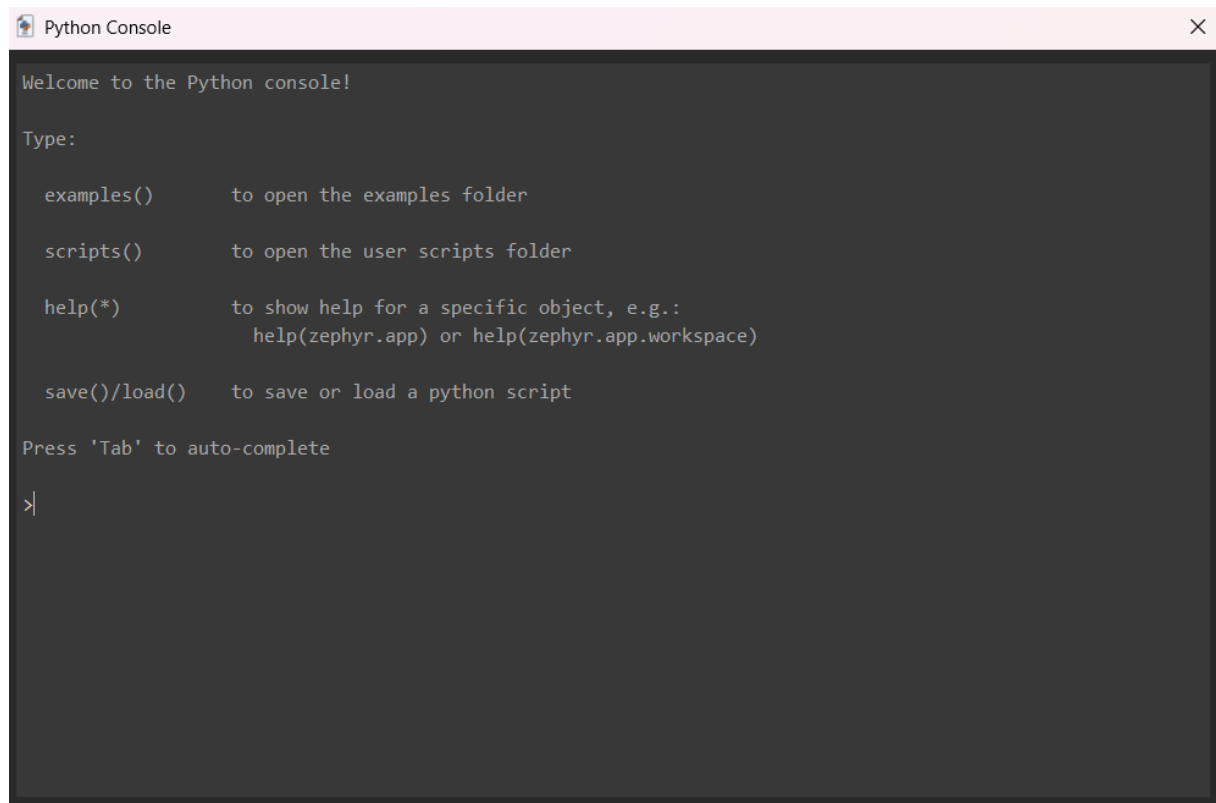


All the control points you pick or take into account will display their elevation value instead of the GCP name, and a new surface will be drawn while picking/importing the control points. You can change the surface color map as well as the size of the height values. Once you click the **OK** button, you will generate both a new mesh and a group of new vertices that will be listed in the **Drawing Element** section of the Project panel.

Tools - Scripting Console

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

You can use this scripting console to customize your own workflow up to a certain degree of freedom using the Python scripting language.



```
Python Console
Welcome to the Python console!

Type:

examples()      to open the examples folder

scripts()       to open the user scripts folder

help(*)         to show help for a specific object, e.g.:
                 help(zephyr.app) or help(zephyr.app.workspace)

save()/load()   to save or load a python script

Press 'Tab' to auto-complete

>|
```

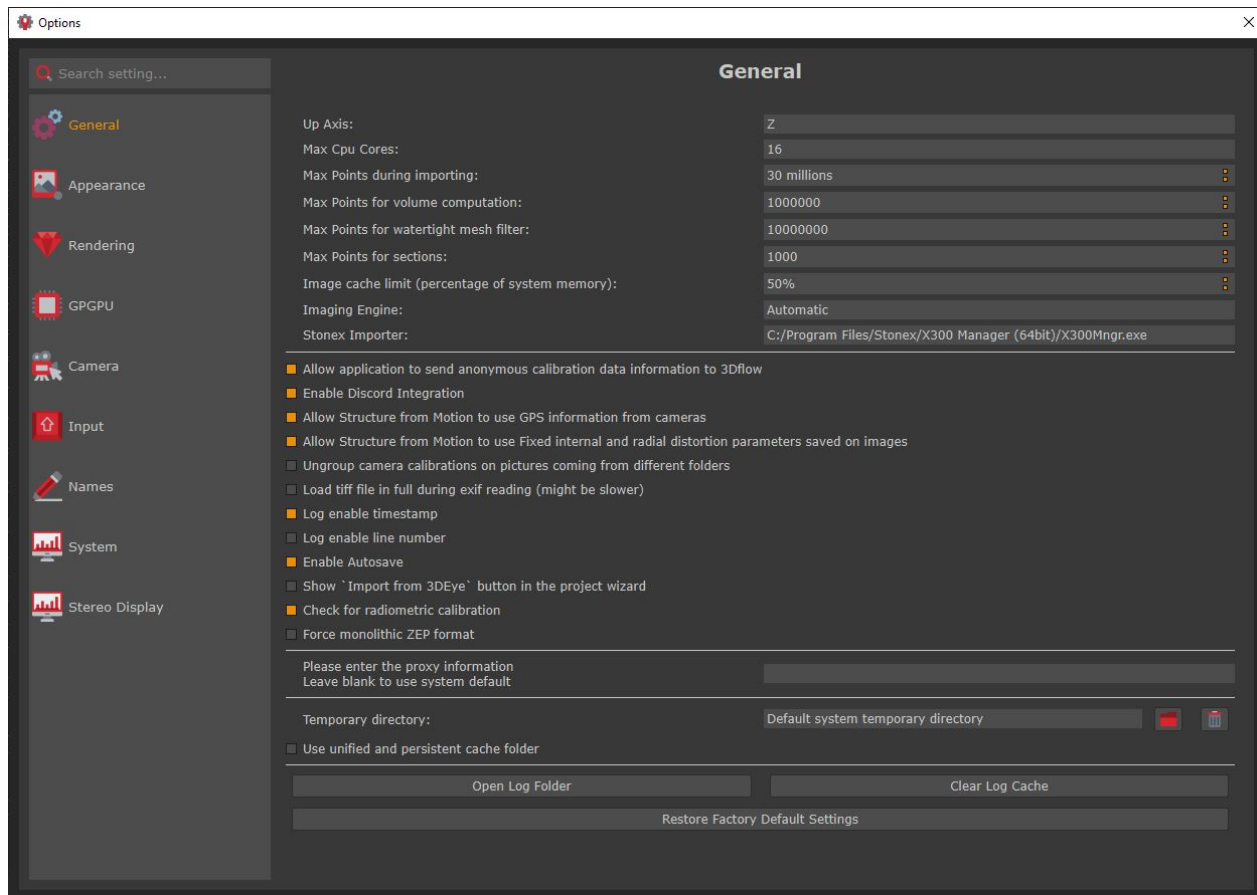
The Python console has its own manual, especially because these functionality will be extended with more bindings in the future.

To generate the Python Console manual, type **zephyr.documentation()** directly in the console. A PDF will be generated on-the-fly with the available functionality, as well as some python examples you can use.

Tools - Options

By clicking the wrench icon  in the toolbar or selecting **Tools > Options** in the menu bar you can enter the **Options** window arranged in nine tabs:

The *search bar* above the option tab can be used for searching options with key words.



- The **General** tab can be used to set Zephyr functionalities, import limitations, access to the log folder, and restore default settings.
- The **Appearance** tabs allow you to set the overall look and feel of the 3DF Zephyr Window, including language, theme, font size and more.
- The **Rendering** tab allows you to edit 3DF Zephyr graphic appearance. You can modify the colors of several items ranging from the workspace to the grid and control points.

Among the most used settings:

- For the viewport, you can change its color with default and custom themes, and also set a Skybox for your 3D model, either by selecting from the panoramic default images (source: [HDRI Haven](#)) or by uploading your own panoramic pictures within the "Skies" folder present in the 3DF Zephyr directory.
- For point clouds generated within 3DF Zephyr, you can change the graphic size of individual points.
- For the cameras, you can edit at any time the alpha channel which is useful to set both the images transparency and the size and color of cones detecting shots in three-dimensional space.
- You can enable/disable GPU processing, either globally or per-single card, in the **GPGPU** tab.

- The **Camera** tab allows you to set values for the camera movement parameters. Also allows managing the connection with 3D devices.
- The **Input** tab allows managing hotkeys bindings.
- You can set the desired default names for generated elements in the workspace in the **Names** tab.
- In the **System** tab, you can toggle (and customize) sleep hours, in which Zephyr will automatically shut down the computer if all computations have finished as well as define other system options.
- The **Stereo Display** tab allows managing connection with 3D monitor.

The "Utilities" menu

From this menu you can launch the following **Utilities**:

3DF Masquerade

3DF Masquerade is a standalone external tool (included in all 3DF Zephyr versions) to create masks to pair with the images to be processed in 3DF Zephyr. A mask is defined as a specific selection of one (or more) images that allows to force zephyr to ignore the corresponding part in a picture. The first time you run **Masquerade** useful tooltips will appear on the screen that will teach you the interface basics.

A complete tutorial (and video tutorial) about 3DF Masquerade can be found at the URL <http://www.3dflow.net/en/technology/documents/3df-zephyr-tutorials/tutorial-use-masking-tool/>.

Masking action in **3DF Zephyr** can be performed with two modes:

- 1) **Automatic masking**: based on machine learning model.
- 2) **Manual masking**: carried out using masking tools in the **Masquerade** interface.

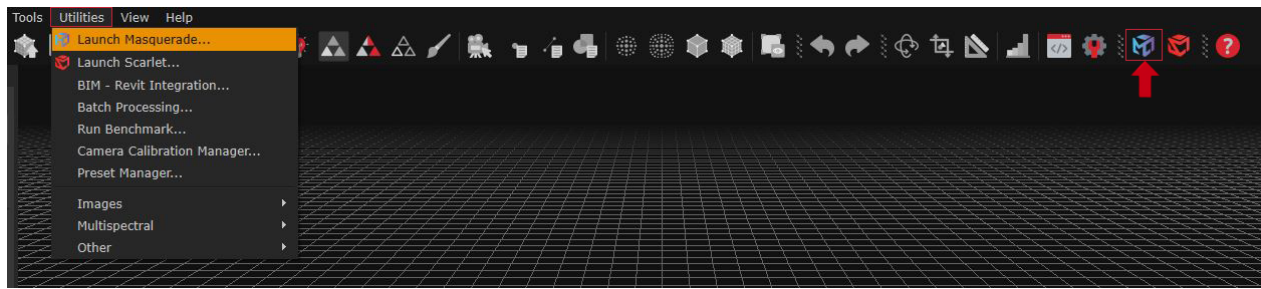
Starting 3DF Masquerade

3DF Masquerade can be launched as an external executable and used independently from **3DF Zephyr**.

1) From the Windows Start Menu: typing '*masq*' in the search bar to locate and open Masquerade

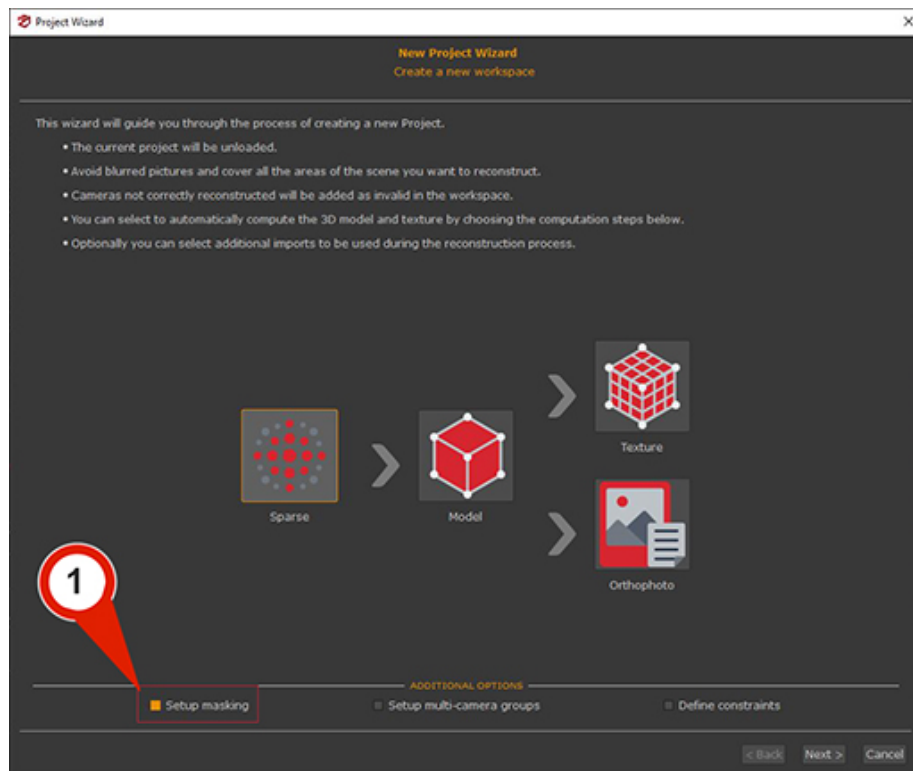
2) From the 3DF Zephyr workspace:

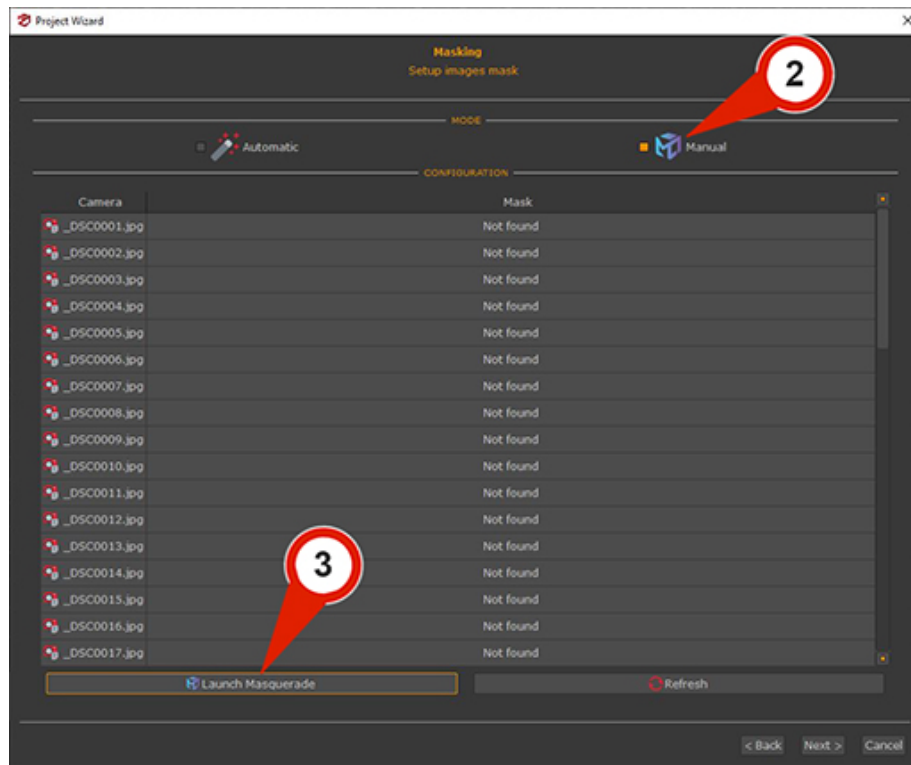
- Via menu bar: navigating to **Utilities > Launch Masquerade**.
- Via toolbar: clicking on the **Masquerade icon**.



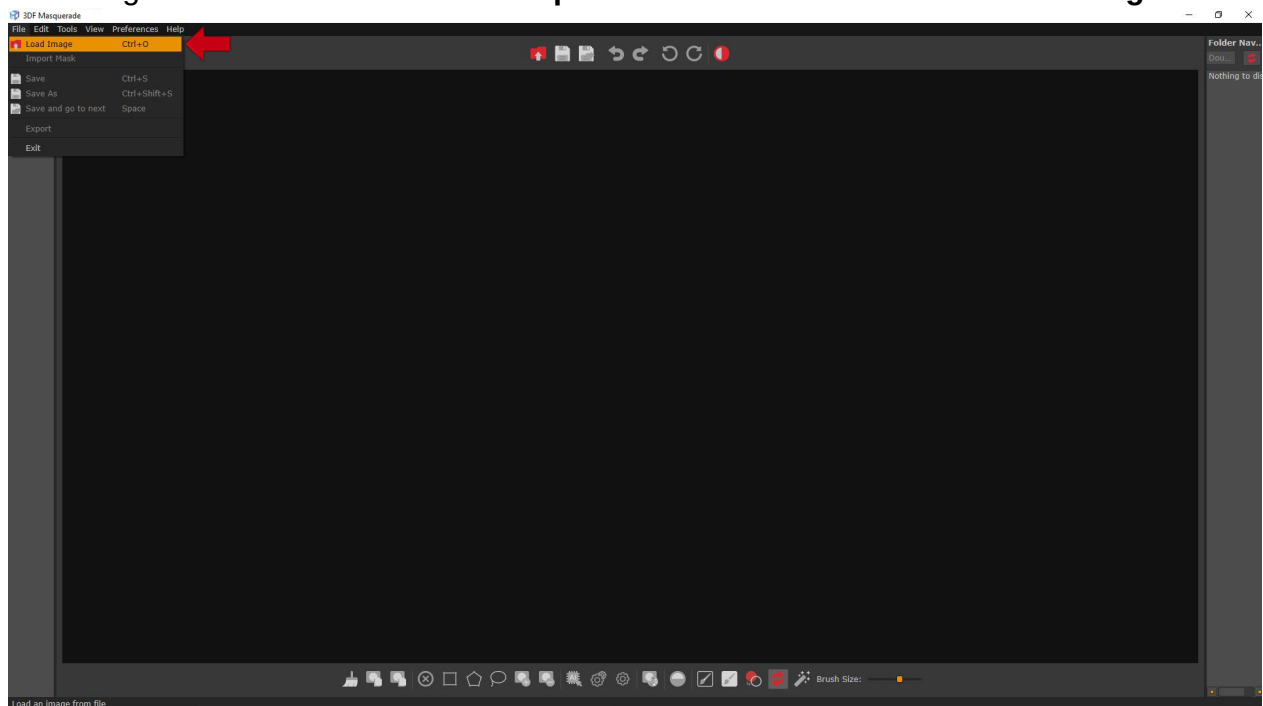
3) From the New Project Wizard menu:

In the first page of the **New Project Wizard**, the **"Setup Masking" (1)** checkbox must be selected. Clicking the **"Next"** button advances to the photo selection phase, where images are loaded automatically. Clicking **"Next"** again proceeds to the **Masking** page, where the **"Manual" (2)** checkbox must be enabled to display the image and mask list and activate the **"Launch Masquerade" (3)** button.

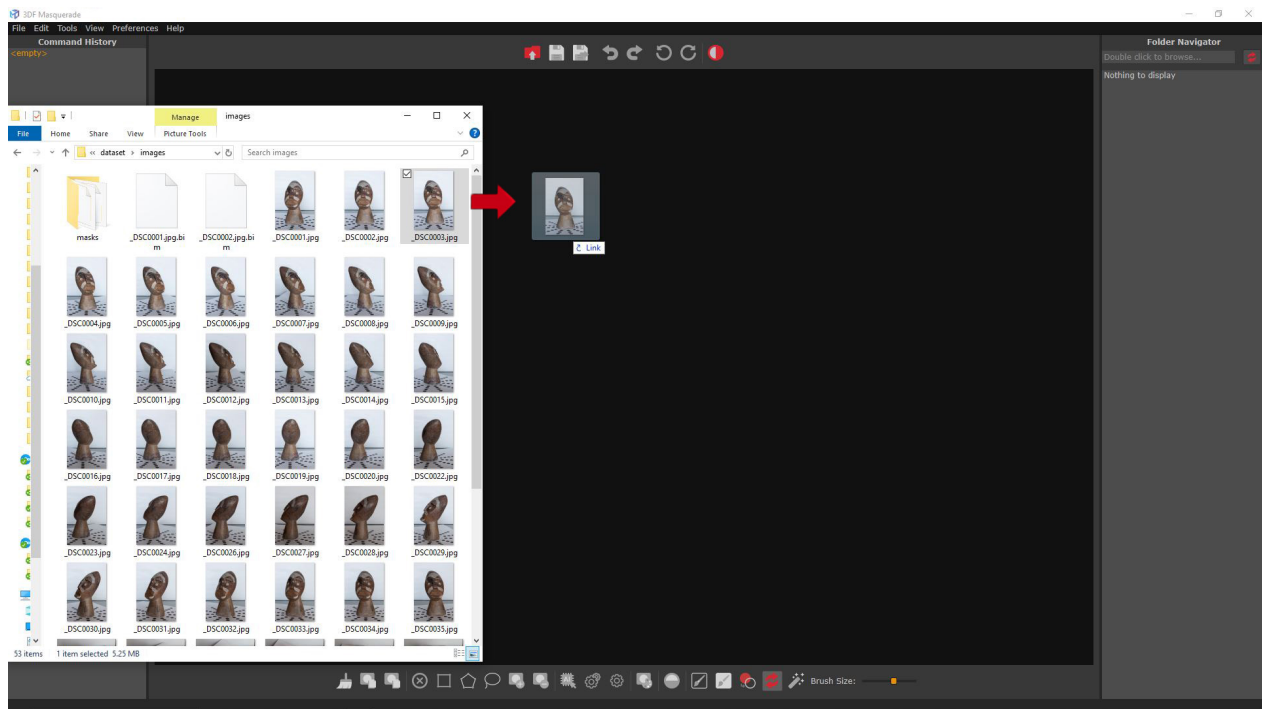




The Images can be loaded inside **Masquerade** from the menu: **File > Load image**.

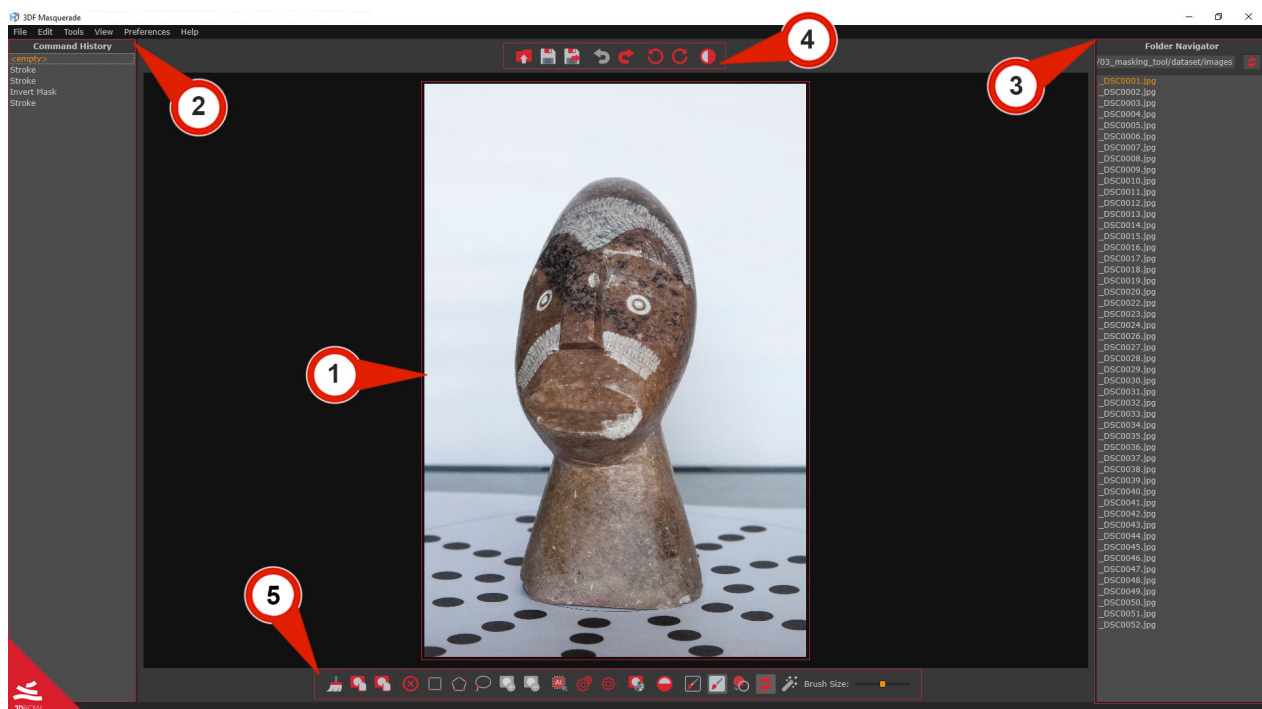


Alternatively, it's possible just to drag and drop the first image in the workspace to load all the images in a folder.



The 3DF Masquerade Interface

The **3DF Masquerade** interface is divided into these sections:



- **Masking workspace (1)** – allow to visualize each picture and work with the masks tools.
- **Command history (2)** – can be used to undo/redo actions taken in 3DF Masquerade.

- **Folder Navigator (3)** – This panel, facilitates quick navigation through images, that will be associated with created masks and marked with a “(M)” symbol. Right-clicking within the panel provides access to the following commands:
 - **Select All:** Selects all listed images and their corresponding masks.
 - **Show in Explorer:** Opens the folder containing the selected image and highlights it.
 - **Delete Mask for This Image:** Permanently removes the mask associated with the selected image from the folder.

Note: Using the **Select All** and then use the “**Delete Mask for This Image**” commands will permanently delete all masks in the current project.

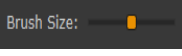
- **Upper toolbar (4)** – provides quick access to core editing tools for managing the masks.

	Load image: the command allows to select an image load all the pictures inside Masquerade.
	Save: this command allows to save the mask just modified
	Save and go next: the command allows to save the modified mask and go to the next image automatically
	Undo / Rendo: this command allows undoing or redoing previously performed actions.
	Rotate clockwise / Rotate counter-clockwise: this command allows rotating the image.
	B/W Mask: this command allows viewing the black-and-white mask of each image.

- **Lower toolbar (5)** – it contains several tools for masks/unmask images.

	Clear mask and Strokes: the command allows to cancel the image current mask and all the strokes made with the brush tools.
	Copy current mask to next image: this command allow to copy the mask to the current image to the next one.
	Copy current mask to all next images: this command allow to copy the mask of the current image to all the other images of the project.

	Clear mask and Strokes: the command allows to cancel the image current mask and all the strokes made with the brush tools.
	Cancel selected tool: the command allows canceling the current selected tool.
	Rectangle selection: this command enables the creation of a selection by dragging a rectangle.
	Polygon selection: this command allows the addition of nodes to a polygon path using the cursor's left-click. The path is automatically closed by double-clicking.
	Lasso selection: this command allows the selection of the images with the lasso mode.
	Add Mask to selected area: this command allows to add the selection to the current mask.
	Clear mask from selected area: this button allows to clear a selection from the current mask.
	Select auto-magic algorithm model: this button allow to select or download the machine learning model which will be used by the automatic computation algorithm.
	Automatic masking for all images: this button allows to automatically compute all the masks of the remaining images.
	Automatic masking for the current image: this button allows to automatically compute the current image mask.
	Mask from colors: this button allow to create a mask starting from RGB colors. The tool can be use to select a color from the image background and then the <i>Threshold</i> and the <i>Gauss iter</i> settings to set the range of color for masking.
	Invert current mask: this command allows to invert the mask.
	Brush foreground : this command activate the brush tool for marking the image's parts to include in the mask.
	Brush background stroke: this command activate the brush tool for marking the image's parts to exclude from the mask.
	Masks to strokes: this button allow to convert the masks on the current images to strokes.

	Clear mask and Strokes: the command allows to cancel the image current mask and all the strokes made with the brush tools.
	Automated masking after each stroke: this command toggle the automated masking computation after each stroke is marked on the image.
	Compute mask from strokes: this button allow to auto-compute the current image after both Foreground and Background strokes are marked. <i>Note: it can be enabled only when the “Automated masking after each stroke” is disabled).</i>
	Brush size: the brush size slider allows to set the dimensions for the Foreground and the Background stroke tools.

Automatic Masking

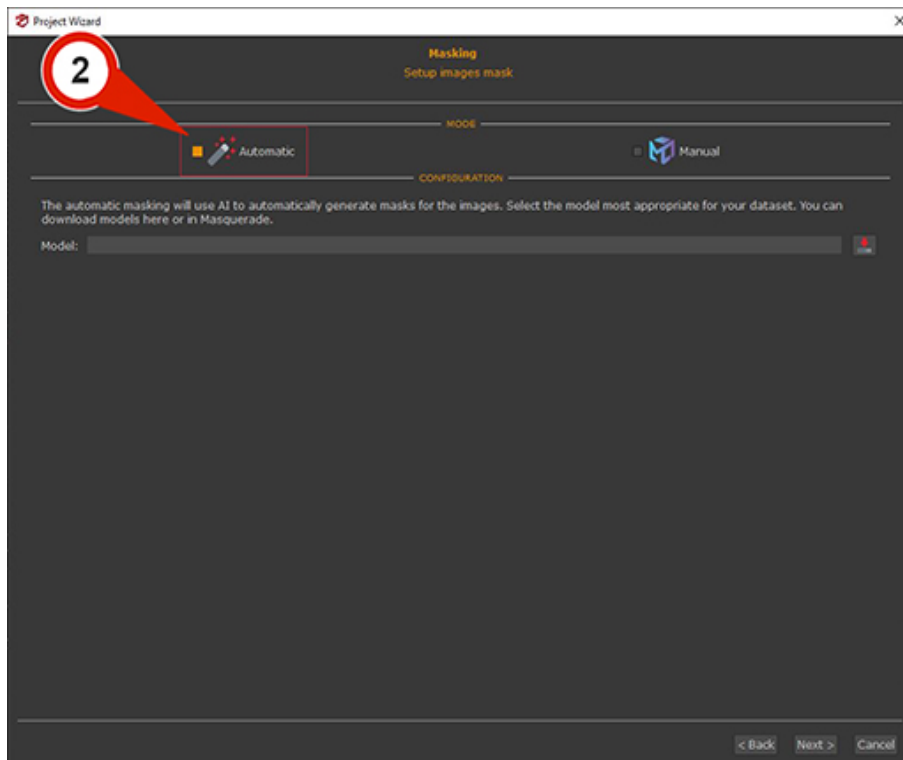
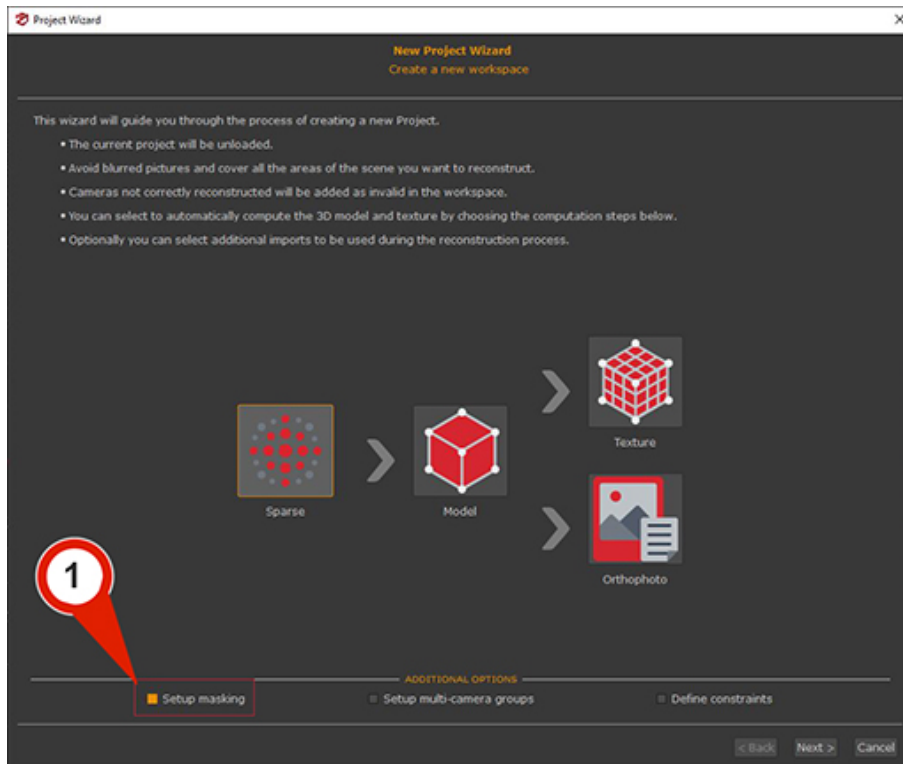
The automatic masking will use a machine learning model to automatically generate masks from images.

Masking can be done as a standalone proces inside Masquerade, or prompted directly in 3DF Zephyr when opening **Workflow > New Project Wizard**.

On the first page, ensure that the **"Setup Masks" (1)** checkbox is selected. Clicking the **"Next"** button advances to the **Photo Selection** phase, where images can be loaded automatically.

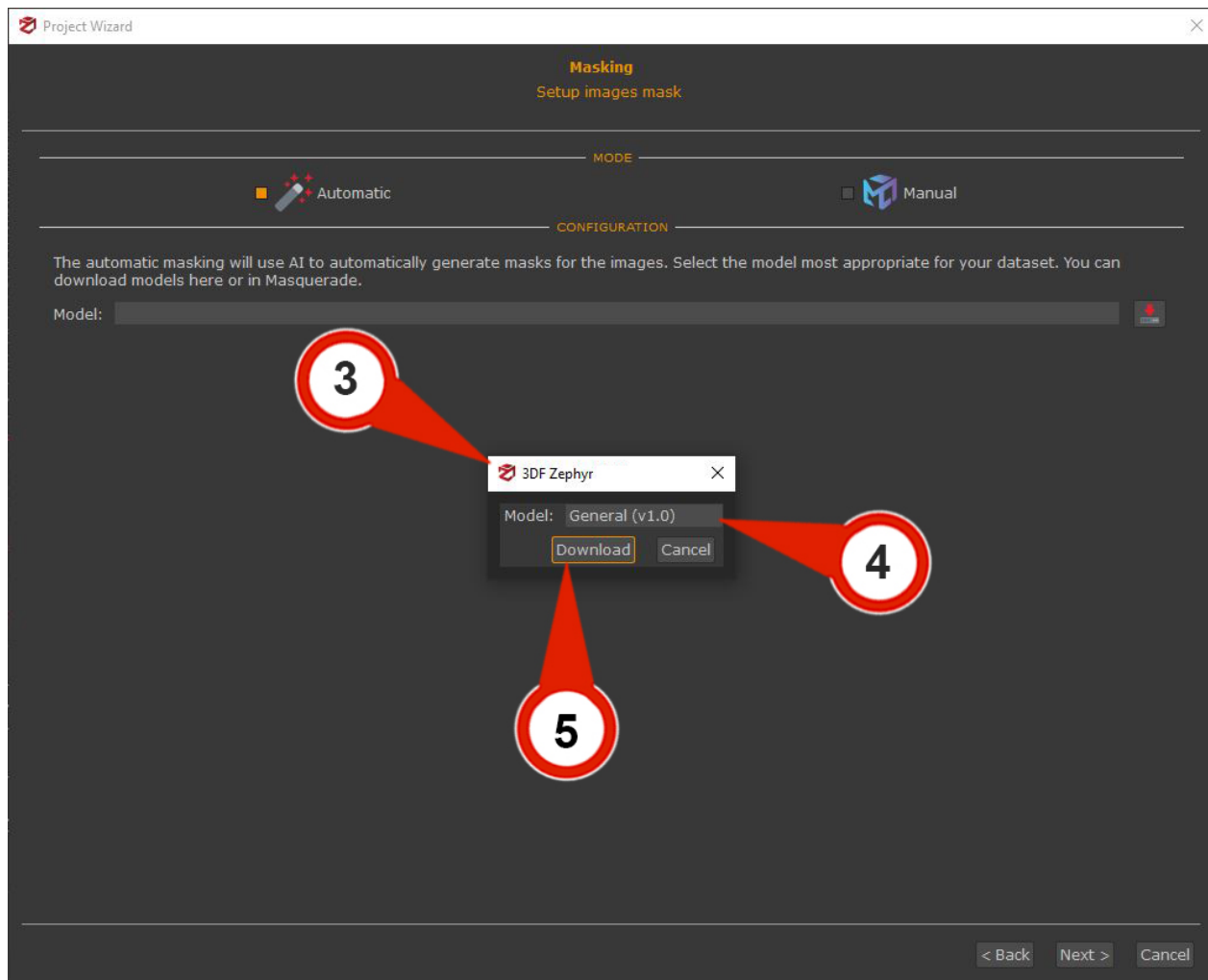
Clicking **"Next"** button again let to proceed to the **Masking** page, where the **"Automatic" (2)** checkbox is selected by default.

To use **Automatic masking**, an AI model must be selected or downloaded from the **Model** dropdown menu. The **General** model is optimized for general use and is particularly effective for close-range datasets.



If no Model is present, just click the **"Download"** button  to open the **Download dialog (3)**. Then, a desired model can be chosen from the **Model (4)** dropdown menu.

After selecting the model, click the **"Download"** (5) button to start the download.



After the **Model** is set, press the **"Next"** button to proceed with the **New project** creation workflow.

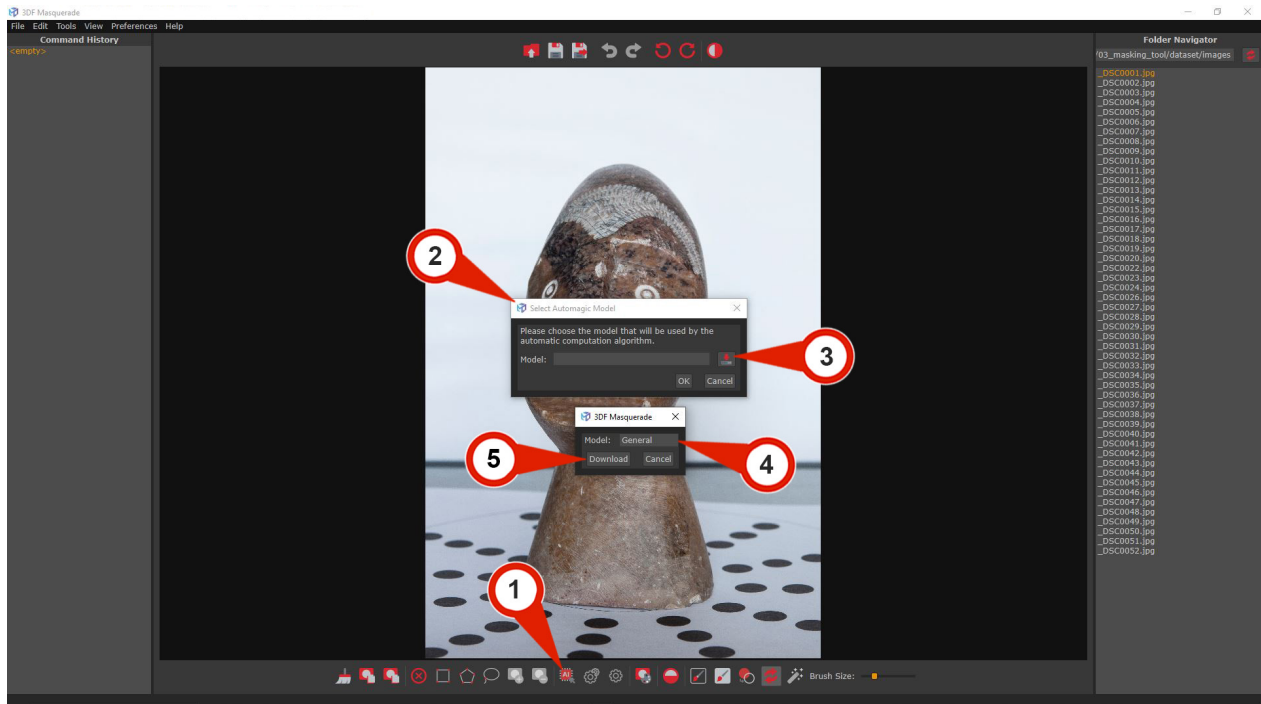
Automatic tool

The automatic masking can be performed by the **Automatic** tool in the **Masquerade interface**.

To use the tool, click the **"Select Automatic Model" (1)** button to open the **Select Automatic Model (2)** window. From there, you can select a machine learning model. If no models have been downloaded, or if you need to download a new one, click the **"Download" (3)** button to open the **Download** dialog.

You can then choose the desired model from the **Model (4)** drop-down menu. The **General** model is optimized for general use and is particularly effective for close-range datasets.

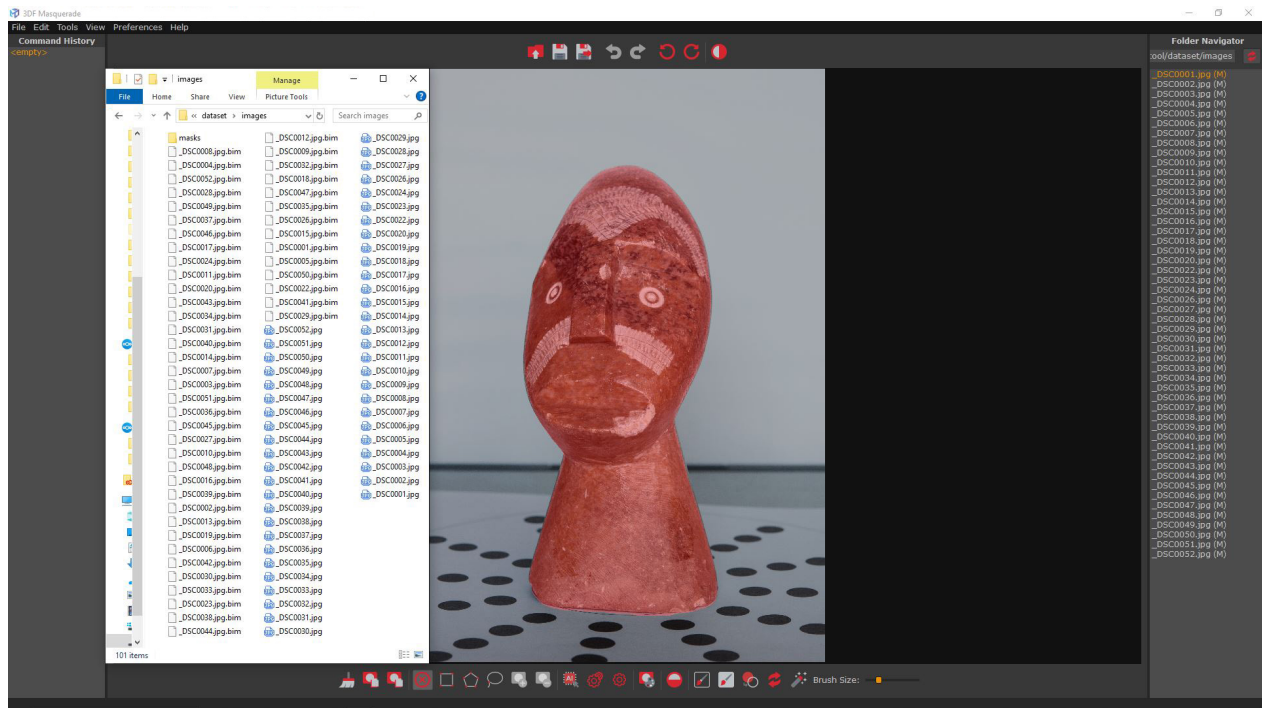
After selecting the model, click the **"Download" (5)** button to start the download.



Once the download is complete, the model will be available for use with the **Automatic tool** to generate masks. The following commands are available in the lower toolbar:

- **“Automatic masking for the current image”** : Generates a mask for the current image. To simplify the process of generating individual masks for each image, the **“Enter”** key can be used to calculate the mask, followed by the **“Space”** key to save the mask and move to the next image.
- **“Automatic masking for all images”** : Automatically generates masks for all images. Clicking on the button a dialog will appear, and choosing **“YES”** will allow Masquerade to generate masks for all images.

All the images in the **Folder Navigator** will be marked with **“(M)”** and each of them will have a mask in *.bim* format saved in the directory.



Manual masking tools

The **Selection tools** allow you to mask specific areas of the subject you are working on. Once a selection is made, it will appear with a blue overlay. When the mask is being applied, the overlay will turn red.

All three tools operate on the same basic principle: simply drag the cursor over the desired area, and then click the “**Mask selection**” button  to apply the mask.

- **Rectangle selection:** drag a rectangle and click the “**Mask selection**” button to mask the selected area.
- **Polygon selection:** use the mouse “**left-click**” button to add nodes to the polygon path and double-click to automatically close it. Press the “**Mask selection**” button to confirm the selected area.
- **Lasso selection:** drag the lasso and click the “**Mask selection**” button to mask the selected area.

A mask subsection can be removed using the “**Clear mask selection**” button



with all the three **Selection tools**.

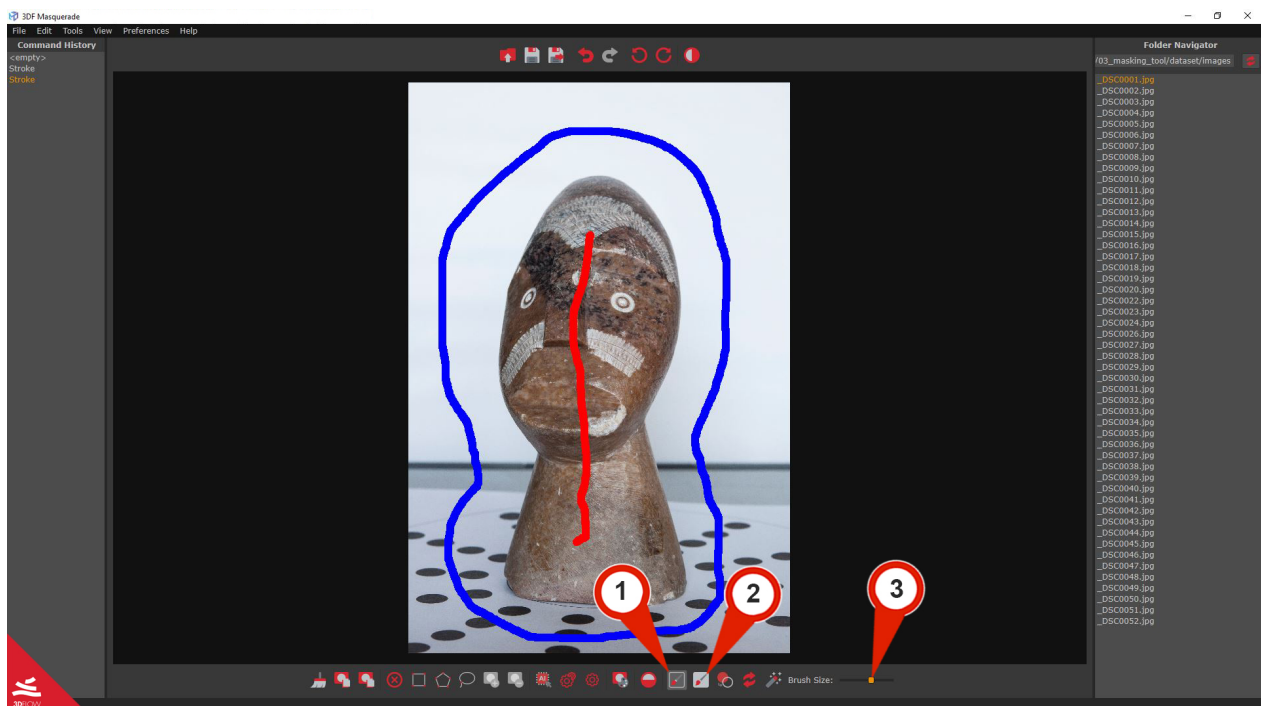
The **Brush tools** (also known as the *Silhouetter tools*) are used to manually create masks or refine those generated by the **Automagic tool**.

3DF Masquerade uses its algorithm to propagate the mask automatically, leveraging the strokes provided by the user. High contrast between the background and the subject improves the tool's effectiveness in generating accurate masks.

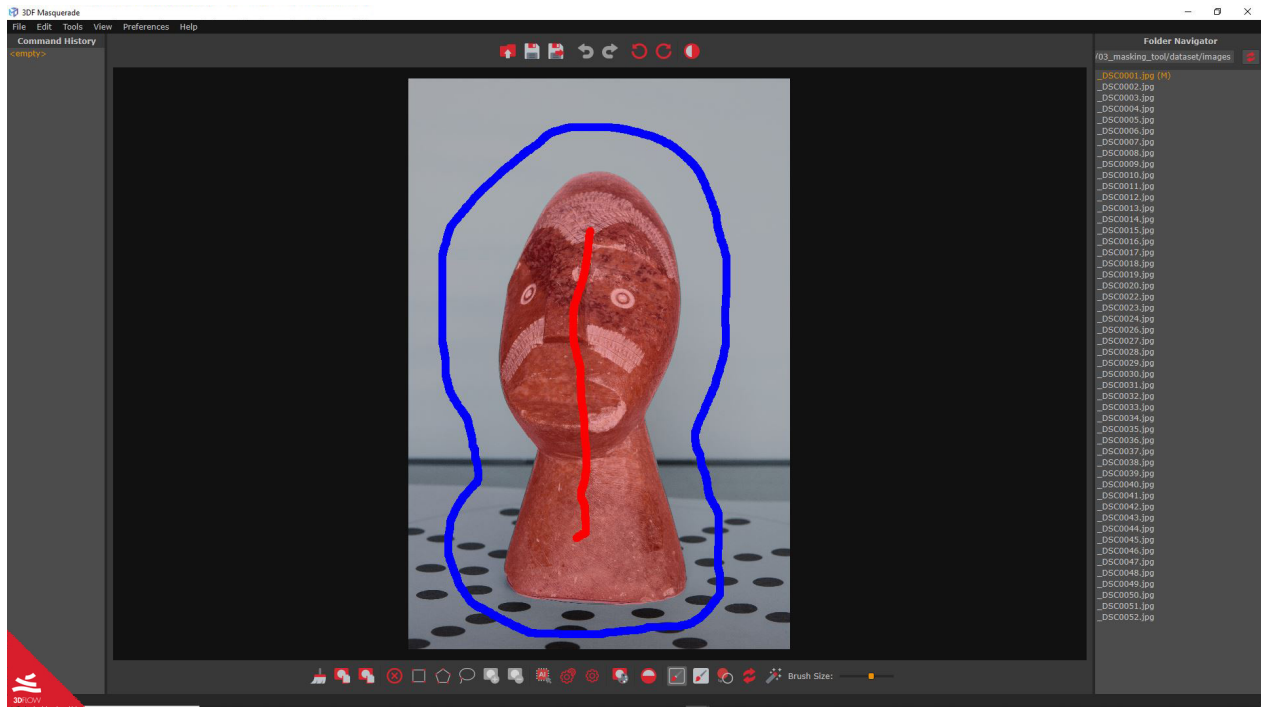
The tool requires at least the following strokes to function:

- **Foreground stroke (red)**: areas marked with the **red stroke** will be included in the mask.
- **Background stroke (blue)**: areas marked with the **blue stroke** will be excluded from the mask.

To start using the tool, click on the “**Foreground stroke**” **(1)** button to activate the **red stroke**, then **left-mouse** to mark areas of the image. To mark the background, either click the “**Background stroke**” **(2)** button or hold the “**shift**” key drawing with the “**left-mouse**” for applying the **blue stroke**. The brush size can be adjusted using the **Brush size slider** **(3)**.



Clicking on the “**Compute mask**” button  will generate the mask propagating the stroke, additionally the **Automated Masking after each stroke** command  can be enabled to compute automatically masks after each stroke applied to the image.



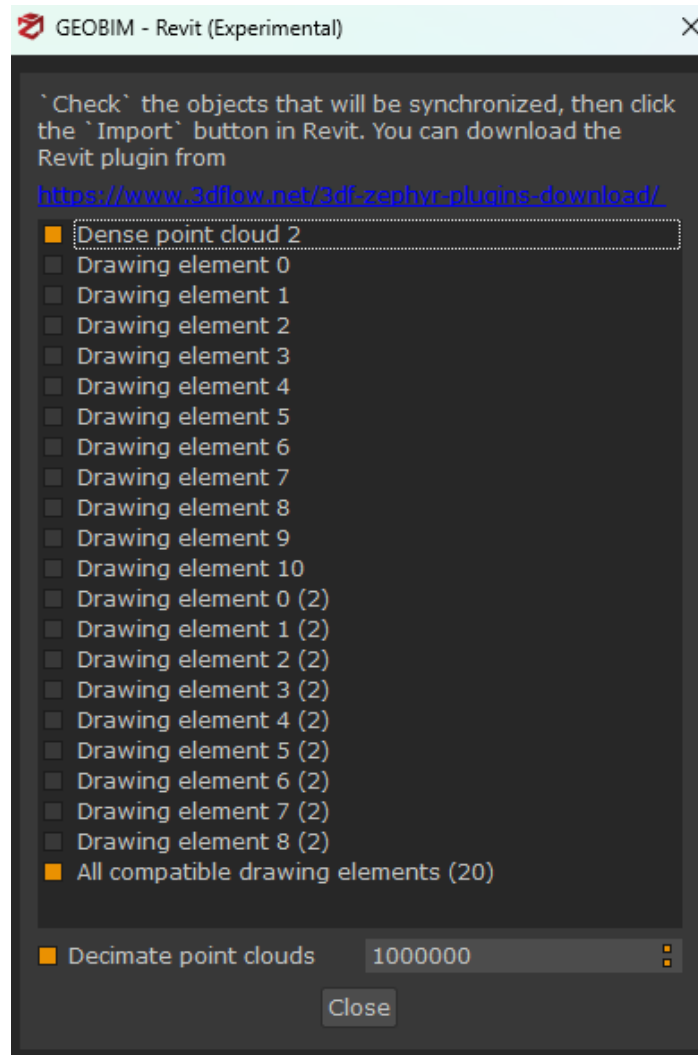
GEOBIM (Revit plugin)

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Using the geobim dialog in 3DF Zephyr you can enable the Revit plugin service that allows for synchronization between the two programs.

Please note that this function is still experimental: you can download the plugin from <https://www.3dflow.net/3df-zephyr-plugins-download/3df-zephyr-geobim-revit-plugin/>

After opening the dialog, you may select the desired elements in the window. Those items will be synchronized in Revit after "Import" has been clicked from Revit, in the "Zephyr Add in" Panel.



You may also decimate point clouds before those are being sent to Revit: this is advised for point clouds composed by more than 2M points. You simply have to select the "decimate point cloud option" and by specifying the desired amount of points to be kept.

Batch processing

This function is not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The **Batch processing** window allows to schedule certain reconstruction jobs. Jobs must be defined via XML files, and they must follow the pipeline workflow, at least partially (this means that you can setup a job from the sparse point cloud generation to the texture mesh generation, eventually stopping at any of the intermediate step, but you can not define a job that starts after a camera orientation).

The xml files must be defined in this format:

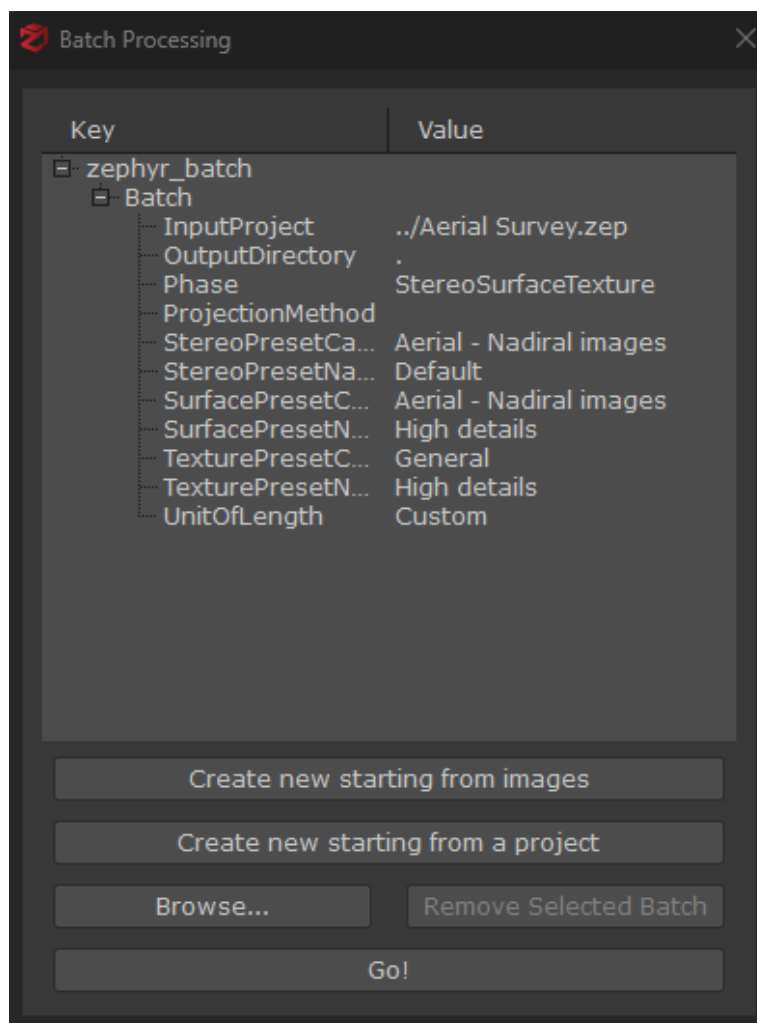
```
<?xml version="1.0"?>
<Settings>
  <Category name="Batch">
    <Entry key="InputDirectory" value="ImagesInputPath">
    <Entry key="OutputDirectory" value="OutputPath"/>
    <Entry key="Phase" value="SamanthaStereo"/>
    <Entry key="SamanthaPresetCategory" value="Urban"/>
  </Category>
</Settings>
```

```

<Entry key="SamanthaPresetName" value="Fast"/>
<Entry key="StereoPresetCategory" value="Urban"/>
<Entry key="StereoPresetName" value="1_Default"/>
<Entry key="SurfacePresetCategory" value="Urban"/>
<Entry key="SurfacePresetName" value="0_Fast"/>
</Category>
</Settings>

```

It is also possible to use the custom parameters directly in the XML. A description of the categories and the parameters is available when selecting "Custom" during the reconstruction wizards or by selecting the properties (with the right click) of an element reconstructed within the workspace. After scheduling one or more job, they will be listed in the interface, from where you'll be able to start the batch operations.



Run benchmark

The Benchmark tool allows to measure the performance of a machine in order to figure out if it is suitable for running a 3D reconstruction using 3DF Zephyr.



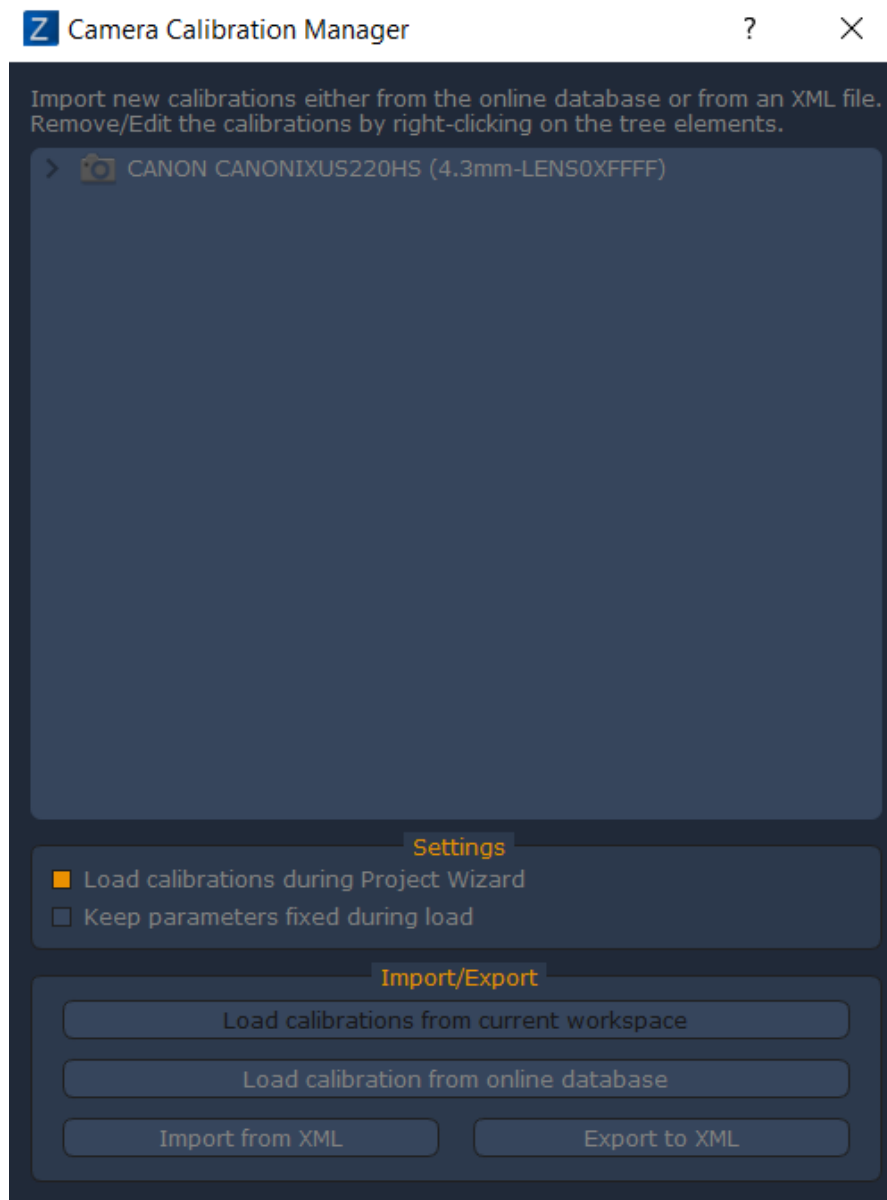
The dialog displays your pc specs, and after you clicked on the **"Run benchmark"** option, you will see the running times for each Zephyr phase and the overall running times.

It's possible to save your benchmark results as an image and text file, or you can anonymously send and share them on the 3Dflow website.

Please note that this function is still experimental.

Camera Calibration Manager

The camera calibration manager allows the user to store camera calibrations on the current system. Although 3DF Zephyr is completely autocalibrated, it is useful to start from a calibrated device when possible.



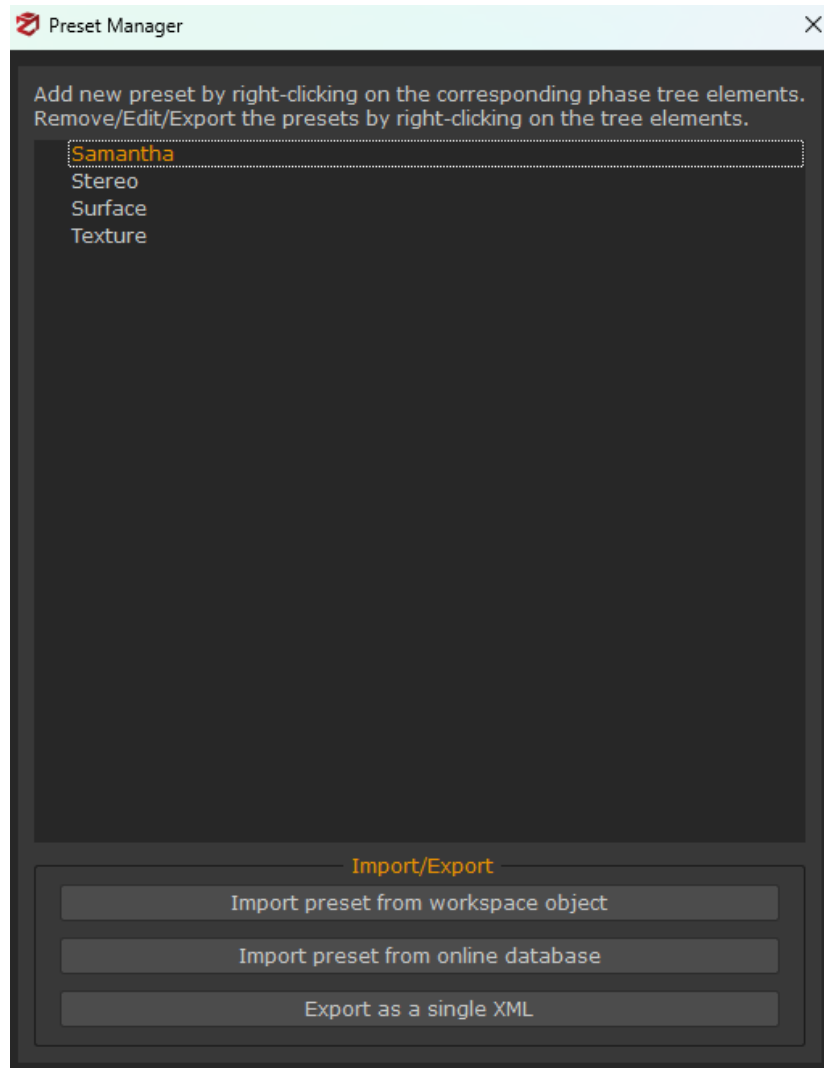
You can import a calibration from the current workspace (if a successful reconstruction has been completed) or you can load it from our online database by simply feeding a JPG (with EXIF data). This service is completely free and anonymous.

You can also import and export camera calibrations from/to XML.

This tool is especially useful for computers working offline, as Zephyr will not be able to check 3Dflow's online database for pre-calibrations.

Preset Manager

The Preset Manager tool allows the user to manage custom presets for processing.



You can import presets from the current workspace (if available) or you can create your own custom one by right clicking the desired category and selecting **"Add preset"**.

If you wish to quickly share a preset with a colleague or a friend, you may also select **"Upload preset"** by right clicking a previously generated preset. Your preset will be uploaded and stored anonymously to our server and an ID string will be shown on screen. You can then select **"Import preset from online database"** using the same ID. Please note that anybody with the ID will be able to download it: this service is completely free and anonymous and 3Dflow does not guarantee persistence of uploaded presets.

You can **export your presets as an .xml file** if needed.

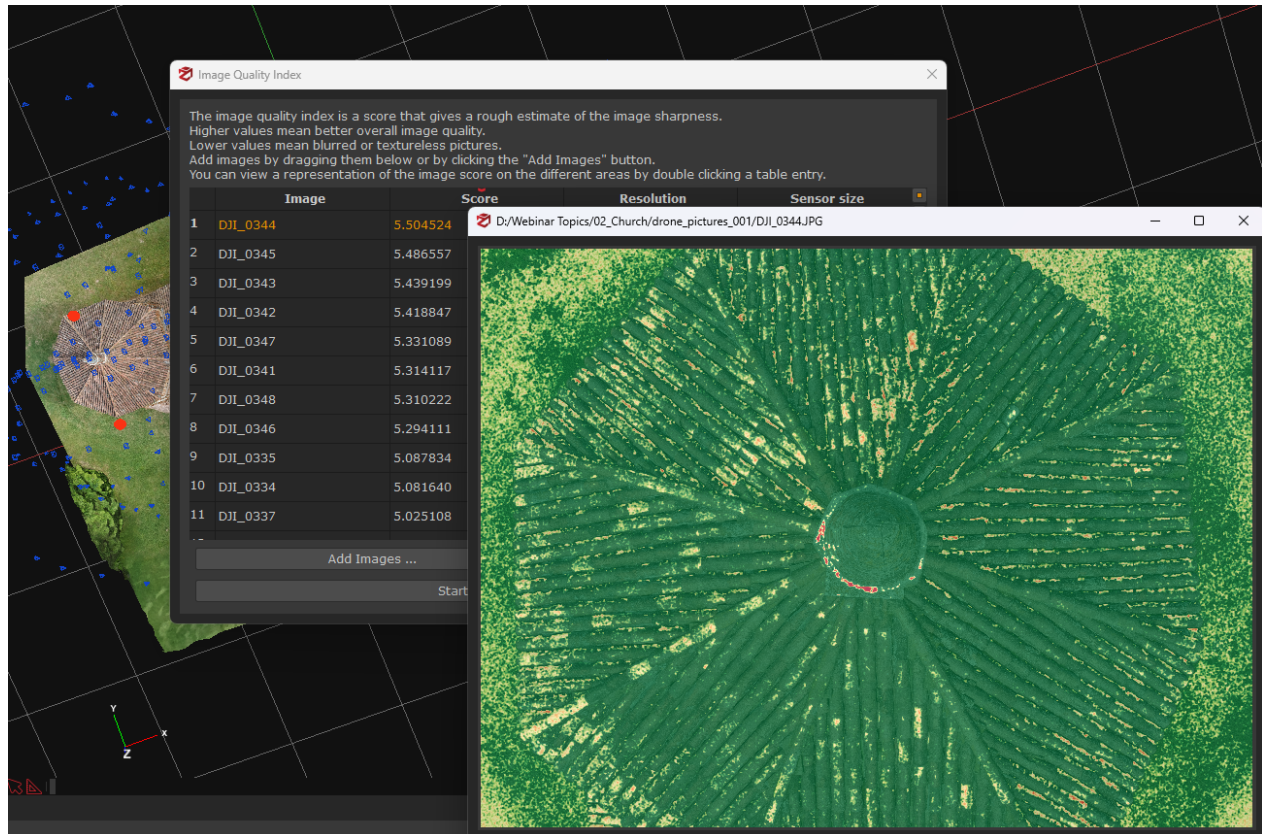
Images

Utilities that apply to images files are all grouped under this sub-menu.

Image quality index

The **Image Quality Index** tool shows a numeric value (and visually in the full version of Zephyr) the quality of the input pictures. You can simply drag and drop the pictures into the quality index window, and the score will be automatically computed. Higher score means higher quality. Please note that this score is computed per picture: it does not use

any 3D information or of workspace information - this will simply compute which areas of the picture are well in focus and potentially with a high density of keypoints. A high-score picture does not automatically mean that a picture has been shot correctly, however a low-score picture should be discarded (in green are shown the better areas). Double click each line to open the visual mode.

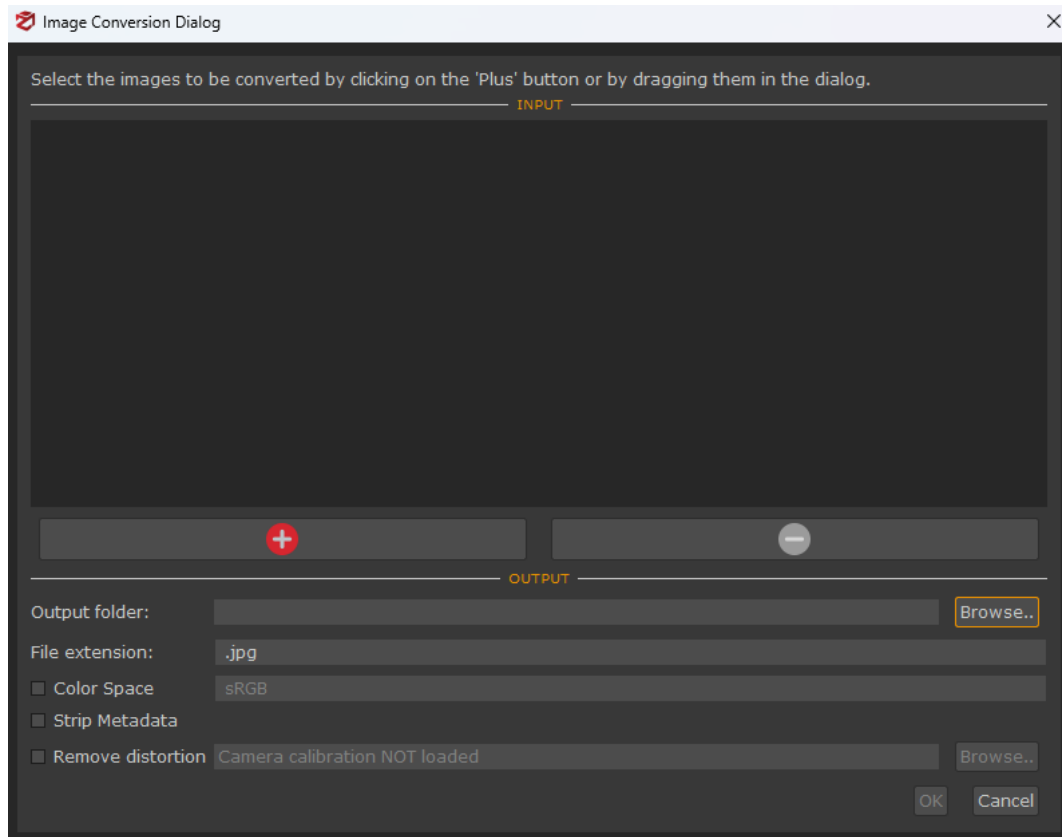


Extract MPO files

This utility allows to extract MPO files. Simply select the MPO files you need to extract by clicking the "+" sign and click OK to start the MPO extraction process.

Image conversion

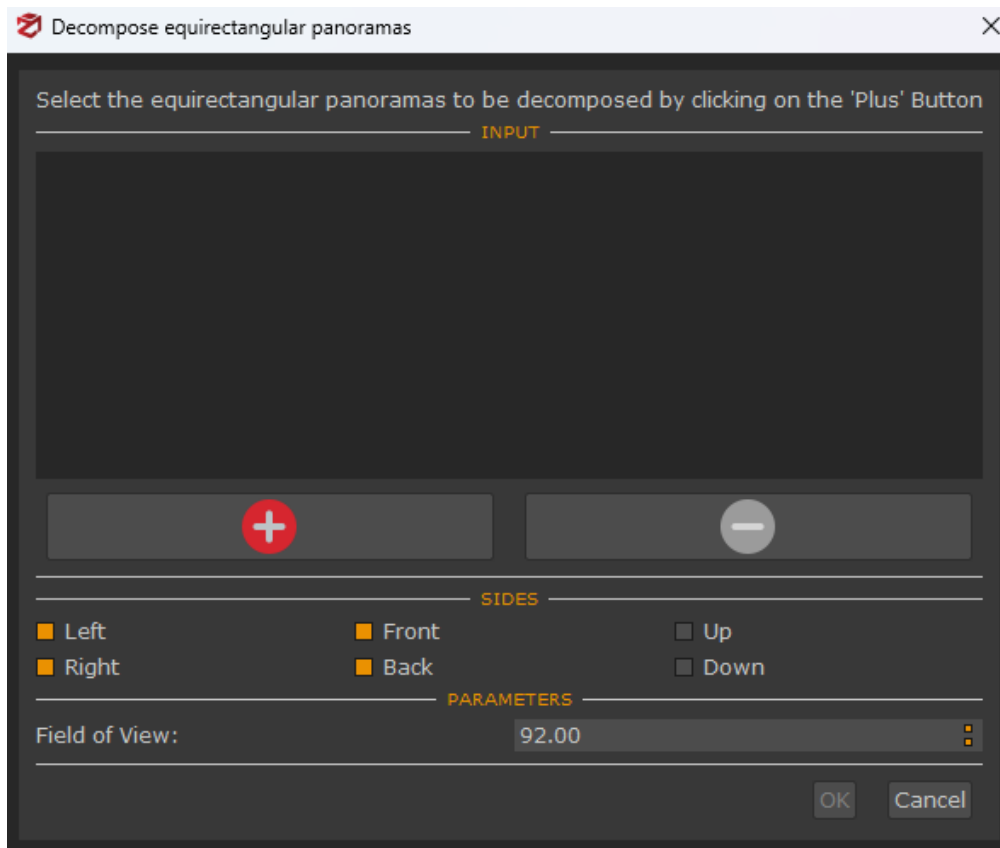
This tool allows to convert pictures to .jpeg, .tiff, .png formats.



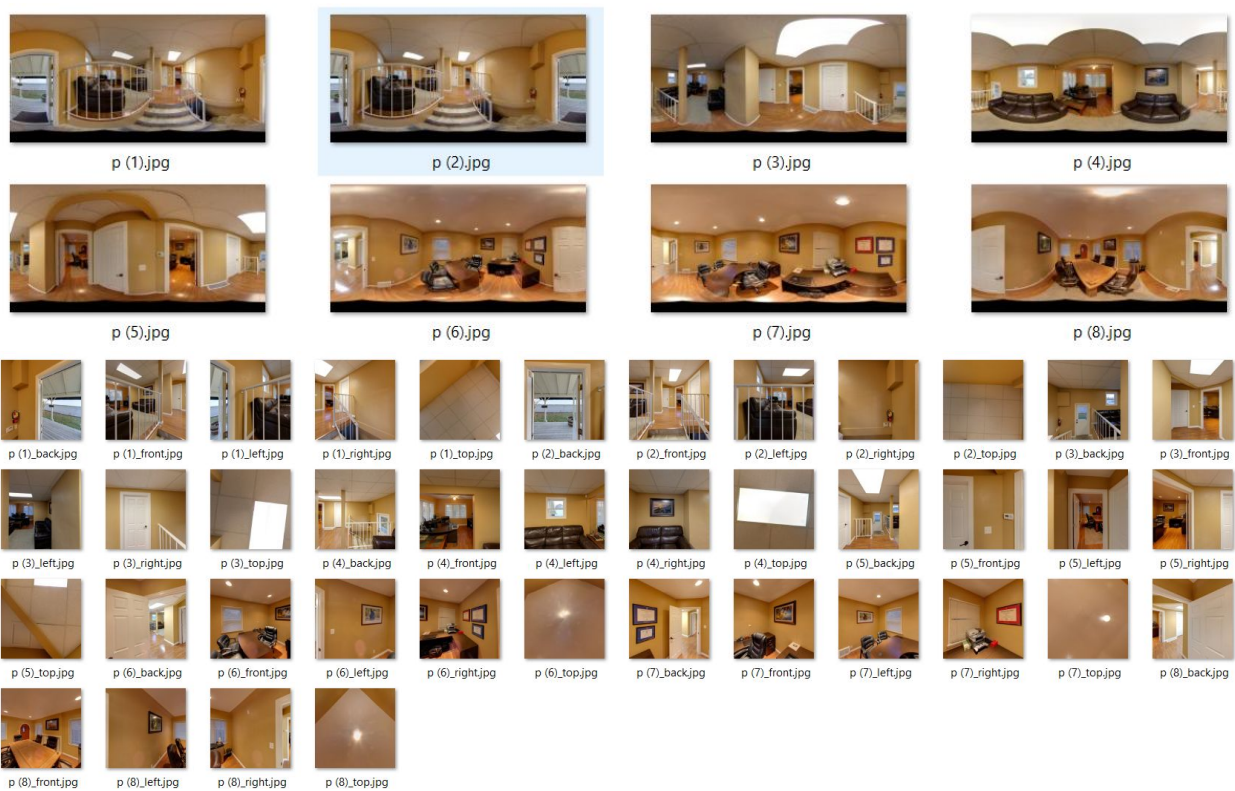
It is also possible to define the color space as well as to apply Gamma correction and to remove picture distortion (the latter option requires a calibration file of the camera equipment to be loaded).

[Decompose equirectangular panoramas](#)

3DF Zephyr can deal with any 360° images by decomposing each picture into 6 pinhole like cameras using the utility "**Decompose equirectangular panoramas**". The images then will be treated normally.



The tool asks to select at least one picture as well as to specify a destination folder.



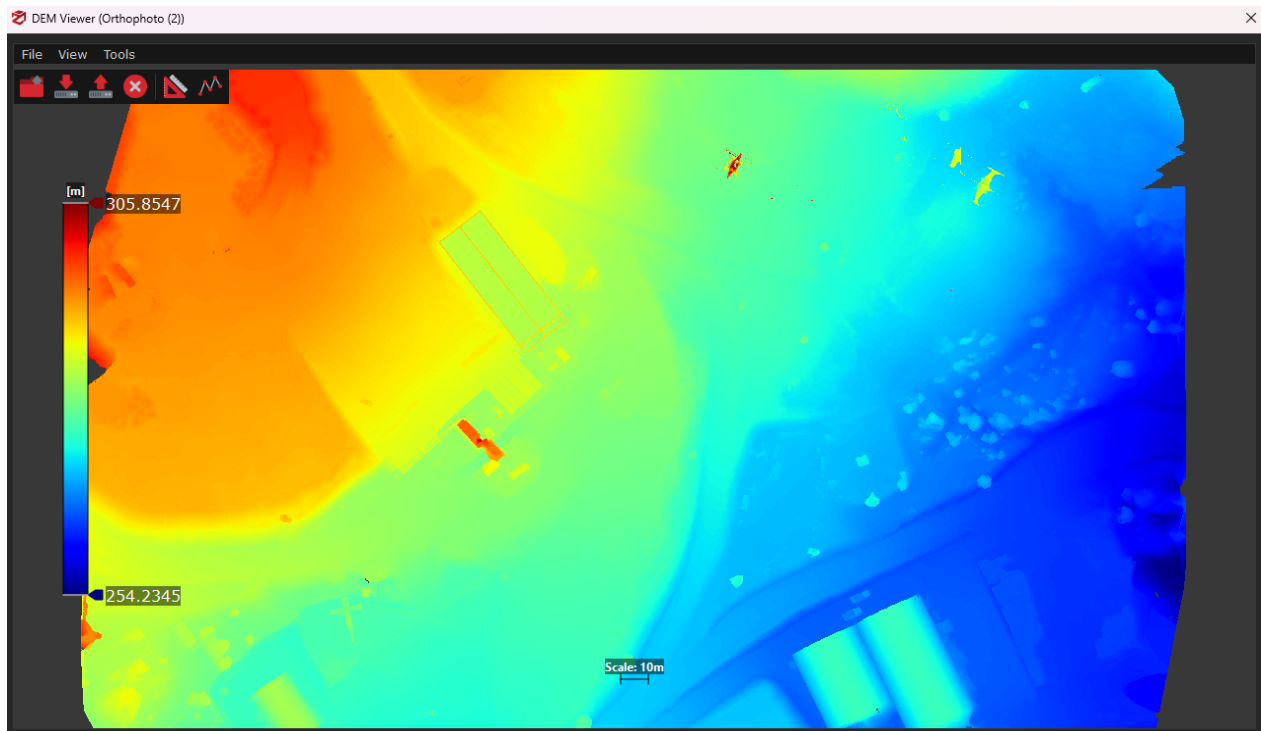
8 panoramas and the resultant pictures after the "Decompose equirectangular panoramas" tool has been exploited

You can select which side of the equirectangular cameras will be extracted by checking the appropriate side. Since v3.700, 3DF Zephyr will optimize the extracted sides and use them as constraints during the Structure from Motion phase as long as the filenames of the extracted cameras will keep the suffixes in the filename (_left, _right, etc.): Zephyr will however ask for confirmation in the project wizard.

DEM viewer and elevation profile

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

The **DEM viewer** utility allows viewing DSM and DTM files directly from the Zephyr UI.

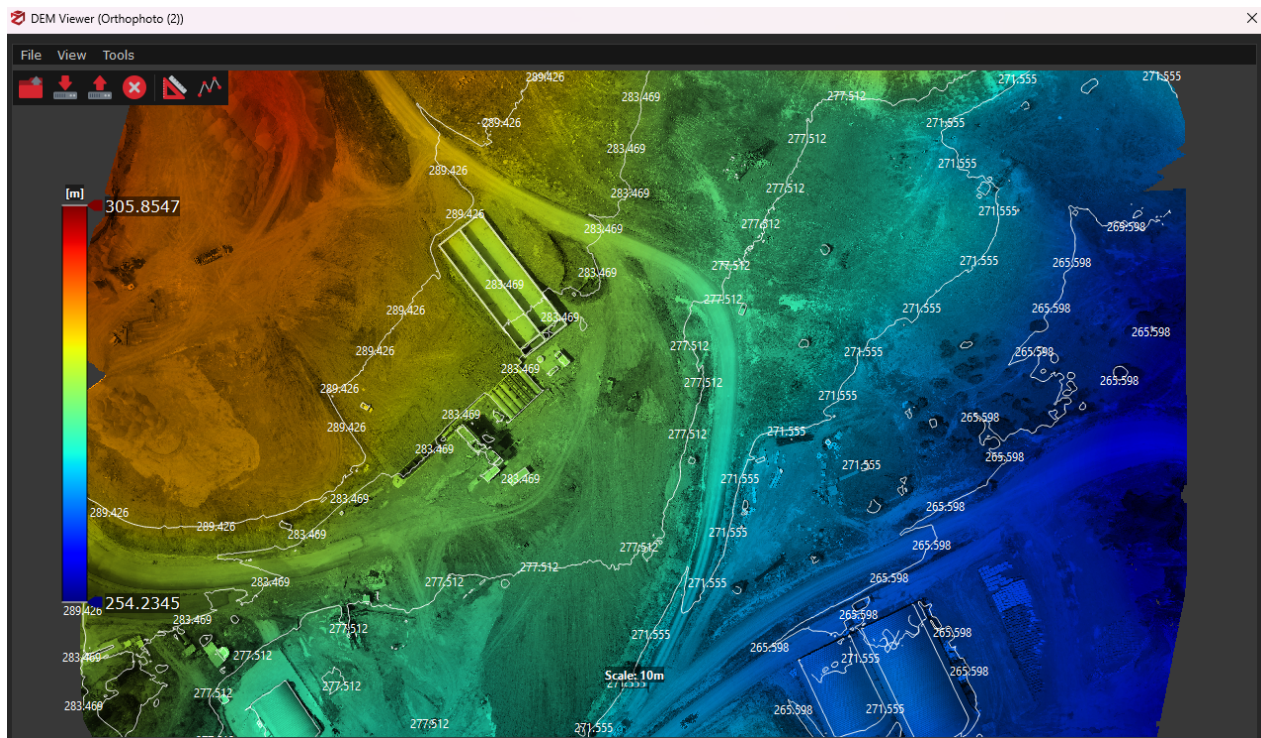


Please note that you are supposed to generate an orthophoto before running DEM generation. To do so, simply click on **Workflow > Generate True Orthophoto from Mesh** and follow the wizard for the orthophoto generation.

The DEM viewer utility can be used to:

- load DSM / DTM and multi-tiled DSM/DTM files (even those not related to the project you are working on) by clicking on **File > Open from file or Open from workspace**;
- load contour lines on DSM / DTM if they have been previously generated in 3DF Zephyr, by clicking on **View > Show polylines**;
- export DSM /DTM as an image (available formats: .png, .jpg, .bmp) by clicking on **File > Export color image**;
- generate elevation profiles;

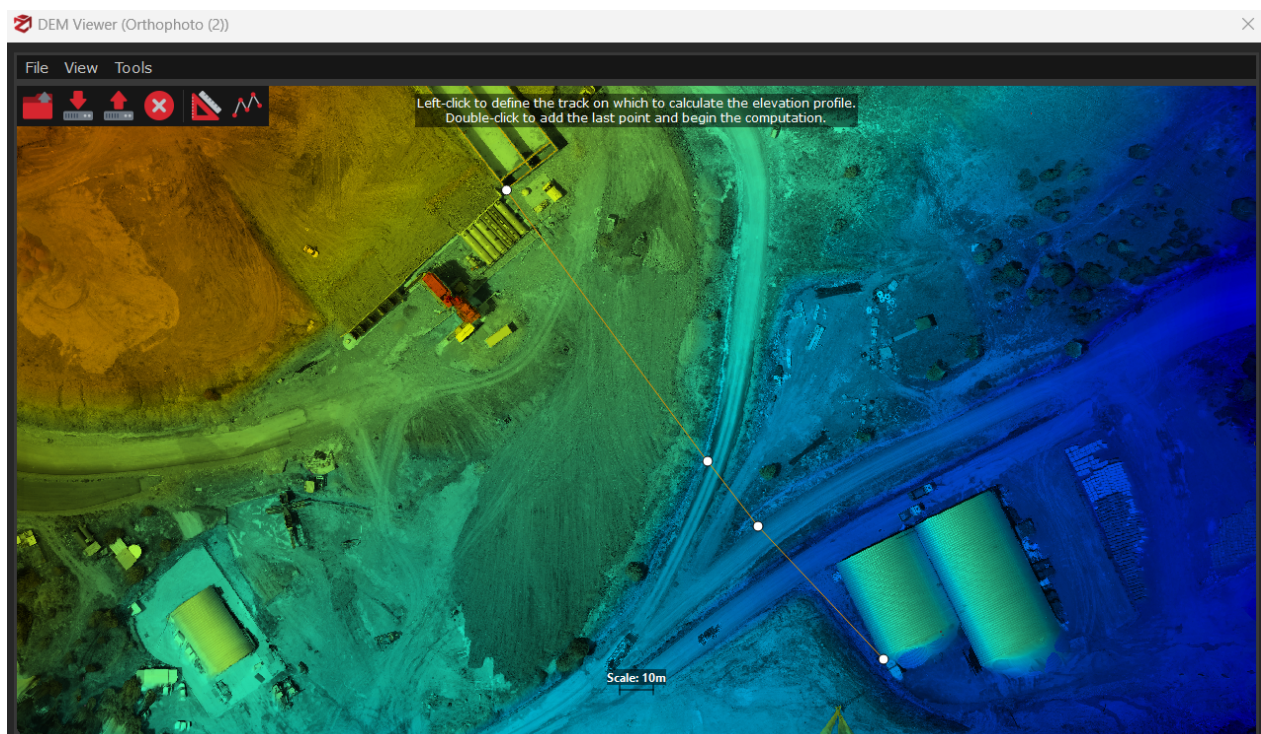
DSM/DTM files and orthophotos are loaded together automatically, provided they are located in the same directory. Here is an example of contour lines, DEM and orthophoto mixed together inside DEM viewer:



Elevation profile generation

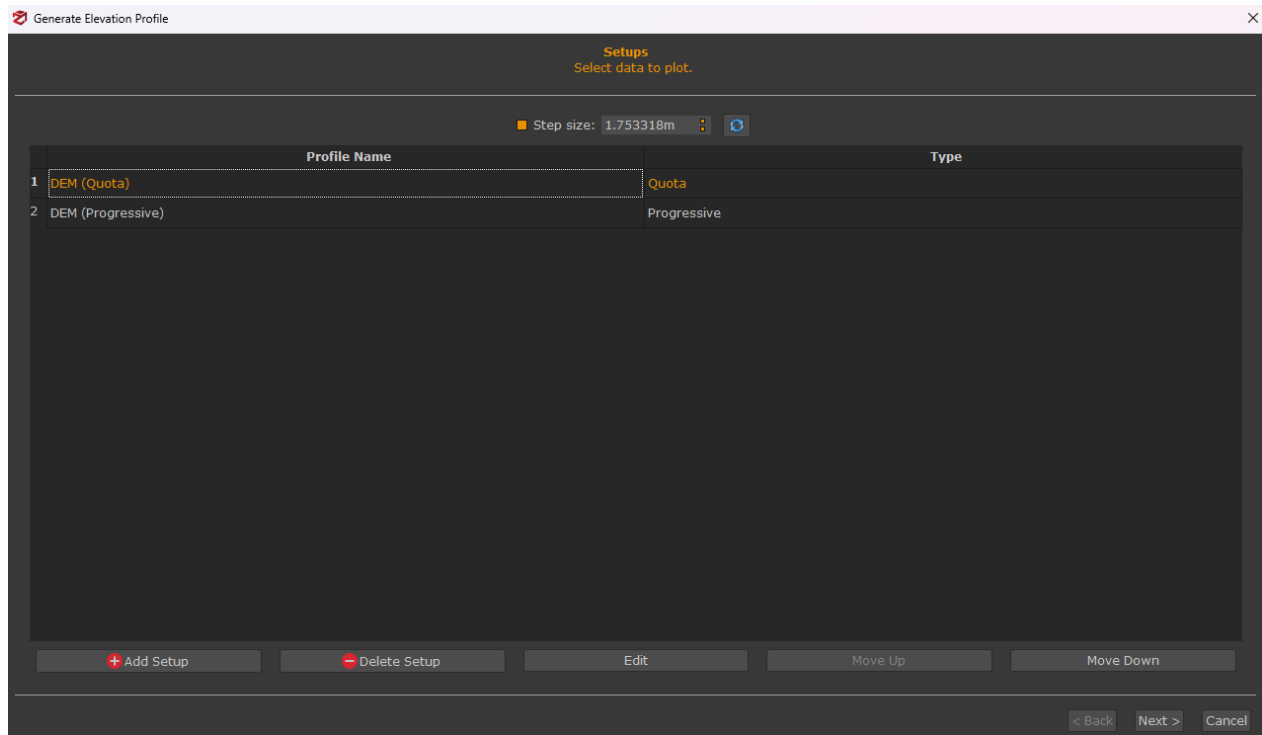
You can generate elevation profiles in the DEM Viewer utility provided that you have already created an orthophoto/DSM/DTM (not necessarily related to the project you are working on).

Simply click on the **Elevation Profile** icon and pick at least two points on the DSM/DTM. Double-click to add the last point and open the setup page. You will notice both the quota and progressive entries are already listed into the chart.

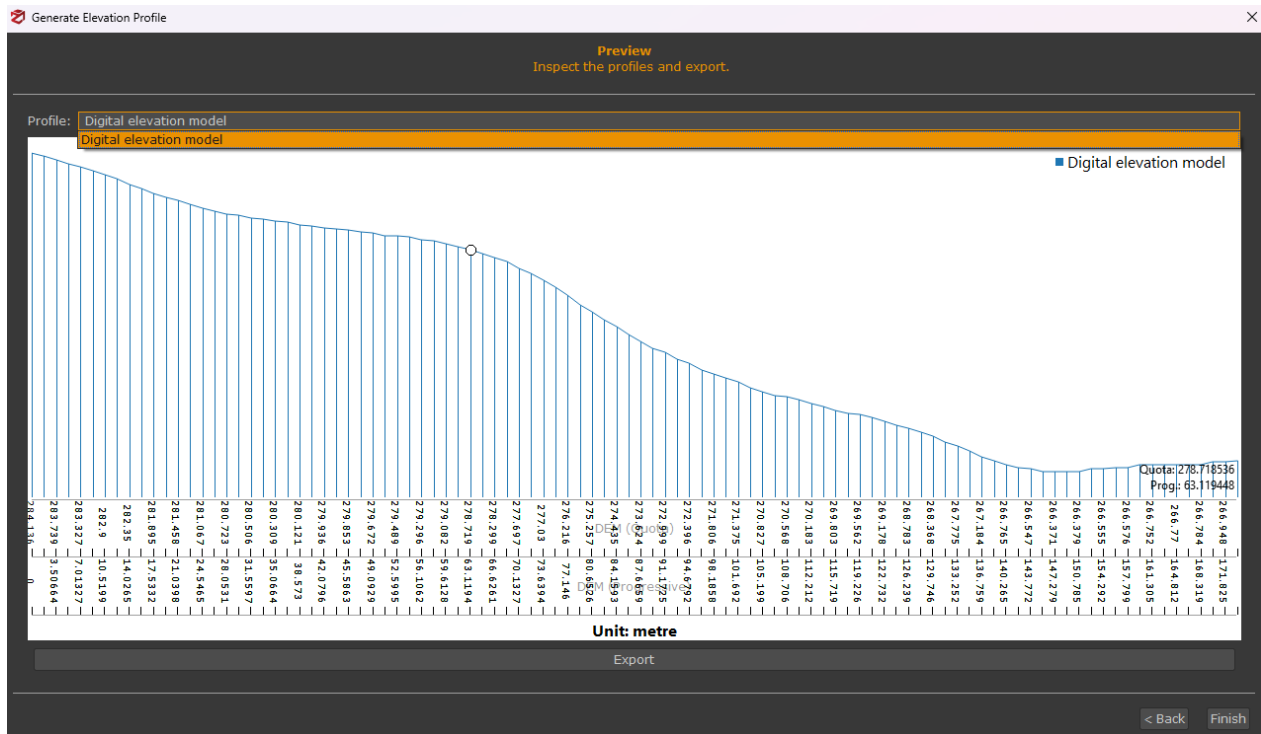


In the setup page you can:

- define the step size and number (distance between each quota/progressive value) in meters;
- add/delete/edit/move up/move down your quota, progressive, latitude or longitude entries clicking the related button;



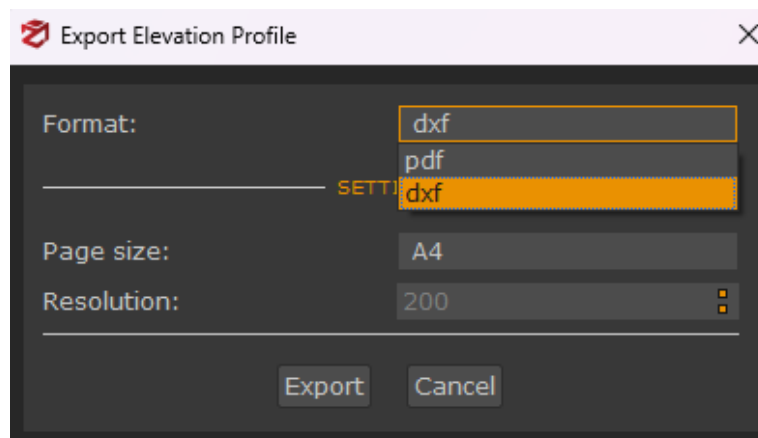
Click **Next** to select the profile you want to generate from the drop-down menu on the preview page, and the elevation profile will be automatically created.



You can click the **Export** button to select the desired format (.pdf, .dxf) as well as the page size and resolution of the .pdf layout.

TIPS

- you can generate an elevation profile from a polyline you have already drawn by clicking **Tools > Sections and Contour lines > Elevation profile from drawing elements** and selecting the desired drawing element using the **Add** button in the Setup page.
- you can generate an elevation profile from a group of control points you have previously placed on the 3D model by clicking **Tools > Lines extraction > make polyline from control points** and continuing the above workflow to generate an elevation profile from a polyline.



You can also calculate distances on the DSM/DTM by clicking on the **Enable measure tool** icon and picking two points on it.

The corresponding distance (meters) will be displayed next to the drawn polyline (see the image below).



Launch camera calibration

The Launch camera calibration utility opens 3DF Lapyx, with an easy to use wizard to compute the camera calibration. Follow the on screen instruction if you wish to precalibrate your camera. You won't need to print anything: the pattern will be shown on the screen and that is what you need to photograph.

Bubble view extraction

This utility allows for extracting bubble views from one or more laser scans. You can choose the image format of the output (jpeg, png) and export the XMPs and the image masks as well.

Multispectral

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

Radiometric calibration and multispectral viewer are accessed from this menu, while [multispectral orthophoto composition](#) is directly managed from the Orthophoto generation function in the Workflow menu.

Launch Radiometric Calibration

These functions are not available in 3DF Zephyr Lite and 3DF Zephyr Free.

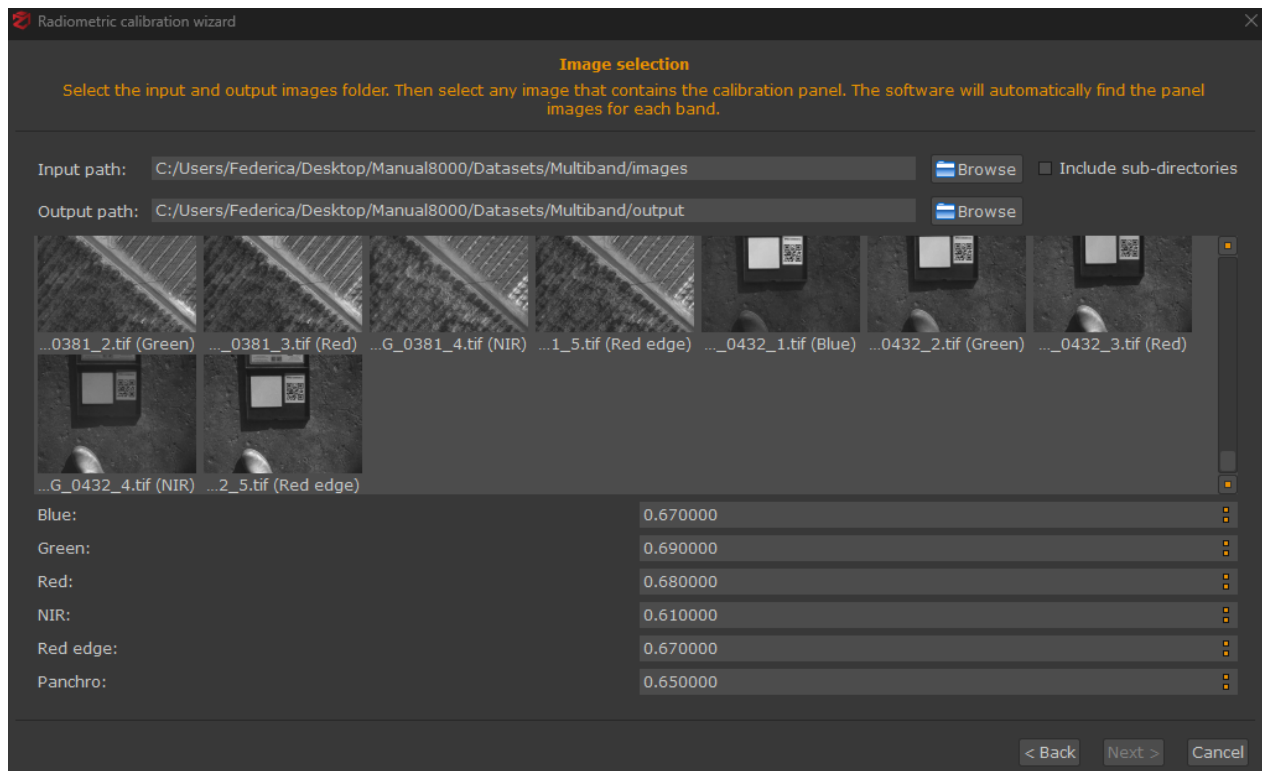
Although not mandatory for processing, it is advisable to take pictures to calibrate your multispectral camera before the actual flight. With this tool, those images can be used for the calibration process.

3DF Zephyr currently supports the MicaSense RedEdge sensor and thermal images taken with DJI devices.

Open the **Radiometric calibration wizard** from the menu: **Utilities > Multispectral > Launch Radiometric Calibration wizard**

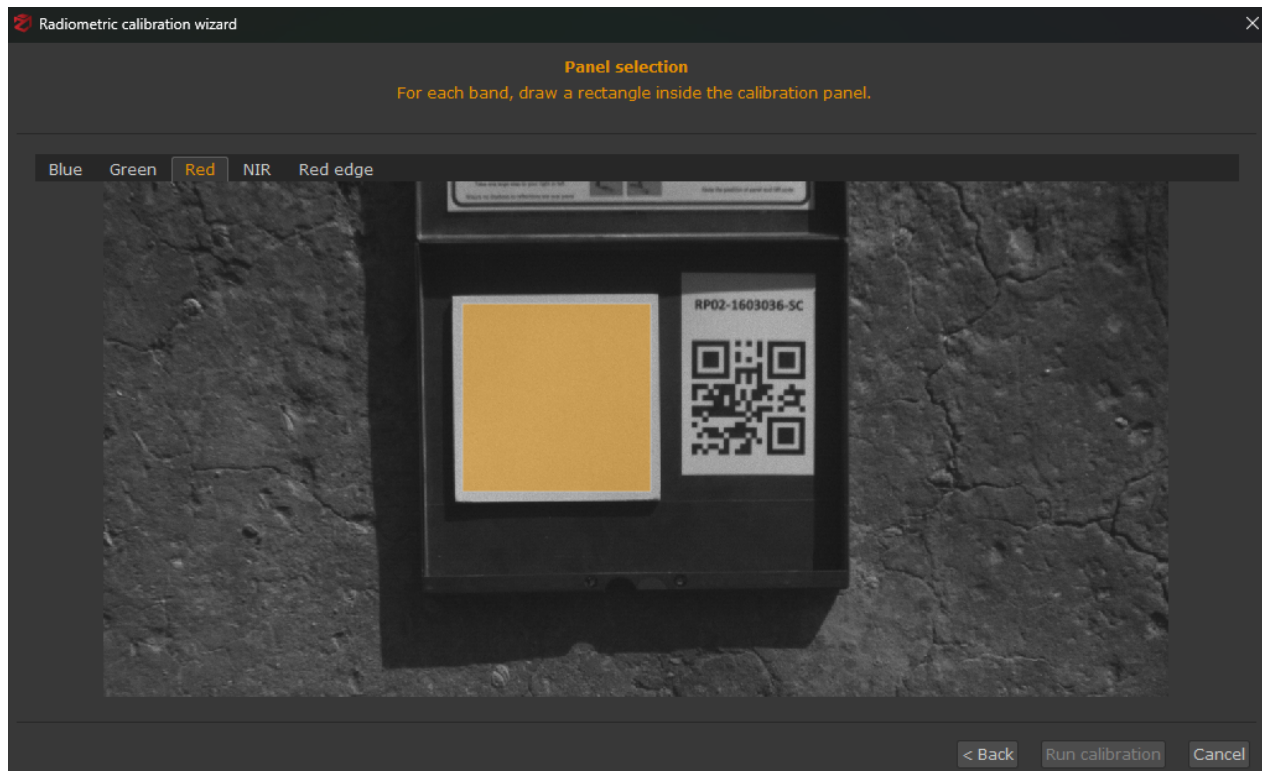
Image Selection

In this page, it's possible to select the input and output directories from the wizard.



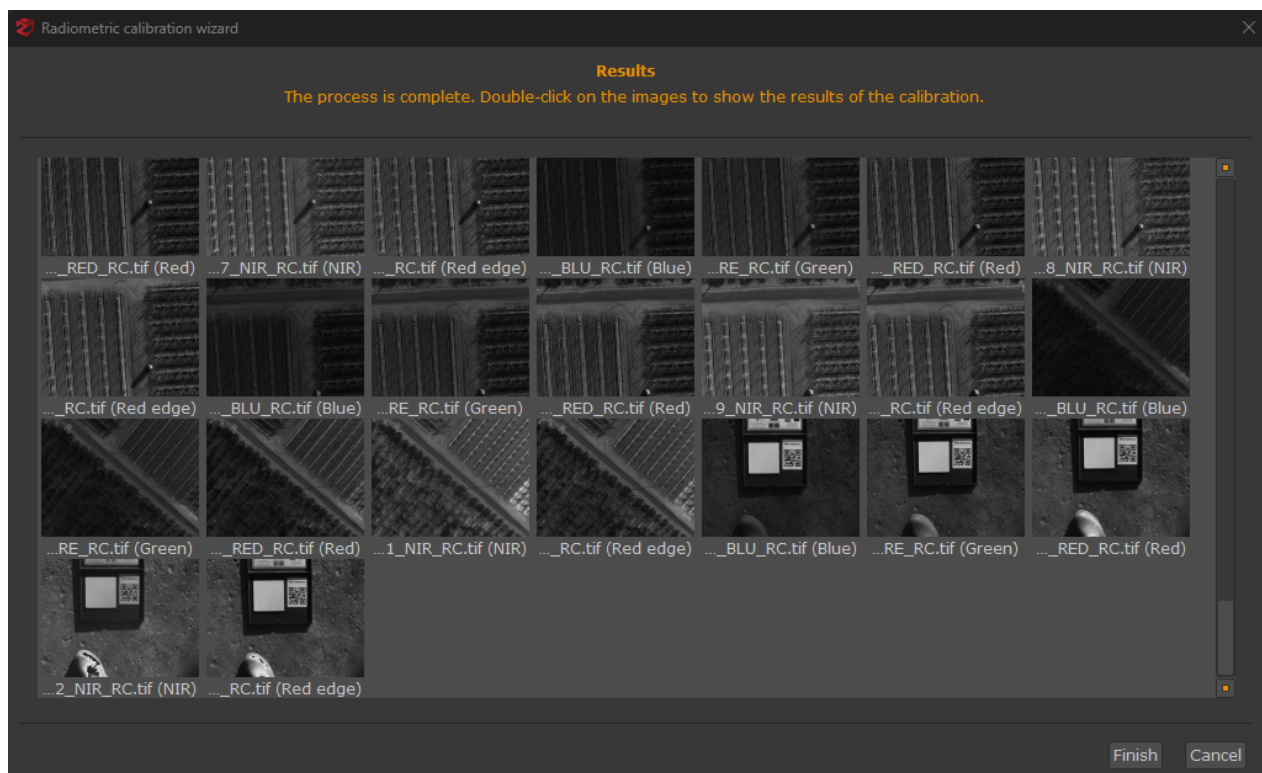
Panel Selection

In order to enable the **"next"** button, you then must select any image that views the calibration panel. 3DF Zephyr will automatically find the panel images for each band. After clicking the next button, you will be asked to draw a square over the calibration panel on each of the available bands.



Once you have drawn the square over all the detected bands, the **"Run Calibration"** button will be clickable. Click it in order to proceed with the calibration process. Once the process is complete, a summary will be shown, where you'll be able to click any image in order to see the result of the calibration.

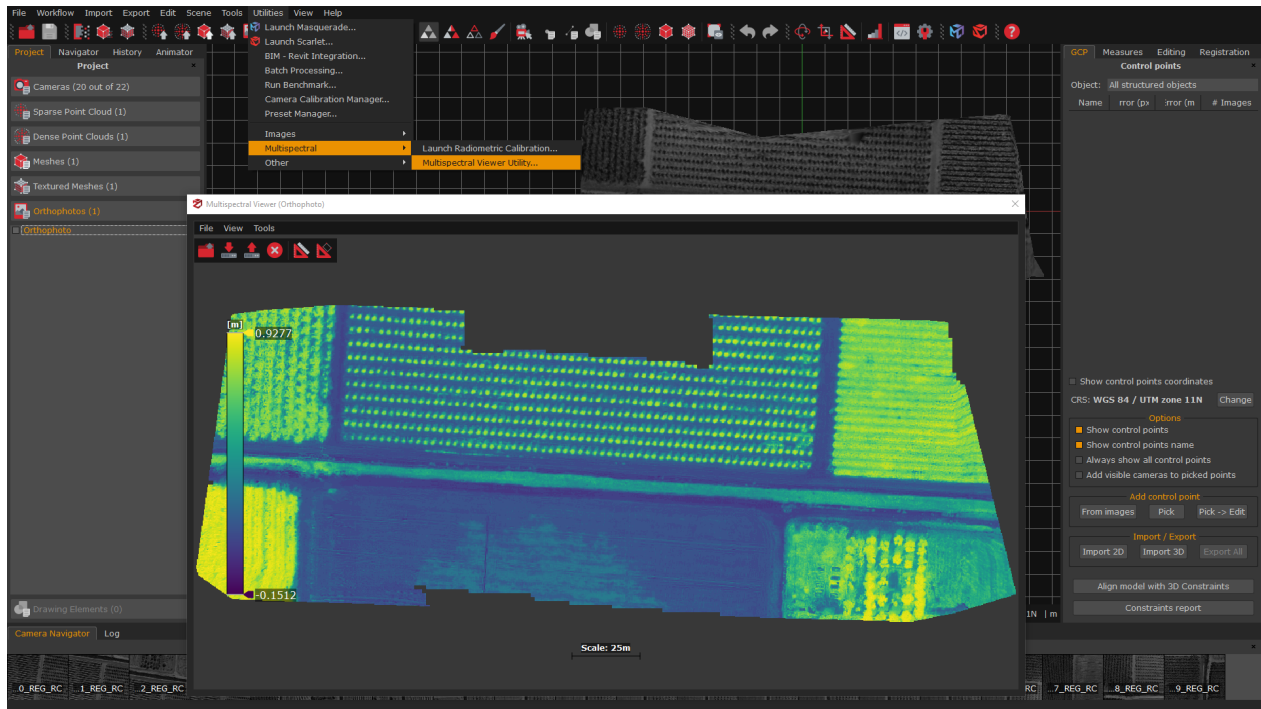
Results



Multispectral Viewer

Similarly to the **DEM viewer**, the **Multispectral Viewer** allows to view TIFF files and make measurements over multispectral images.

The viewer can be opened from the menu **Utilities > Multispectral > Multispectral viewer utility**.



Note: the **Multispectral viewer utility** can be open directly from the **Project** tab and right-clicking on the multi-band orthophoto.

In The **File** menu, you can use the following options to load the images in the viewer:

Open from files option: allow to load tag images in *.tif* format. This command is useful to open and check even those files that are not necessarily related to the project you are working on.

Open from workspace option: it loads the multi-band orthophoto previously saved in the current project.

Export color images option: it allows exporting multi-band orthophoto to one of the following image formats: *.png*, *.jpg*, *.bmp*.

In the **View** menu it's possible to set different color options for visualizing the orthophoto and it's bands:

Band option: it allows to change the orthophoto's bands visualized in the viewer.

Colormap option: it allow to set the orthophoto's colormap in the viewer. The default

colormap is **viridis**, but it can be changed by clicking on it. The **Invert** option will invert the colors and with **Set color map levels** a different numbers of level can be inserted.

The **Tools** menu offers the possibility to make measurements on the multiband orthophoto:

The **Enable distance** tool: it allows you to define and measure distances.

The **Enable area** tool: it allows you to place (at least) 3 points and calculate an area.

The **Color bar** on the left side of the viewer allows you to set the elevation range thanks to the minimum and maximum elevation thresholds.

Other

System Info

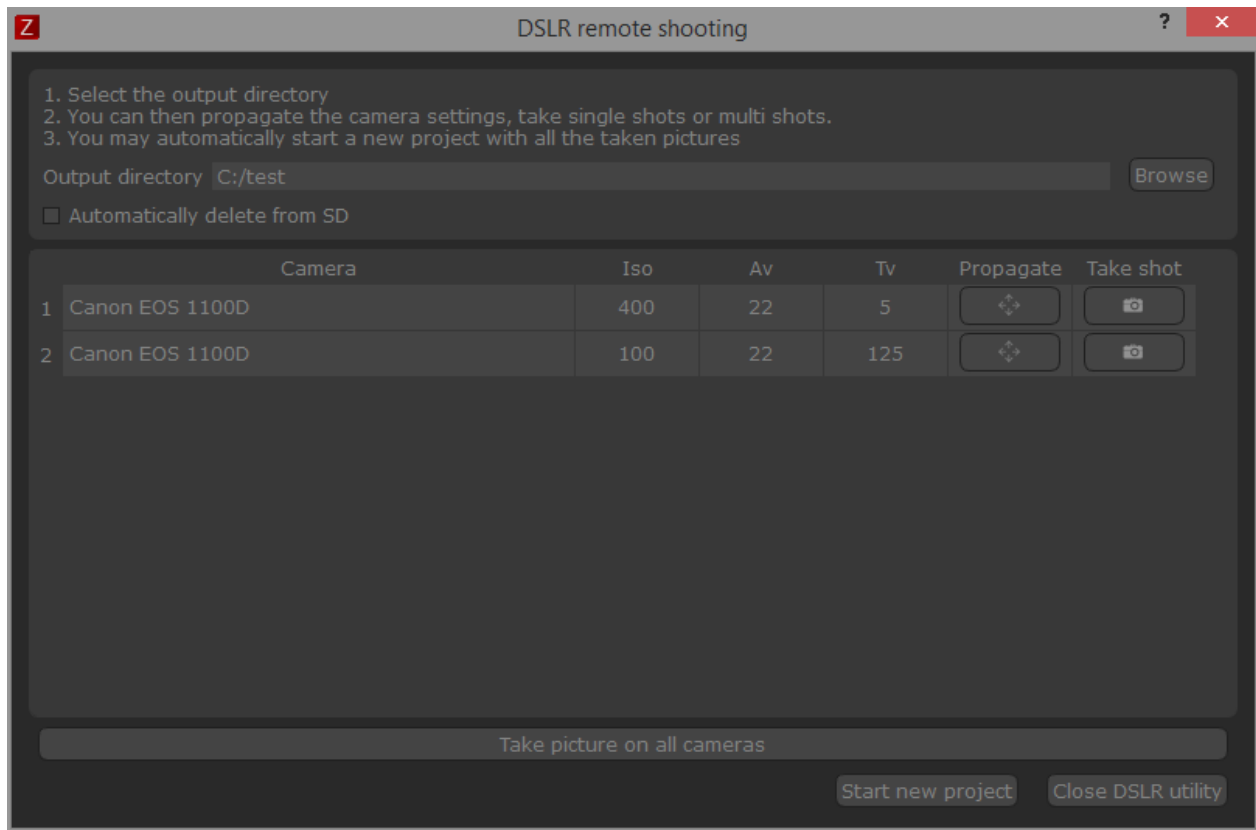
Opens the system monitoring panel. you can toggle the desired information by clicking the desired item shown in the list on the right side of this panel.

DSLR Remote Shooting

This utility requires the download and installation of the DSLR remote shooting plugin available from <http://www.3dflow.net/remote-dslr-sync-shooting-plugin-download-3df-zephyr/>

Please note that this utility is still to be considered in beta. At the moment of writing, this plugin only supports Canon DSLR cameras.

In order to launch this utility, you must first install the plugin: once you have done so, turn on your cameras, connect them to your PC and then launch the utility: the utility will not detect newly connected cameras so you must restart the utility in case you need to connect additional cameras.



Once you have selected the output directory, you will see the detected cameras in the interface as a list : each row corresponds to a camera. You may change ISO, Av and Tv settings physically on a target camera (you will see the changes happen in real time in the cameras list) and then use the appropriate "propagate" button to propagate those settings to other cameras.

Please note that other settings (white balance, etc.) have to be setup manually on each camera.

You may use the appropriate "Take shot" to take a picture from a specific camera or use the "take picture on all cameras button": please note that in this last case, there is a delay (about 100ms) for each connected camera.

If you need synchronization, you should trigger simultaneously the cameras, for example with a radio control.

Notes about the physical setup: although theoretically Zephyr could handle a number of cameras that is limited by the physical USB ports available, it is advised to limit to 16 cameras for notebooks and 32 for desktops. Please also remember that USB cables should not be longer than 5m and if possible avoid using USB hubs.

3DF Zephyr Lite has a hard limit of two cameras.

Handle laser scanner point clouds

Since version 3.0, Zephyr supports laser scan native format files.

In order to install native laser scan support, you have to install the free plugin for the desired format from <http://www.3dflow.net/native-laser-scanner-support-plugin-3df->

[zephyr-download/](#)

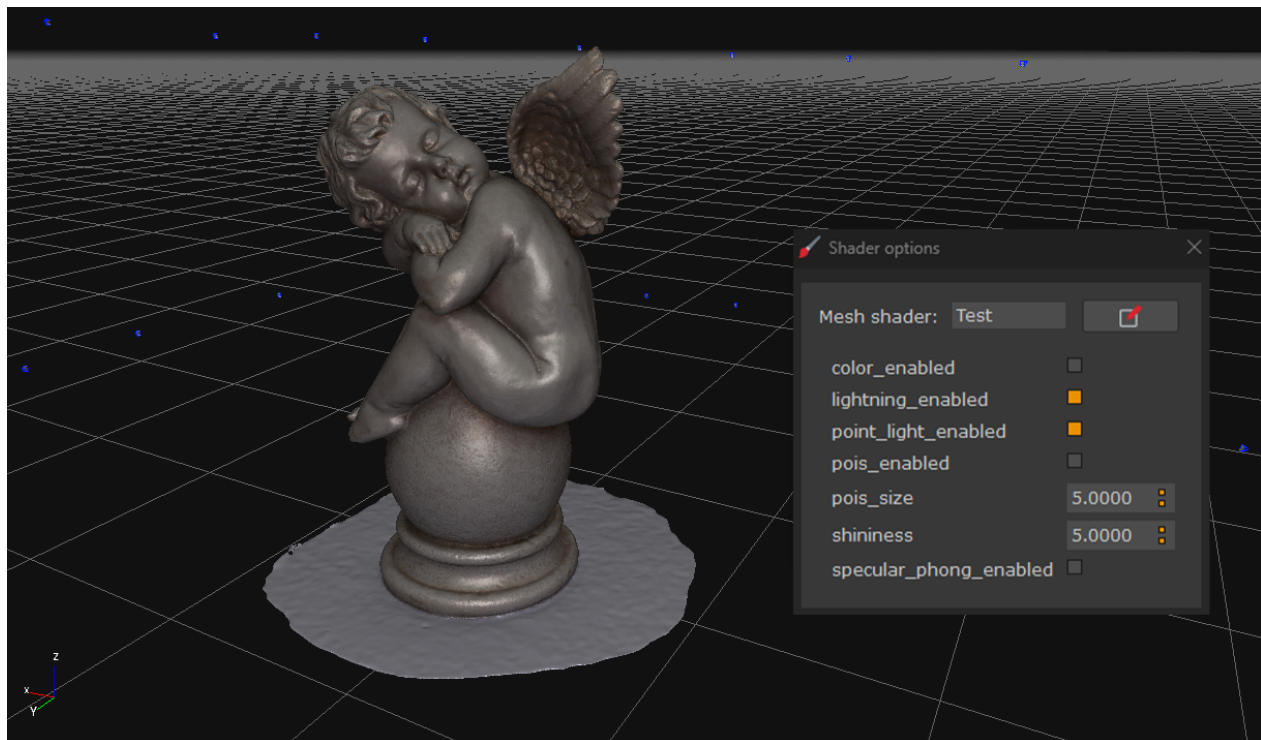
3DF Zephyr Lite and Free can open (as viewer) laser scan format files as well, while the full version of 3DF Zephyr also have the option to import those file in the workspace.

3DF Zephyr supports the following native format files from the following laser scan device manufacturers:

- Faro (.fls, .flw)
- RIEGL (.rdbx)
- Dot Product (.dp)
- Z+F (.zfs)
- Recap (.rcp)

Custom shaders

An alternative shading system is available for advanced users who wish to write and customize the shading used by Zephyr.



You can select the shader using the  button in the toolbar.

You can then switch 3DF Zephyr default shader or write your own. You can find a test shader installed alongside Zephyr.

Troubleshooting

3DF Zephyr is a very complex software: in this section, you'll find some general troubleshooting hints as well as some frequently asked questions.

First ad foremost, please remember that you can contact the tech support at the email

address support@3dflow.net or on the forum at the URL <http://www.3dflow.net/forums/>

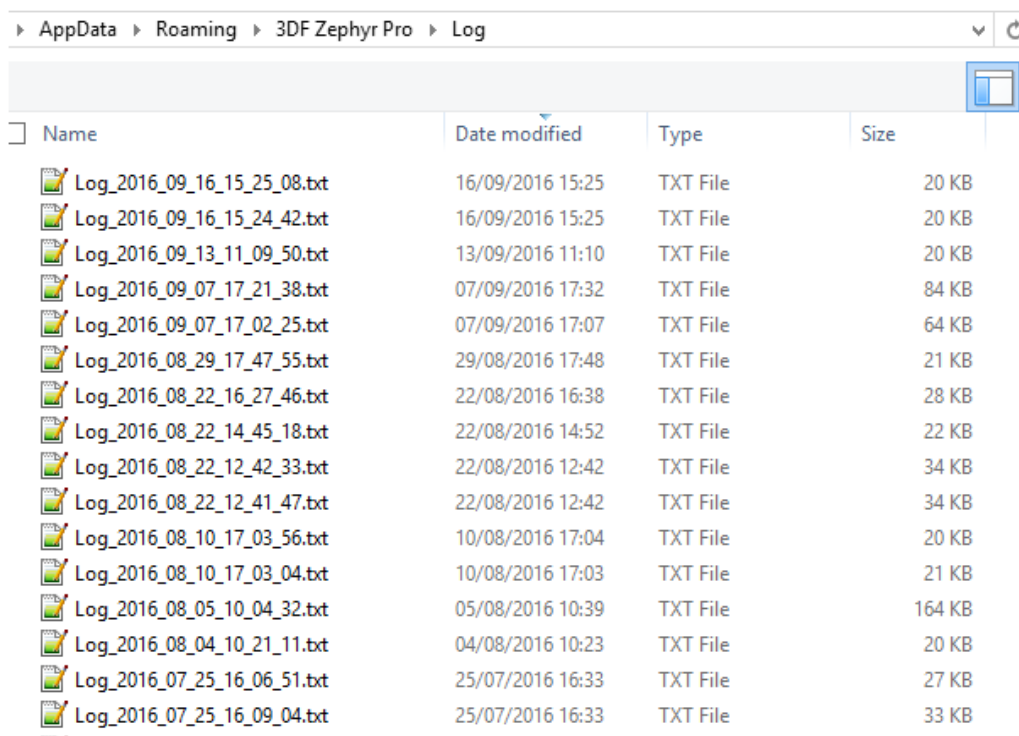
When contacting the tech support, please try to have these information ready:

- **Operating System and Hardware specifications**

It's very helpful for us to know which platform Zephyr is running on. Please let us know, at a minimum, your operating system as well as its hardware specs (at least CPU, RAM and Video Card)

- **Log files**

Zephyr logs a lot helpful information on text files that are saved in your %appdata% directory - you may access this directly easily from the Zephyr options menu by selection the "Application" tab and then clicking on the "Open Log Folder" directory.



Name	Date modified	Type	Size
Log_2016_09_16_15_25_08.txt	16/09/2016 15:25	TXT File	20 KB
Log_2016_09_16_15_24_42.txt	16/09/2016 15:25	TXT File	20 KB
Log_2016_09_13_11_09_50.txt	13/09/2016 11:10	TXT File	20 KB
Log_2016_09_07_17_21_38.txt	07/09/2016 17:32	TXT File	84 KB
Log_2016_09_07_17_02_25.txt	07/09/2016 17:07	TXT File	64 KB
Log_2016_08_29_17_47_55.txt	29/08/2016 17:48	TXT File	21 KB
Log_2016_08_22_16_27_46.txt	22/08/2016 16:38	TXT File	28 KB
Log_2016_08_22_14_45_18.txt	22/08/2016 14:52	TXT File	22 KB
Log_2016_08_22_12_42_33.txt	22/08/2016 12:42	TXT File	34 KB
Log_2016_08_22_12_41_47.txt	22/08/2016 12:42	TXT File	34 KB
Log_2016_08_10_17_03_56.txt	10/08/2016 17:04	TXT File	20 KB
Log_2016_08_10_17_03_04.txt	10/08/2016 17:03	TXT File	21 KB
Log_2016_08_05_10_04_32.txt	05/08/2016 10:39	TXT File	164 KB
Log_2016_08_04_10_21_11.txt	04/08/2016 10:23	TXT File	20 KB
Log_2016_07_25_16_06_51.txt	25/07/2016 16:33	TXT File	27 KB
Log_2016_07_25_16_09_04.txt	25/07/2016 16:33	TXT File	33 KB

Make sure to attach the relevant log files in order to help us pinpoint the cause of your issue.

After contacting us, you will be contacted by our tech support.

FAQs

Some common questions can be answered here:

I get a numeric error message on startup and Zephyr cannot be activated, what can I do?

Make sure that you are connected to the internet when activating your product and that the time and date on your system are correct. If you are using a trial key, please remember to activate it within 14 days of generation.

Zephyr can't write on hard disk, what can I do?

Make sure that no other software is preventing Zephyr to access the file system. In any case, you may specify an arbitrary temporary directory from the options menu.

Can I install 3DF Zephyr on more than one computer with one license?

You can uninstall and install 3DF Zephyr as many times and on as many computers as you need. The only requirement is that there can be only one simultaneously installed copy of Zephyr on your computers. If your license allows you more than one installation, then that limitation applies.

I'm experiencing problems/crashes with 3DF Zephyr. What should I do?

3DF Zephyr is a complex software, so it's hard to tell without further information. Post on the forums or send us an email, describing your problem and don't forget to attach the logs!

How do I use the developer console?

Please consider that this feature is for support only, things will break if not used correctly. The console uses LUA 5.3.1 but no external dependencies are needed.

Which is the difference between Constraints and Control points?

Let's think about an aerial capture where you have both coordinates taken by a GPS system on drone and some coordinates on the ground taken with a total station for instance.

After you have placed your points in Zephyr, you can choose which points must be the constraints, namely the points you are confident (of their accuracy) the most, and which points will be taken into account as simple references.

The first group will be the points taken on ground with the total station since their accuracy is definitely higher than GPS coordinates taken by the GPS system on drone, that represent the second group.

How can I ignore GPS data before performing my 3D reconstruction?

Simply click on Tools > Option > Application and disable "Allow Structure from Motion to use GPS information from cameras" option.

Which is the difference between structured objects and unstructured objects?

An object (photogrammetric clouds or scans) can be named "structured" when it includes the origin's point of its element (laser scanner devices rather than pictures). Native laser scanning file formats usually include the origin's point as well as other formats such as the E57 one. Other formats such as the .las one never provide the origin's point.

Performance tweaking

Please always make sure that Zephyr is running on a computer with the latest NVIDIA and CUDA software updates (when possible).

3DF Zephyr takes advantage of the CUDA technology, so running Zephyr on a machine with one (or more!) NVIDIA cards is strongly advised. If you are considering an hardware update, make sure to consider:

- adding a SSD drive if you don't own one already
- adding an NVIDIA card
- adding more ram (depending on the size of your datasets)
- using a faster CPU

Disable coloring if you don't need it

If you are only interested in getting a textured model, there is no need for the intermediate steps to compute the color in the point cloud and mesh generation. You can disable coloring from the general application options dialog. You may also right click an element and select "update colors" if you wish to compute them for a specific one.

Use a unified and persistent cache directory

You can also use a unified and persistent cache directory. Please note that this is not the default behaviour, as it will use a lot of available space and you will have to manually clean it.

We strongly suggest you run 3DF Zephyr on a workstation that has a SSD drive. If your windows installation is on a mechanical drive and you have another SSD drive, you may also consider switching the temporary directory on that drive.

Running Zephyr via remote desktop

Zephyr requires OpenGL 1.4 in order to render its interface: please keep in mind this when controlling Zephyr via remote desktop (both from a physical machine or from a virtual machine).

Microsoft RDP (until Windows Server 2019) does not support OpenGL 1.4 - you must use a remote desktop client that supports OpenGL 1.4, for example Splashtop or Hamachi Logmein if your Microsoft RDP version does not support OpenGL 1.4.

Please also note that even virtual machines must have their correct drivers installed. Make sure that you have your graphics drivers up to date. In some rare cases - i.e. when a video card has just arrived on the market - you may need to install the developers NVIDIA driver available at the URL <https://developer.nvidia.com/cuda-downloads> until the newer version of Zephyr takes care of that.